

KSZ8863MLL/FLL/RLL

Integrated 3-Port 10/100 Managed Switch with PHYs

Revision 1.5

General Description

The KSZ8863MLL/FLL/RLL are highly-integrated 3-port switch on a chip ICs in industry's smallest footprint. They are designed to enable a new generation of low port count, cost-sensitive and power efficient 10/100Mbps switch systems. Low power consumption, advanced power management, and sophisticated QoS features (e.g., IPv6 priority classification support) make these devices ideal for IPTV, IP-STB, VoIP, automotive and industrial applications.

The KSZ8863 family is designed to support the GREEN requirement in today's switch systems. Advanced power management schemes include software power down, per port power down and the energy detect mode that shuts downs the transceiver when a port is idle.

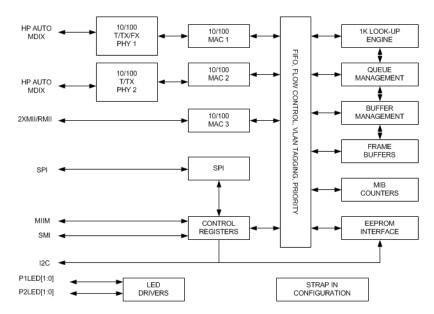
KSZ8863MLL/FLL/RLL also offer a by-pass mode, which enables system-level power saving. In this mode, the processor connected to the switch through the MII interface can be shut down without impacting the normal switch operation. The configurations provided by the KSZ8863 family enables the flexibility to meet requirements of different applications:

- KSZ8863MLL: Two 10/100BASE-T/TX transceivers and one MII interface.
- KSZ8863RLL: Two 10/100BASE-T/TX transceivers and one RMII interface.
- KSZ8863FLL: One 100BASE-FX, one 10/100BASE-T/TX transceivers and one MII interface.

The device is available in RoHS-compliant 48-pin LQFP package. Industrial-grade and Automotive-grade are also available.

The datasheets and supporting documents can be found at Micrel's web site at: <u>www.micrel.com</u>.

Functional Diagram



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Features

- Advanced Switch Features
 - IEEE 802.1q VLAN support for up to 16 groups (full-range of VLAN IDs)
 - VLAN ID tag/untag options, per port basis
 - IEEE 802.1p/q tag insertion or removal on a per port basis (egress)
 - Programmable rate limiting at the ingress and egress on a per port basis
 - Broadcast storm protection with % control (global and per port basis)
 - IEEE 802.1d rapid spanning tree protocol support
 - tail tag mode (1 byte added before FCS) support at port3 to inform the processor which ingress port receives the packet and its priority
 - Bypass feature which Automatically sustains the switch function between Port1 and Port2 when CPU (Port 3 interface) goes to the sleep mode
 - Self-address filtering
 - Individual MAC address for port1 and port2
 - Support RMII interface and 50 MHz reference clock output
 - IGMP snooping (Ipv4) support for multicast packet Filtering
 - IPv4/IPv6 QoS support.
 - MAC filtering function to forward unknown unicast packets to specified port
- Comprehensive Configuration Register Access
 - Serial management interface (SMI) to all internal registers
 - MII management (MIIM) interface to PHY registers
 - High speed SPI and I²C Interface to all internal registers
 - I/0 pins strapping and EEPROM to program selective registers in unmanaged switch mode
 - Control registers configurable on the fly (portpriority, 802.1p/d/q, AN...)
- QoS/CoS Packet Prioritization Support
 - Per port, 802.1p and DiffServ-based
 - Re-mapping of 802.1p priority field per port basis Four priority levels
- Proven Integrated 3-Port 10/100 Ethernet Switch
 - 3rd generation switch with three MACs and two PHYs fully compliant with IEEE 802.3u standard
 - Non-blocking switch fabric assures fast packet delivery by utilizing an 1K MAC address lookup table and a store-and-forward architecture

- Full duplex IEEE 802.3x flow control (PAUSE) with force mode option
- Half-duplex back pressure flow control
- HP Auto MDI-X for reliable detection of and correction for straight-through and crossover cables with disable and enable option
- Micre LinkMD[®] TDR-based cable diagnostics permit identification of faulty copper cabling
- MII interface supports both MAC mode and PHY mode
- Comprehensive LED Indicator support for link, activity, full/half duplex and 10/100 speed
- HBM ESD Rating 4kV

Switch Monitoring Features

- Port mirroring/monitoring/sniffing: ingress and/or egress traffic to any port or MII
- MIB counters for fully compliant statistics gathering 34 MIB counters per port
- Loopback modes for remote diagnostic of failure
- Low Power Dissipation
 - Full-chip software power-down (register configuration not saved)
 - Energy-detect mode support
 - Dynamic clock tree shutdown feature
 - Per port based software power-save on PHY (idle link detection, register configuration preserved)
 - Voltages: Single 3.3V supply with internal 1.8V LDO for 3.3V VDDIO
 - Optional 3.3V, 2.5V and 1.8V for VDDIO
 - Transceiver power 3.3V for VDDA_3.3
- Industrial Temperature Range: –40°C to +85°C
- Available in 48-Pin LQFP, Lead-free package

Applications

- Typical
 - VoIP Phone
 - Set-top/Game Box
 - Automotive
 - Industrial Control
 - IPTV POF
 - SOHO Residential Gateway
 - Broadband Gateway / Firewall / VPN
 - Integrated DSL/Cable Modem
 - Wireless LAN access point + gateway
 - Standalone 10/100 switch

Ordering Information

Part Number	Junction Temperature Range	Package	Lead Finish/Grade
KSZ8863MLL	0°C to 70°C	48-Pin LQFP	Pb-Free/Commercial
KSZ8863MLLI	-40°C to +85°C	48-Pin LQFP	Pb-Free/Industrial
KSZ8863FLL	0°C to 70°C	48-Pin LQFP	Pb-Free/Commercial
KSZ8863FLLI	-40°C to +85°C	48-Pin LQFP	Pb-Free/Industrial
KSZ8863RLL	0°C to 70°C	48-Pin LQFP	Pb-Free/Commercial
KSZ8863RLLI	-40°C to +85°C	48-Pin LQFP	Pb-Free/Industrial

Revision History

Date	Summary of Changes		
07/10/08	Initial release	1.0	
00/08/00	Remove LinkMD feature.	1 1	
09/08/09	Update the Electrical Characteristics.	1.1	
09/23/09	Add LinkMD feature on Port 2.		
09/23/09	Fix the typo on register 194		
10/01/09	Modify pin 28(SMRXD31) description		
08/18/10	Remove Turbo MII feature and its timing, add MDC/MDIO timing, update the descriptions of the by- pass mode, tag insertion, power management, pins, registers and so on. Update max rating, RMII timing and electrical characteristics.		
05/25/11	Add the descriptions of the registers from register 175-186. Add a note for port register control 12, update the description for some registers, update reset timing diagram.		
08/5/11	Add the descriptions for MDC/MDIO SMI mode and IGMP mode. updates junction thermal data and lead temperature.		
01/27/14	Update the descriptions for RMII mode. Update the operation Min/Max voltage in different VDDIO, change TTL I/O to CMOS I/O, update the pin 39 SPIS_N description. Update the register 166		

Contents

Functional Diagram	
Applications	2
Pin Description and I/O Assignment	
Pin Configuration	
Functional Description	
Functional Overview: Physical Layer Transceiver	
100BASE-TX Transmit	
100BASE-TX Transmit	
PLL Clock Synthesizer	
Scrambler/De-scrambler (100BASE-TX Only)	
100BASE-FX Operation	
100BASE-FX Signal Detection	
100BASE-FX Far-End Fault	
10BASE-T Transmit	
10BASE-T Receive	
MDI/MDI-X Auto Crossover	
Straight Cable	
Crossover Cable	
Auto-Negotiation	
LinkMD [®] Cable Diagnostics	
Access	
Usage	
Functional Overview: Power Management	
Normal Operation Mode	
Energy Detect Mode	
Soft Power Down Mode	
Power Saving Mode	
Port based Power Down Mode	
Functional Overview: MAC and Switch	
Address Lookup	
Learning	
Migration	
Aging	
Forwarding	
Switching Engine	
MAC Operation	
Inter Packet Gap (IPG)	
Back-Off Algorithm	
Late Collision	
Illegal Frames	
Full Duplex Flow Control	
Half-Duplex Backpressure	
Broadcast Storm Protection	
Port Individual MAC address and Source Port Filtering	
MII Interface Operation	
RMII Interface Operation	
MII Management (MIIM) Interface	
Serial Management Interface (SMI)	

Advanced Switch Functions	
Bypass Mode	
IEEE 802.1Q VLAN Support	
QoS Priority Support	
Port-Based Priority	
802.1p-Based Priority	35
DiffServ-Based Priority	35
Spanning Tree Support.	
Rapid Spanning Tree Support	
Tail Tagging Mode	
IGMP Support	
IGMP Snooping	
IGMP Send Back to the Subscribed Port	
Port Mirroring Support	
Rate Limiting Support	
Unicast MAC Address Filtering	
Configuration Interface	
f ² C Master Serial Bus Configuration	
I2C Slave Serial Bus Configuration	
SPI Slave Serial Bus Configuration	41
Loopback Support	
Far-end Loopback	
Near-end (Remote) Loopback	
MII Management (MIIM) Registers	
PHY1 Register 0 (PHYAD = 0x1, REGAD = 0x0): MII Basic Control	
PHY2 Register 0 (PHYAD = 0x2, REGAD = 0x0): MII Basic Control	
PHY1 Register 1 (PHYAD = 0x1, REGAD = 0x1): MII Basic Status	
PHY2 Register 1 (PHYAD = 0x2, REGAD = 0x1): MII Basic Status	
PHY1 Register 2 (PHYAD = 0x1, REGAD = 0x2): PHYID High	
PHY2 Register 2 (PHYAD = 0x2, REGAD = 0x2): PHYID High	
PHY1 Register 3 (PHYAD = 0x1, REGAD = 0x3): PHYID Low	
PHY2 Register 3 (PHYAD = $0x2$, REGAD = $0x3$): PHYID Low	
PHY1 Register 4 (PHYAD = $0x1$, REGAD = $0x4$): Auto-Negotiation Advertisement Ability	
PHY2 Register 4 (PHYAD = 0x2, REGAD = 0x4): Auto-Negotiation Advertisement Ability	
PHY1 Register 5 (PHYAD = 0x1, REGAD = 0x5): Auto-Negotiation Link Partner Ability PHY2 Register 5 (PHYAD = 0x2, REGAD = 0x5): Auto-Negotiation Link Partner Ability	
PHY2 Register 5 (PHYAD = 0x2, REGAD = 0x5). Auto-negotiation Link Partner Ability PHY1 Register 29 (PHYAD = 0x1, REGAD = 0x1D): Not support	
PHY1 Register 29 (PHYAD = 0x1, REGAD = 0x1D). Not support PHY2 Register 29 (PHYAD = 0x2, REGAD = 0x1D): LinkMD Control/Status	
PHY2 Register 29 (PHYAD = 0x2, REGAD = 0x1D). LINKVID CONTONStatus PHY1 Register 31 (PHYAD = 0x1, REGAD = 0x1F): PHY Special Control/Status	
PHY2 Register 31 (PHYAD = 0x1, REGAD = 0x1F): PHY Special Control/StatusPHY2 Register 31 (PHYAD = 0x2, REGAD = 0x1F): PHY Special Control/Status	
Memory Map (8-bit Registers)	
Global Registers	
Port Registers	
Advanced Control Registers	
Auvanced Control Registers	

Register Description	51
Global Registers (Registers 0 – 15)	51
Register 0 (0x00): Chip ID0	
Register 1 (0x01): Chip ID1 / Start Switch	51
Register 2 (0x02): Global Control 0	51
Register 3 (0x03): Global Control 1	52
Register 4 (0x04): Global Control 2	52
Register 5 (0x05): Global Control 3	53
Register 6 (0x06): Global Control 4	54
Register 7 (0x07): Global Control 5	54
Register 8 (0x08): Global Control 6	55
Register 9 (0x09): Global Control 7	
Register 10 (0x0A): Global Control 8	
Register 11 (0x0B): Global Control 9	
Register 12 (0x0C): Global Control 10	
Register 13 (0x0D): Global Control 11	
Register 14 (0x0E): Global Control 12	
Register 15 (0x0F): Global Control 13	
Port Registers (Registers 16 – 95)	
Register 16 (0x10): Port 1 Control 0	
Register 32 (0x20): Port 2 Control 0	
Register 48 (0x30): Port 3 Control 0	
Register 17 (0x11): Port 1 Control 1	
Register 33 (0x21): Port 2 Control 1	
Register 49 (0x31): Port 3 Control 1	
Register 18 (0x12): Port 1 Control 2	
Register 34 (0x22): Port 2 Control 2	
Register 50 (0x32): Port 3 Control 2	
Register 19 (0x13): Port 1 Control 3	
Register 35 (0x23): Port 2 Control 3	
Register 51 (0x33): Port 3 Control 3	
Register 20 (0x14): Port 1 Control 4	
Register 36 (0x24): Port 2 Control 4	
Register 52 (0x34): Port 3 Control 4	
Register 21 (0x15): Port 1 Control 5	
Register 37 (0x25): Port 2 Control 5	
Register 53 (0x35): Port 3 Control 5	
Register 22[6:0] (0x16): Port 1 Q0 ingress data rate limit	
Register 38[6:0] (0x26): Port 2 Q0 ingress data rate limit	
Register 54[6:0] (0x36): Port 3 Q0 ingress data rate limit	
Register 23[6:0] (0x17): Port 1 Q1 ingress data rate limit	
Register 39[6:0] (0x27): Port 2 Q1 ingress data rate limit Register 55[6:0] (0x37): Port 3 Q1 ingress data rate limit	
Register 24[6:0] (0x37). Port 3 Q1 ingress data rate limit Register 24[6:0] (0x18): Port 1 Q2 ingress data rate limit	
Register 40[6:0] (0x18): Port 2 Q2 ingress data rate limit Register 40[6:0] (0x28): Port 2 Q2 ingress data rate limit	
Register 56[6:0] (0x28): Port 3 Q2 ingress data rate limit	
Register 25[6:0] (0x30): Port 1 Q3 ingress data rate limit	
Register 41[6:0] (0x19): Port 2 Q3 ingress data rate limit	
Register 57[6:0] (0x29): Port 3 Q3 ingress data rate limit	
Register 26 (0x1A): Port 1 PHY Special Control/Status	
Register 42 (0x1A): Port 2 PHY Special Control/Status	
Register 58 (0x3A): Reserved, not applied to port 3	
Register 27 (0x1B): Port 1 Not support	
Register 43 (0x2B): Port 2 LinkMD Result	
Register 59 (0x3B): Reserved, not applied to port 3	
Register 28 (0x1C): Port 1 Control 12	
Register 44 (0x2C): Port 2 Control 12	64

	Register 60 (0x3C): Reserved, not applied to port 3	64
	Register 29 (0x1D): Port 1 Control 13	
	Register 45 (0x2D): Port 2 Control 13	
	Register 61 (0x3D): Reserved, not applied to port 3	
	Register 30 (0x1E): Port 1 Status 0	
	Register 46 (0x2E): Port 2 Status 0	
	Register 62 (0x3E): Reserved, not applied to port 3	
	Register 31 (0x1F): Port 1 Status 1	
	Register 47 (0x2F): Port 2 Status 1	
	Register 63 (0x3F): Port 3 Status 1	
	Register 67 (0x43): Reset	
	nced Control Registers (Registers 96-198)	
	Register 96 (0x60): TOS Priority Control Register 0	
I	Register 97 (0x61): TOS Priority Control Register 1	68
I	Register 98 (0x62): TOS Priority Control Register 2	68
	Register 99 (0x63): TOS Priority Control Register 3	
	Register 100 (0x64): TOS Priority Control Register 4	
	Register 101 (0x65): TOS Priority Control Register 5	
	Register 102 (0x66): TOS Priority Control Register 6	
	Register 103 (0x67): TOS Priority Control Register 7	
	Register 104 (0x68): TOS Priority Control Register 8	
	Register 105 (0x69): TOS Priority Control Register 9	
	Register 106 (0x6A): TOS Priority Control Register 10	
	Register 100 (000A): TOS Priority Control Register 11	
	Register 107 (0x0B). TOS Priority Control Register 12	
	Register 108 (0x6C): TOS Priority Control Register 12 Register 109 (0x6D): TOS Priority Control Register 13	
	Register 110 (0x6E): TOS Priority Control Register 14	
	Register 111 (0x6F): TOS Priority Control Register 15	
	Registers 112 to 117	
I	Register 112 (0x70): MAC Address Register 0	73
I	Register 113 (0x71): MAC Address Register 1	73
	Register 114 (0x72): MAC Address Register 2	
	Register 115 (0x73): MAC Address Register 3	
I	Register 116 (0x74): MAC Address Register 4	73
	Register 117 (0x75): MAC Address Register 5	
	Registers 118 to 120	
	Register 118 (0x76): User Defined Register 1	
	Register 119 (0x77): User Defined Register 2	
I	Register 120 (0x78): User Defined Register 3	74
I	Registers 121 to 131	74
I	Register 121 (0x79): Indirect Access Control 0	74
I	Register 122 (0x7A): Indirect Access Control 1	74
I	Register 123 (0x7B): Indirect Data Register 8	74
I	Register 124 (0x7C): Indirect Data Register 7	75
	Register 125 (0x7D): Indirect Data Register 6	
l	Register 126 (0x7É): Indirect Data Register 5	75
	Register 127 (0x7F): Indirect Data Register 4	
	Register 128 (0x80): Indirect Data Register 3	
	Register 129 (0x81): Indirect Data Register 2	
	Register 130 (0x82): Indirect Data Register 1	
	Register 131 (0x83): Indirect Data Register 0	
	Register 147~142(0x93~0x8E): Station Address 1 MACA1	
	Register 153~148 (0x99~0x94): Station Address 2 MACA2	
	Register 154[6:0] (0x9A): Port 1 Q0 Egress data rate limit	76
	Register 154[0:0] (0x9A): Fort 2 Q0 Egress data rate limit	
	Register 162[6:0] (0x92): Port 3 Q0 Egress data rate limit	
	Register 155[6:0] (0xA2): Port 1 Q1 Egress data rate limit	
		10

Register 159[6:0] (0x9F): Port 2 Q1 Egress data rate limit	76
Register 163[6:0] (0xA3): Port 3 Q1 Egress data rate limit	
Register 156[6:0] (0x9C): Port 1 Q2 Egress data rate limit	
Register 160[6:0] (0x60): Port 2 Q2 Egress data rate limit	
Register 164[6:0] (0xA4): Port 3 Q2 Egress data rate limit	
Register 157[6:0] (0x9D): Port 1 Q3 Egress data rate limit	
Register 161[6:0] (0x61): Port 2 Q3 Egress data rate limit	
Register 165[6:0] (0x45): Port 3 Q3 Egress data rate limit	
Register 166 (0xA6): KSZ8863 mode indicator	
Register 167 (0xA7): High Priority Packet Buffer Reserved for Q3	
Register 168 (0xA8): High Priority Packet Buffer Reserved for Q2	
Register 169 (0xA9): High Priority Packet Buffer Reserved for Q1	
Register 170 (0xAA): High Priority Packet Buffer Reserved for Q0	
Register 171 (0xAB): PM Usage Flow Control Select Mode 1	
Register 172 (0xAC): PM Usage Flow Control Select Mode 2	
Register 173 (0xAD): PM Usage Flow Control Select Mode 3	
Register 174 (0xAE): PM Usage Flow Control Select Mode 4	
Register 175 (0xAF): TXQ Split for Q3 in Port 1	
Register 176 (0xB0): TXQ Split for Q2 in Port 1	
Register 177 (0xB1): TXQ Split for Q1 in Port 1	
Register 178 (0xB2): TXQ Split for Q0 in Port 1	
Register 179 (0xB2): TXQ Split for Q3 in Port 2	
Register 180 (0xB4): TXQ Split for Q2 in Port 2	
Register 181 (0xB5): TXQ Split for Q1 in Port 2	
Register 182 (0xB6): TXQ Split for Q0 in Port 2	
Register 183 (0xB7): TXQ Split for Q3 Port 3	
Register 184 (0xB8): TXQ Split for Q2 Port 3	
Register 185 (0xB9): TXQ Split for Q1 in Port 3	
Register 186 (0xBA): TXQ Split for Q0 in Port 3	
Register 187 (0xBB): Interrupt enable register	
Register 188 (0xBC): Link Change Interrupt	
Register 189 (0xBD): Force Pause Off Iteration Limit Enable	
Register 192 (0xC0): Fiber Signal Threshold	
Register 193 (0xC1): Internal 1.8V LDO Control	81
Register 194 (0xC2): Insert SRC PVID	
Register 195 (0xC3): Power Management and LED Mode	
Register 196(0xC4): Sleep Mode	
Register 198 (0xC6): Forward Invalid VID Frame and Host Mode	
Static MAC Address Table	
Examples:	
VLAN Table	
Dynamic MAC Address Table	
MIB (Management Information Base) Counters	
Additional MIB Counter Information	
Absolute Maximum Ratings	
Operating Ratings	

Electrical Characteristics	
EEPROM Timing	
MII Timing	
RMII Timing	
RMII Timing I ² C Slave Mode Timing	
SPI Timing	100
Auto-Negotiation Timing	
	103
Reset Timing	104
Reset Circuit	
Selection of Isolation Transformers	106
Selection of Reference Crystal	106
Package Information	107

List of Figures

Figure 1.	Typical Straight Cable Connection	. 19
Figure 2.	Typical Crossover Cable Connection	. 20
Figure 3.	Auto-Negotiation and Parallel Operation	. 21
Figure 4.	Destination Address Lookup Flow Chart, Stage 1	. 25
Figure 5.	Destination Address Resolution Flow Chart, Stage 2	. 26
Figure 6.	802.1p Priority Field Format	. 35
Figure 7.	Tail Tag Frame Format	. 37
	Tail Tag Rules	
Figure 9.	EEPROM Configuration Timing Diagram	. 40
Figure 10.	SPI Write Data Cycle	. 42
Figure 11.	SPI Read Data Cycle	. 42
	SPI Multiple Write	
Figure 13.	SPI Multiple Read	. 43
Figure 14.	Far-End Loopback Path	. 43
Figure 15.	Near-End (Remote) Loopback Path	. 44
Figure 16.	EEPROM Interface Input Timing Diagram	. 94
	EEPROM Interface Output Timing Diagram	
	MAC Mode MII Timing – Data Received from MII	
	MAC Mode MII Timing – Data Transmitted to MII	
	PHY Mode MII Timing – Data Received from MII	
Figure 21.	PHY Mode MII Timing – Data Transmitted to MII	. 96
	RMII Timing – Data Received from RMII	
	RMII Timing – Data Transmitted to RMII	
	I ² C Input Timing	
	I ² C Start Bit Timing	
	SPI Input Timing	
	SPI Output Timing	
	Auto-Negotiation Timing	
	MDC/MDIO Timing	
•	Reset Timing	
	Recommended Reset Circuit	
Figure 34.	Recommended Reset Circuit for interfacing with CPU/FPGA Reset Output	105

List of Tables

Table 1. FX Signal Threshold	
Table 2. MDI/MDI-X Pin Definitions	19
Table 3. Internal Function Block Status	23
Table 4. MII Signals	29
Table 5. RMII Clock Setting	
Table 6. RMII Signal Description	
Table 7. RMII Signal Connections	
Table 8. MII Management Interface Frame Format	
Table 9. Serial Management Interface (SMI) Frame Format	
Table 10. FID+DA Lookup in VLAN Mode	
Table 11. FID+SA Lookup in VLAN Mode	
Table 12. Spanning Tree States	
Table 13. SPI Connections	
Table 14. Data Rate Limit Table	
Table 16. Format of Static VLAN Table (16 Entries)	
Table 17. Format of Dynamic MAC Address Table (1K Entries)	
Table 18. Format of "Per Port" MIB Counters	
Table 19. Port 1's "Per Port" MIB Counters Indirect Memory Offsets	
Table 20. Format of "All Port Dropped Packet" MIB Counters	
Table 21. "All Port Dropped Packet" MIB Counters Indirect Memory Offsets	
Table 22. EEPROM Timing Parameters	94
Table 23. MAC Mode MII Timing Parameters	
Table 24. PHY Mode MII Timing Parameters	
Table 25. RMII Timing Parameters	
Table 26. I ² C Timing Parameters	
Table 27. SPI Input Timing Parameters	
Table 28. SPI Output Timing Parameters	
Table 29. Auto-Negotiation Timing Parameters	
Table 30. MDC/MDIO Timing Parameters	
Table 32. Transformer Selection Criteria	
Table 33. Qualified Single Port Magnetics	
Table 34. Typical Reference Crystal Characteristics	106

Pin Description and I/O Assignment

Pin Number	Pin Name	Type ⁽¹⁾	Description
1	RXM1	I/O	Physical receive or transmit signal (- differential)
2	RXP1	I/O	Physical receive or transmit signal (+ differential)
3	TXM1	I/O	Physical transmit or receive signal (- differential)
4	TXP1	I/O	Physical transmit or receive signal (+ differential)
5	VDDA_3.3	Р	3.3V analog V _{DD}
6		0	Set physical transmit output current.
0	ISET	0	Pull-down this pin with a 11.8K 1% resistor to ground.
7	VDDA_1.8	Р	1.8V analog core power input from VDDCO (pin 42).
8	RXM2	I/O	Physical receive or transmit signal (- differential)
9	RXP2	I/O	Physical receive or transmit signal (+ differential)
10	AGND	Gnd	Analog ground.
11	TXM2	I/O	Physical transmit or receive signal (- differential)
12	TXP2	I/O	Physical transmit or receive signal (+ differential)
13	NC	NC	No Connection.
	X1	I	25 or 50MHz crystal/oscillator clock connections.
14			Pins (X1, X2) connect to a crystal. If an oscillator is used, X1 connects to a 3.3V tolerant oscillator and X2 is a NC.
15	X2	0	Note: Clock is ±50ppm for both crystal and oscillator, the clock should be applied to X1 pin before reset voltage goes high.
16	SMTXEN3	lpu	Switch MII transmit enable
			MLL/FLL: Switch MII transmit data bit 3
17	SMTXD33/	lou	RLL: Strap option: RMII mode Clock selection
17	EN_REFCLKO_3	lpu	PU = Enable REFCLKO_3 output
			PD = Disable REFCLKO_3 output
			Switch MII transmit data bit 2
			RLL: Strap option: X1 pin Clock selection (for Rev A3 and behind A3)
18	SMTXD32	lpu	PU = 25MHz to X1 pin as clock source (default).
			PD = 50MHz to X1 pin as clock source to provide/receive 50MHz RMII reference clock for RLL part.
19	SMTXD31	lpu	Switch MII/RMII transmit data bit 1
20	SMTXD30	lpu	Switch MII/RMII transmit data bit 0
21	GND	Gnd	Digital ground
22	VDDIO	Р	3.3V, 2.5V or 1.8V digital VDD input power supply for IO with well decoupling capacitors.

Notes:

 Speed : Low (100BASE-TX), High (10BASE-T) Full duplex : Low (full duplex), High (half duplex) Act : Toggle (transmit / receive activity) Link : Low (link), High (no link)

P = Power supply. Gnd = Ground.
I = Input.
Ipu/O = Input with internal pull-up during reset, output pin otherwise.
Ipu = Input w/ internal pull-up.
Ipd = Input w/ internal pull-down.
Opu = Output w/ internal pull-up.
Opd = Output w/ internal pull-down.

Pin Description and I/O Assignment (Continued)

Pin Number	Pin Name	Type ⁽¹⁾	Description
			MLL/FLL: Switch MII transmit clock (MII and SNI modes only)
23			Output in PHY MII mode and SNI mode
	SMTXC3/	I/O	Input in MAC MII and RMII mode.
20	REFCLKI_3	1/0	RLL: Reference clock input
			Note: pull-down by resistor is needed if internal reference clock is used in RLL by register 198 bit 3.
	SMTXER3/		Switch port3 MII transmit error in MII mode
24	MII_LINK_3	lpd	0= MII link indicator from host in MII PHY mode.
			1= No link on port 3 MII PHY mode and enable By-pass mode.
			Switch MII/RMII receive data valid
			Strap option: Force duplex mode (P1DPX)
25	SMRXDV3	lpu/O	PU = port 1 default to full duplex mode if P1ANEN = 1 and auto- negotiation fails. Force port 1 in full-duplex mode if P1ANEN = 0.
			PD = port 1 default to half duplex mode if P1ANEN = 1 and auto- negotiation fails. Force port 1 in half duplex mode if P1ANEN = 0.
			MLL/FLL: Switch MII receive data bit 3/
	SMRXD33/		RLL: Output reference clock in RMII mode.
26		lpu/O	Strap option: enable auto-negotiation on port 2 (P2ANEN)
	REFCLKO_3		PU = enable
			PD = disable
			Switch MII receive data bit 2
27	SMRXD32	lpu/O	Strap option: Force the speed on port 2 (P2SPD)
21	SINIRAD32		PU = force port 2 to 100BT if P2ANEN = 0
			PD = force port 2 to 10BT if P2ANEN = 0
			Switch MII/RMII receive data bit 1
			Strap option: Force duplex mode (P2DPX)
28	SMRXD31	lpu/O	PU = port 2 default to full duplex mode if $P2ANEN = 1$ and auto-negotiation fails. Force port 2 in full duplex mode if $P2ANEN = 0$.
			PD = Port 2 set to half duplex mode if $P2ANEN = 1$ and auto-negotiation fails. Force port 2 in half duplex mode if $P2ANEN = 0$.
			Switch MII/RMII receive data bit 0
			Strap option: Force flow control on port 2 (P2FFC)
29	SMRXD30	lpu/O	PU = always enable (force) port 2 flow control feature.
			PD = port 2 flow control feature enable is determined by auto- negotiation result.
			Switch MII receive clock.
30	SMRXC3 I/O	I/O	Output in PHY MII mode
			Input in MAC MII mode
31	GND	Gnd	Digital ground
32	VDDC	Р	1.8V digital core power input from VDDCO (pin 42).
33	SCOL3	lpu/O	Switch MII collision detect
34	SCRS3	lpu/O	Switch MII carrier sense

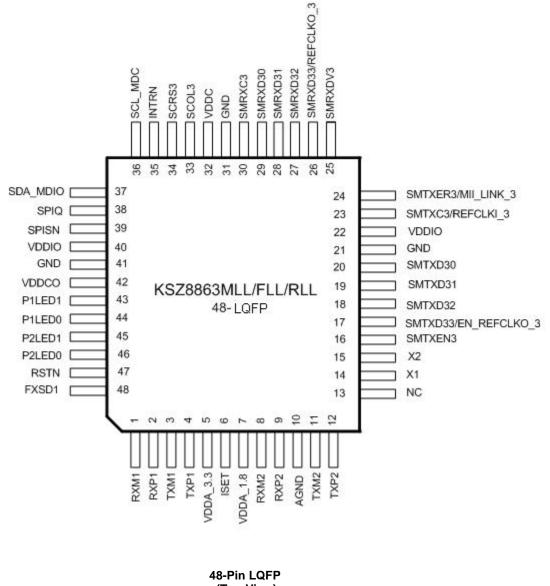
Pin Description and I/O Assignment (Continued)

Pin Number	Pin Name	Type ⁽¹⁾	Description
			Interrupt
35	INTRN	Opu	Active Low signal to host CPU to indicate an interrupt status bit is set when lost link. Refer to register 187 and 188.
			SPI slave mode / I ² C slave mode: clock input
36	SCL_MDC	I/O	I ² C master mode: clock output
			MIIM clock input
			SPI slave mode: serial data input
37	SDA_MDIO	lpu/O	I ² C master/slave mode: serial data input/output
57	SDA_INDIO	ipu/O	MIIM: data input/out
			Note: an external pull-up is needed on this pin when it is in use.
			SPI slave mode: serial data output
			Note: an external pull-up is needed on this pin when it is in use.
38	SPIQ	lpd/O	Strap option: Force flow control on port 1 (P1FFC)
			PU = always enable (force) port 1 flow control feature
			PD = port 1 flow control feature enable is determined by auto negotiation result.
			SPI slave mode: chip select (active low)
39	SPISN	Ind	When SPISN is high, the KSZ8863MLL/FLL/RLLis deselected and SPIQ is held in high impedance state.
39	3P13N	lpd	A high-to-low transition is used to initiate SPI data transfer.
			Note: an external pull-up is needed on this pin when using SPI or MDC/MDIO-MIIM/SMI mode.
40	VDDIO	Р	3.3V, 2.5V or 1.8V digital VDD input power supply for IO with well decoupling capacitors.
41	GND	Gnd	Digital ground
			1.8V core power voltage output (internal 1.8V LDO regulator output), this 1.8V output pin provides power to both VDDA_1.8 and VDDC input pins.
42	VDDCO	Р	Note: Internally 1.8V LDO regulator input comes from VDDIO. Do not connect an external power supply to VDDCO pin. The ferrite bead is requested between analog and digital 1.8V core power.
			Port 1 LED Indicators:
			Default: Speed (refer to register 195 bit[5:4])
43	P1LED1	lpu/O	Strap option: Force the speed on port 1 (P1SPD)
			PU = force port 1 to 100BT if P1ANEN = 0
			PD = force port 1 to 10BT if P1ANEN = 0
			Port 1 LED Indicators:
			Default: Link/Act. (refer to register 195 bit[5:4])
44	P1LED0	lpd/O	Strap option: enable auto-negotiation on port 1 (P1ANEN)
			PU = enable (It is better to pull up in design)
			PD = disable (default)

Pin Description and I/O Assignment (Continued)

Pin Number	Pin Name	Type ⁽¹⁾	Description					
45	P2LED1	lpu/O	Port 2 LED Indicat	ors:				
			Default: Speed (refer to register 195 bit[5:4])					
			Strap option: Seria	al bus c	onfiguration			
			Port 2 LED Indicat	ors:				
			Default: Link/Act. (r	efer to i	register 195 bit[5:4])			
			Strap option: Seria	al bus c	onfiguration			
			Serial bus configura KSZ8863MLL/FLL/		ns to select mode of access to ernal registers.			
			[P2LED1, P2LED0] = [0, 0)] — I ² C master (EEPROM) mode			
					d, the KSZ8863MLL/FLL/RLL will be confi s internal registers and the values of its st			
			Interface Signals	Туре	Description			
			SPIQ	0	Not used (tri-stated)			
			SCL_MDC	0	l ² C clock			
			SDA_MDIO	I/O	I ² C data I/O			
			SPISN	Ι	Not used			
			[P2LED1, P2LED0] = [0, 1] — I ² C slave mode			
			The external I ² C master will drive the SCL_MDC clock.					
46	P2LED0	lpu/O	Ipu/O The KSZ8863MLL/FLL/RLL device addresses are:					
			1011_1111 <read< td=""><td> ></td><td></td><td></td></read<>	>				
			1011_1110 <write< td=""><td>?></td><td></td><td></td></write<>	? >				
			Interface Signals	Туре	Description			
			SPIQ	0	Not used (tri-stated)			
			SCL_MDC	Ι	l ² C clock			
			SDA_MDIO	I/O	I ² C data I/O			
			SPISN	1	Not used			
			[P2LED1, P2LED0] = [1, 0] — SPI slave mode			
			Interface Signals	Туре	Description			
			SPIQ	0	SPI data out			
			SCL_MDC	1	SPI clock			
			SDA_MDIO	Ι	SPI data In			
			SPISN	Ι	SPI chip select			
			- ,	•••] – SMI/MIIM-mode			
					BMLL/FLL/RLL provides access to all its in L_MDC and SDA_MDIO pins.	ternal 8-		
					3MLL/FLL/RLL provides access to its 16- MDC and SDA_MDIO pins.	oit MIIM		
47	RSTN	lpu	Hardware reset pin	(active	low)			
48	FXSD1	I	MLL/RLL: No conneresistor.	ection o	r connect to analog ground by 1Kohm pull	-down		
			FLL: Fiber signal de	etect				

Pin Configuration



(Top View)

Functional Description

The KSZ8863MLL/FLL/RLL contains two 10/100 physical layer transceivers and three MAC units with an integrated Layer 2 managed switch.

The KSZ8863MLL/FLL/RLL has the flexibility to reside in either a managed or unmanaged design. In a managed design, the host processor has complete control of the KSZ8863MLL/FLL/RLL via the SMI interface, MIIM interface, SPI bus, or I²C bus. An unmanaged design is achieved through I/O strapping and/or EEPROM programming at system reset time.

On the media side, the KSZ8863MLL/FLL/RLL supports IEEE 802.3 10BASE-T and 100BASE-TX on both PHY ports. Physical signal transmission and reception are enhanced through the use of patented analog circuitries that make the design more efficient and allow for lower power consumption and smaller chip die size.

Functional Overview: Physical Layer Transceiver

100BASE-TX Transmit

The 100BASE-TX transmit function performs parallel-to-serial conversion, 4B/5B coding, scrambling, NRZ-to-NRZI conversion, and MLT3 encoding and transmission.

The circuitry starts with a parallel-to-serial conversion, which converts the MII data from the MAC into a 125MHz serial bit stream. The data and control stream is then converted into 4B/5B coding, followed by a scrambler. The serialized data is further converted from NRZ-to-NRZI format, and then transmitted in MLT3 current output. The output current is set by an external1% 11.8K Ω resistor for the 1:1 transformer ratio.

The output signal has a typical rise/fall time of 4ns and complies with the ANSI TP-PMD standard regarding amplitude balance, overshoot, and timing jitter. The wave-shaped 10BASE-T output is also incorporated into the 100BASE-TX transmitter.

100BASE-TX Receive

The 100BASE-TX receiver function performs adaptive equalization, DC restoration, MLT3-to-NRZI conversion, data and clock recovery, NRZI-to-NRZ conversion, de-scrambling, 4B/5B decoding, and serial-to-parallel conversion.

The receiving side starts with the equalization filter to compensate for inter-symbol interference (ISI) over the twisted pair cable. Since the amplitude loss and phase distortion is a function of the cable length, the equalizer must adjust its characteristics to optimize performance. In this design, the variable equalizer makes an initial estimation based on comparisons of incoming signal strength against some known cable characteristics, and then tunes itself for optimization. This is an ongoing process and self-adjusts against environmental changes such as temperature variations.

Next, the equalized signal goes through a DC restoration and data conversion block. The DC restoration circuit is used to compensate for the effect of baseline wander and to improve the dynamic range. The differential data conversion circuit converts the MLT3 format back to NRZI. The slicing threshold is also adaptive.

The clock recovery circuit extracts the 125MHz clock from the edges of the NRZI signal. This recovered clock is then used to convert the NRZI signal into the NRZ format. This signal is sent through the de-scrambler followed by the 4B/5B decoder. Finally, the NRZ serial data is converted to the MII format and provided as the input data to the MAC.

PLL Clock Synthesizer

The KSZ8863MLL/FLL/RLL generates 125MHz, 62.5MHz, and 31.25MHz clocks for system timing. Internal clocks are generated from an external 25MHz or 50MHz crystal or oscillator. KSZ8863RLL can generates a 50MHz reference clock for the RMII interface

Scrambler/De-scrambler (100BASE-TX Only)

The purpose of the scrambler is to spread the power spectrum of the signal to reduce electromagnetic interference (EMI) and baseline wander. Transmitted data is scrambled through the use of an 11-bit wide linear feedback shift register (LFSR). The scrambler generates a 2047-bit non-repetitive sequence, and the receiver then de-scrambles the incoming data stream using the same sequence as at the transmitter.

100BASE-FX Operation

100BASE-FX operation is similar to 100BASE-TX operation with the differences being that the scrambler/de-scrambler and MLT3 encoder/decoder are bypassed on transmission and reception. In addition, auto-negotiation is bypassed and auto MDI/MDI-X is disabled.

100BASE-FX Signal Detection

In 100BASE-FX operation, FXSD (fiber signal detect), input pin 48, is usually connected to the fiber transceiver SD (signal detect) output pin. The fiber signal threshold can be selected by register 192 bit 6 for port 1, When FXSD is less than the threshold, no fiber signal is detected and a far-end fault (FEF) is generated. When FXSD is over the threshold, the fiber signal is detected.

Alternatively, the designer may choose not to implement the FEF feature. In this case, the FXSD input pin is tied high to force 100BASE-FX mode.

100BASE-FX signal detection is summarized in Table 1:

Register 192 bit 7 bit 6 (port 1)	Fiber Signal Threshold at FXSD
1	2.0V
0	1.2V

Table 1. FX Signal Threshold

To ensure proper operation, a resistive voltage divider is recommended to adjust the fiber transceiver SD output voltage swing to match the FXSD pin's input voltage threshold.

100BASE-FX Far-End Fault

A far-end fault (FEF) occurs when the signal detection is logically false on the receive side of the fiber transceiver. The KSZ8863FLL detects a FEF when its FXSD input is below the Fiber Signal Threshold. When a FEF is detected, the KSZ8863FLL signals its fiber link partner that a FEF has occurred by sending 84 1's followed by a zero in the idle period between frames. By default, FEF is enabled.

10BASE-T Transmit

The 10BASE-T driver is incorporated with the 100BASE-TX driver to allow for transmission using the same magnetics. They are internally wave-shaped and pre-emphasized into outputs with a typical 2.3V amplitude. The harmonic contents are at least 27dB below the fundamental frequency when driven by an all-ones Manchester-encoded signal.

10BASE-T Receive

On the receive side, input buffers and level detecting squelch circuits are employed. A differential input receiver circuit and a phase-locked loop (PLL) perform the decoding function. The Manchester-encoded data stream is separated into clock signal and NRZ data. A squelch circuit rejects signals with levels less than 400mV or with short pulse widths to prevent noise at the RXP-or-RXM input from falsely triggering the decoder. When the input exceeds the squelch limit, the PLL locks onto the incoming signal and the KSZ8863MLL/FLL/RLL decodes a data frame. The receiver clock is maintained active during idle periods in between data reception.

MDI/MDI-X Auto Crossover

To eliminate the need for crossover cables between similar devices, the KSZ8863MLL/FLL/RLL supports HP Auto MDI/MDI-X and IEEE 802.3u standard MDI/MDI-X auto crossover. HP Auto MDI/MDI-X is the default.

The auto-sense function detects remote transmit and receive pairs and correctly assigns transmit and receive pairs for the KSZ8863MLL/FLL/RLL device. This feature is extremely useful when end users are unaware of cable types, and also, saves on an additional uplink configuration connection. The auto-crossover feature can be disabled through the port control registers, or MIIM PHY registers.

The IEEE 802.3u standard MDI and MDI-X definitions are illustrated in Table 2.

MDI	MC	MDI-X		
RJ-45 Pins	Signals	RJ-45 Pins	Signals	
1	TD+	1	RD+	
2	TD-	2	RD-	
3	RD+	3	TD+	
6	RD-	6	TD-	

Table 2. N	/IDI/MDI-X Pin	Definitions
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Straight Cable

A straight cable connects an MDI device to an MDI-X device, or an MDI-X device to an MDI device. Figure 1 depicts a typical straight cable connection between a NIC card (MDI) and a switch, or hub (MDI-X).

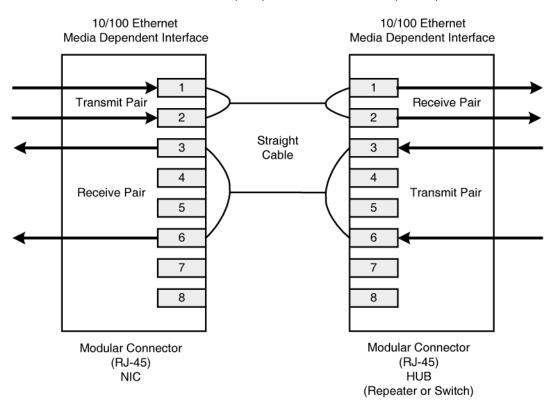


Figure 1. Typical Straight Cable Connection

Crossover Cable

A crossover cable connects an MDI device to another MDI device, or an MDI-X device to another MDI-X device. Figure 2 shows a typical crossover cable connection between two switches or hubs (two MDI-X devices).

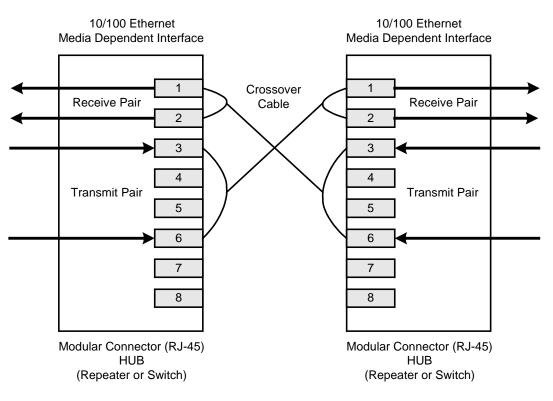


Figure 2. Typical Crossover Cable Connection

Auto-Negotiation

The KSZ8863MLL/FLL/RLL conforms to the auto-negotiation protocol, defined in Clause 28 of the IEEE 802.3u specification.

Auto-negotiation allows unshielded twisted pair (UTP) link partners to select the best common mode of operation. In autonegotiation, link partners advertise their capabilities across the link to each other. If auto-negotiation is not supported or the KSZ8863MLL/FLL/RLL link partner is forced to bypass auto-negotiation, the KSZ8863MLL/FLL/RLL sets its operating mode by observing the signal at its receiver. This is known as parallel detection, and allows the KSZ8863MLL/FLL/RLL to establish link by listening for a fixed signal protocol in the absence of auto-negotiation advertisement protocol.

The link up process is shown in Figure 3.

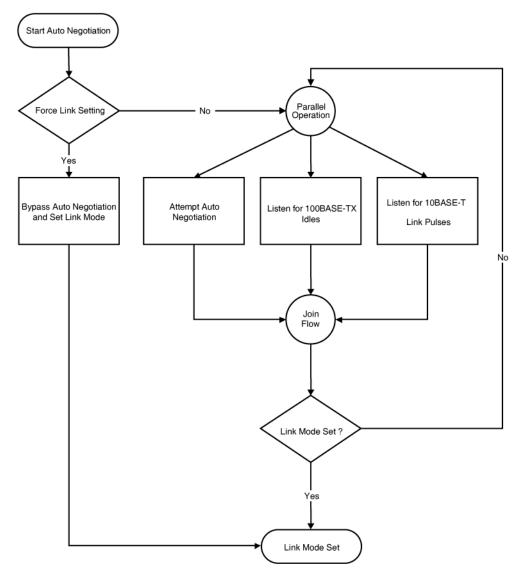


Figure 3. Auto-Negotiation and Parallel Operation

LinkMD[®] Cable Diagnostics

KSZ8863MLL/FLL/RLL supports the LinkMD[®]. The LinkMD[®] feature utilizes time domain reflectometry (TDR) to analyze the cabling plant for common cabling problems such as open circuits, short circuits and impedance mismatches.

LinkMD[®] works by sending a pulse of known amplitude and duration down the MDI and MDI-X pairs and then analyzes the shape of the reflected signal. Timing the pulse duration gives an indication of the distance to the cabling fault. Internal circuitry displays the TDR information in a user-readable digital format.

Note: Cable diagnostics are only valid for copper connections and do not support fiber optic operation.

Access

LinkMD[®] is initiated by accessing the PHY special control/status registers {26, 42} and the LinkMD result registers {27, 43} for ports 1 and 2 respectively; and in conjunction with the port registers control 13 for ports 1 and 2 respectively to disable Auto MDI/MDIX.

Alternatively, the MIIM PHY registers 0 and 29 can be used for LinkMD[®] access.

Usage

The following is a sample procedure for using LinkMD[®] with registers {42,43,45} on port 2.

- 1. Disable auto MDI/MDI-X by writing a '1' to register 45, bit [2] to enable manual control over the differential pair used to transmit the LinkMD[®] pulse.
- 2. Start cable diagnostic test by writing a '1' to register 42, bit [4]. This enable bit is self-clearing.
- 3. Wait (poll) for register 42, bit [4] to return a '0', indicating cable diagnostic test is completed.
- 4. Read cable diagnostic test results in register 42, bits [6:5]. The results are as follows:
 - 00 = normal condition (valid test)
 - 01 = open condition detected in cable (valid test)
 - 10 = short condition detected in cable (valid test)
 - 11 = cable diagnostic test failed (invalid test)

The '11' case, invalid test, occurs when the KSZ8863MLL/FLL/RLL is unable to shut down the link partner. In this instance, the test is not run, since it would be impossible for the KSZ8863MLL/FLL/RLL to determine if the detected signal is a reflection of the signal generated or a signal from another source.

5. Get distance to fault by concatenating register 42, bit [0] and register 43, bits [7:0]; and multiplying the result by a constant of 0.4. The distance to the cable fault can be determined by the following formula:

D (distance to cable fault) = 0.4 x {(register 26, bit [0]),(register 27, bits [7:0])}

D (distance to cable fault) is expressed in meters.

Concatenated value of registers 42 and 43 is converted to decimal before multiplying by 0.4.

The constant (0.4) may be calibrated for different cabling conditions, including cables with a velocity of propagation that varies significantly from the norm.

Functional Overview: Power Management

The KSZ8863MLL/FLL/RLL supports enhanced power management feature in low power state with energy detection to ensure low-power dissipation during device idle periods. There are five operation modes under the power management function which is controlled by two bits in Register 195 (0xC3) and one bit in Register 29 (0x1D),45(0x2D) as shown below:

Register 195 bit[1:0] = 00 Normal Operation Mode

Register 195 bit[1:0] = 01 Energy Detect Mode

Register 195 bit[1:0] = 10 Soft Power Down Mode

Register 195 bit[1:0] = 11 Power Saving Mode

Register 29,45 bit 3 =1 Port Based Power Down Mode

Table 3 indicates all internal function blocks status under four different power management operation modes.

KSZ8863MLL/FLL/RLL Function Blocks		Power Management Operation Modes							
	Normal Mode	ormal Mode Power Saving Mode Energy Detect Mode Soft Power Down Mode							
Internal PLL Clock	Enabled	Enabled	Disabled	Disabled					
Tx/Rx PHY	Enabled	Rx unused block disabled	Energy detect at Rx	Disabled					
MAC	Enabled	Enabled	Disabled	Disabled					
Host Interface	Enabled	Enabled	Disabled	Disabled					

Table 3. Internal Function Block Status

Normal Operation Mode

This is the default setting bit[1:0]=00 in register 195 after the chip power-up or hardware reset . When KSZ8863MLL/FLL/RLL is in this normal operation mode, all PLL clocks are running, PHY and MAC are on and the host interface is ready for CPU read or write.

During the normal operation mode, the host CPU can set the bit[1:0] in register 195 to transit the current normal operation mode to any one of the other three power management operation modes.

Energy Detect Mode

The energy detect mode provides a mechanism to save more power than in the normal operation mode when the KSZ8863MLL/FLL/RLL is not connected to an active link partner. In this mode, the device will save up to 87% of the power. If the cable is not plugged, the KSZ8863MLL/FLL/RLL can automatically enter to a low power state, a.k.a., the energy detect mode. In this mode, KSZ8863MLL/FLL/RLL will keep transmitting 120ns width pulses at 1 pulse/s rate. Once activity resumes due to plugging a cable or attempting by the far end to establish link, the KSZ8863MLL/FLL/RLL can automatically power up to normal power state in energy detect mode.

Energy detect mode consists of two states, normal power state and low power state. While in low power state, the KSZ8863MLL/FLL/RLL reduces power consumption by disabling all circuitry except the energy detect circuitry of the receiver. The energy detect mode is entered by setting bit[1:0]=01 in register 195. When the KSZ8863MLL/FLL/RLL is in this mode, it will monitor the cable energy. If there is no energy on the cable for a time longer than pre-configured value at bit[7:0] Go-Sleep time in register 196, KSZ8863MLL/FLL/RLL will go into a low power state. When KSZ8863MLL/FLL/RLL is in low power state, it will keep monitoring the cable energy. Once the energy is detected from the cable, KSZ8863MLL/FLL/RLL will enter normal power state. When KSZ8863MLL/FLL/RLL is at normal power state, it is able to transmit or receive packet from the cable.

It will save about 87% of the power when MII interface is in PHY mode (Register 53 bit 7 =0), pin SMTXER3/MII_LINK_3 is connected to High, register 195 bit [1:0] =01, bit 2 =1(Disable PLL), not cables are connected.

Soft Power Down Mode

The soft power down mode is entered by setting bit[1:0]=10 in register 195. When KSZ8863MLL/FLL/RLL is in this mode, all PLL clocks are disabled, the PHY and the MAC are off, all internal registers value will not change. When the host set bit[1:0]=00 in register 195, this device will be back from current soft power down mode to normal operation mode.

Power Saving Mode

The power saving mode is entered when auto-negotiation mode is enabled, cable is disconnected, and by setting bit[1:0]=11 in register 195. When KSZ8863MLL/FLL/RLL is in this mode, all PLL clocks are enabled, MAC is on, all internal registers value will not change, and host interface is ready for CPU read or write. In this mode, it mainly controls the PHY transceiver on or off based on line status to achieve power saving. The PHY remains transmitting and only turns off the unused receiver block. Once activity resumes due to plugging a cable or attempting by the far end to establish link, the KSZ8863MLL/FLL/RLL can automatically enabled the PHY power up to normal power state from power saving mode.

During this power saving mode, the host CPU can set bit[1:0] =0 in register 195 to transit the current power saving mode to any one of the other three power management operation modes.

Port-Based Power-Down Mode

In addition, the KSZ8863MLL/FLL/RLL features a per-port power down mode. To save power, a PHY port that is not in use can be powered down via port control register 29 or 45 bit 3, or MIIM PHY register. It will saves about 15mA per port.

Functional Overview: MAC and Switch

Address Lookup

The internal lookup table stores MAC addresses and their associated information. It contains a 1K unicast address table plus switching information.

The KSZ8863MLL/FLL/RLL is guaranteed to learn 1K addresses and distinguishes itself from hash-based lookup tables, which depending on the operating environment and probabilities, may not guarantee the absolute number of addresses it can learn.

Learning

The internal lookup engine updates its table with a new entry if the following conditions are met:

- 1. The received packet's Source Address (SA) does not exist in the lookup table.
- 2. The received packet is good; the packet has no receiving errors, and is of legal length.

The lookup engine inserts the qualified SA into the table, along with the port number and time stamp. If the table is full, the last entry of the table is deleted to make room for the new entry.

Migration

The internal lookup engine also monitors whether a station has moved. If a station has moved, it will update the table accordingly. Migration happens when the following conditions are met:

- 1. The received packet's SA is in the table but the associated source port information is different.
- 2. The received packet is good; the packet has no receiving errors, and is of legal length.

The lookup engine will update the existing record in the table with the new source port information.

Aging

The lookup engine updates the time stamp information of a record whenever the corresponding SA appears. The time stamp is used in the aging process. If a record is not updated for a period of time, the lookup engine removes the record from the table. The lookup engine constantly performs the aging process and will continuously remove aging records. The aging period is about 200 seconds. This feature can be enabled or disabled through register 3 (0x03) bit [2].

Forwarding

The KSZ8863MLL/FLL/RLL forwards packets using the algorithm that is depicted in the following flowcharts. Figure 4 shows stage one of the forwarding algorithm where the search engine looks up the VLAN ID, static table, and dynamic table for the destination address, and comes up with "port to forward 1" (PTF1). PTF1 is then further modified by spanning tree, IGMP snooping, port mirroring, and port VLAN processes to come up with "port to forward 2" (PTF2), as shown in Figure 5. The packet is sent to PTF2.

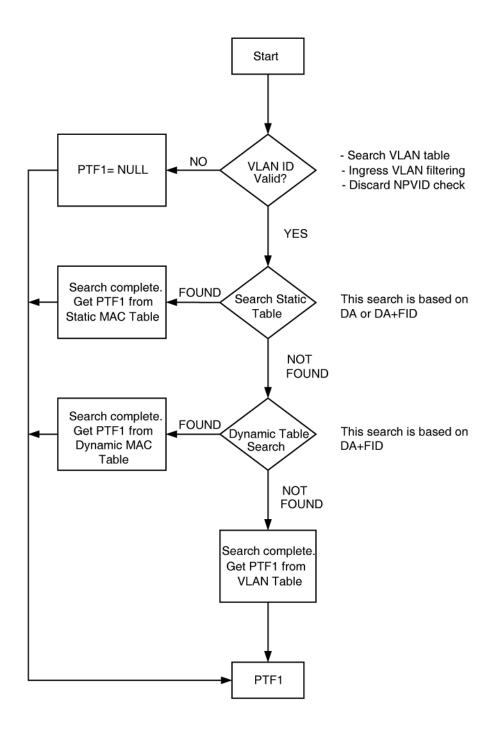
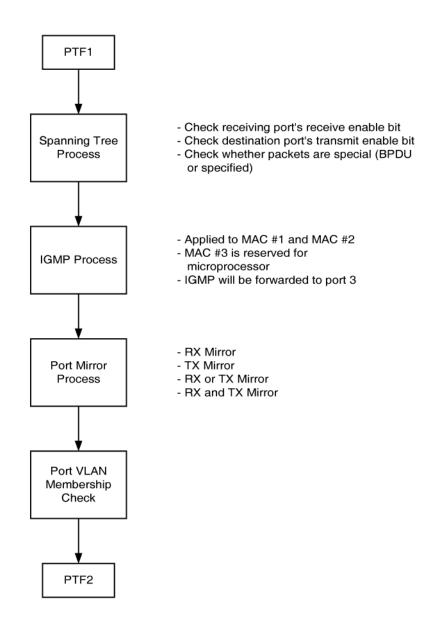


Figure 4. Destination Address Lookup Flow Chart, Stage 1





The KSZ8863MLL/FLL/RLL will not forward the following packets:

1. Error packets

These include framing errors, Frame Check Sequence (FCS) errors, alignment errors, and illegal size packet errors.

2. IEEE802.3x PAUSE frames

KSZ8863MLL/FLL/RLL intercepts these packets and performs full duplex flow control accordingly.

3. "Local" packets

Based on destination address (DA) lookup. If the destination port from the lookup table matches the port from which the packet originated, the packet is defined as "local."

Switching Engine

The KSZ8863MLL/FLL/RLL features a high-performance switching engine to move data to and from the MACs' packet buffers. It operates in store and forward mode, while the efficient switching mechanism reduces overall latency.

The switching engine has a 32kB internal frame buffer. This buffer pool is shared between all three ports. There are a total of 256 buffers available. Each buffer is sized at 128 bytes.

MAC Operation

The KSZ8863MLL/FLL/RLL strictly abides by IEEE 802.3 standards to maximize compatibility.

Inter Packet Gap (IPG)

If a frame is successfully transmitted, the 96 bits time IPG is measured between the two consecutive MTXEN. If the current packet is experiencing collision, the 96 bits time IPG is measured from MCRS and the next MTXEN.

Back-Off Algorithm

The KSZ8863MLL/FLL/RLL implements the IEEE 802.3 standard for the binary exponential back-off algorithm, and optional "aggressive mode" back-off. After 16 collisions, the packet is optionally dropped depending on the switch configuration for register 4 (0x04) bit [3].

Late Collision

If a transmit packet experiences collisions after 512 bit times of the transmission, the packet is dropped.

Illegal Frames

The KSZ8863MLL/FLL/RLL discards frames less than 64 bytes, and can be programmed to accept frames up to1518 bytes, 1536 bytes or 1916 bytes. These maximum frame size settings are programmed in register 4 (0x04). Since the KSZ8863MLL/FLL/RLL supports VLAN tags, the maximum sizing is adjusted when these tags are present.

Full Duplex Flow Control

The KSZ8863MLL/FLL/RLL supports standard IEEE 802.3x flow control frames on both transmit and receive sides.

On the receive side, if the KSZ8863MLL/FLL/RLL receives a pause control frame, the KSZ8863MLL/FLL/RLL will not transmit the next normal frame until the timer, specified in the pause control frame, expires. If another pause frame is received before the current timer expires, the timer will be updated with the new value in the second pause frame. During this period (while it is flow controlled), only flow control packets from the KSZ8863MLL/FLL/RLL are transmitted.

On the transmit side, the KSZ8863MLL/FLL/RLL has intelligent and efficient ways to determine when to invoke flow control. The flow control is based on availability of the system resources, including available buffers, available transmit queues and available receive queues.

The KSZ8863MLL/FLL/RLL will flow control a port that has just received a packet if the destination port resource is busy. The KSZ8863MLL/FLL/RLL issues a flow control frame (XOFF), containing the maximum pause time defined by the IEEE 802.3x standard. Once the resource is freed up, the KSZ8863MLL/FLL/RLL sends out the other flow control frame (XON) with zero pause time to turn off the flow control (turn on transmission to the port). A hysteresis feature is provided to prevent the flow control mechanism from being constantly activated and deactivated.

The KSZ8863MLL/FLL/RLL flow controls all ports if the receive queue becomes full.

Half-Duplex Backpressure

A half-duplex backpressure option (not in IEEE 802.3 standards) is also provided. The activation and deactivation conditions are the same as full duplex flow control. If backpressure is required, the KSZ8863MLL/FLL/RLL sends preambles to defer the other stations' transmission (carrier sense deference).

To avoid jabber and excessive deference (as defined in the 802.3 standard), after a certain time, the KSZ8863MLL/FLL/RLL discontinues the carrier sense and then raises it again quickly. This short silent time (no carrier sense) prevents other stations from sending out packets thus keeping other stations in a carrier sense deferred state. If the port has packets to send during a backpressure situation, the carrier sense type backpressure is interrupted and those packets are transmitted instead. If there are no additional packets to send, carrier sense type backpressure is reactivated again until switch resources free up. If a collision occurs, the binary exponential back-off algorithm is skipped and carrier sense is generated immediately, thus reducing the chance of further collisions and carrier sense is maintained to prevent packet reception.

To ensure no packet loss in 10 BASE-T or 100 BASE-TX half duplex modes, the user must enable the following:

- Aggressive back-off (register 3 (0x03), bit [0])
- No excessive collision drop (register 4 (0x04), bit [3])

Note: These bits are not set as defaults, as this is not the IEEE standard.

Broadcast Storm Protection

The KSZ8863MLL/FLL/RLL has an intelligent option to protect the switch system from receiving too many broadcast packets. As the broadcast packets are forwarded to all ports except the source port, an excessive number of switch resources (bandwidth and available space in transmit queues) may be utilized. The KSZ8863MLL/FLL/RLL has the option to include "multicast packets" for storm control. The broadcast storm rate parameters are programmed globally, and can be enabled or disabled on a per port basis. The rate is based on a 67ms interval for 100BT and a 500ms interval for 10BT. At the beginning of each interval, the counter is cleared to zero, and the rate limit mechanism starts to count the number of bytes during the interval. The rate definition is described in register 6 (0x06) and 7 (0x07). The default setting is 0x63 (99 decimal). This is equal to a rate of 1%, calculated as follows:

148,800 frames/sec × 67ms/interval × 1% = 99 frames/interval (approx.) = 0x63

Note: 148,800 frames/sec is based on 64-byte block of packets in 100BASE-TX with 12 bytes of IPG and 8 bytes of preamble between two packets.

Port Individual MAC address and Source Port Filtering

The KSZ8863MLL/FLL/RLL provide individual MAC address for port 1 and port 2 respectively. They can be set at register 142-147 and 148-153. The packet will be filtered if its source address matches the MAC address of port 1 or port 2 when the register 21 and 37 bit 6 is set to 1 respectively. For example, the packet will be dropped after it completes the loop of a ring network.

MII Interface Operation

The Media Independent Interface (MII) is specified in Clause 22 of the IEEE 802.3u Standard. It provides a common interface between physical layer and MAC layer devices. The MII provided by the KSZ8863MLL/FLL is connected to the device's third MAC, the MII default is PHY mode and can set to MAC mode by the register 53 bit7. The interface contains two distinct groups of signals: one for transmission and the other for reception. Table 4 describes the signals used by the MII bus.

PHY-Mode Connections			MAC-Mode Con	nections
External MAC	KSZ8863MLL/FLL	Pin	External	KSZ8863MLL/FLL
Controller Signals	PHY Signals	Descriptions	PHY Signals	MAC Signals
MTXEN	SMTXEN3	Transmit enable	MTXEN	SMRXDV3
MTXER	SMTXER3	Transmit error	MTXER	(not used)
MTXD3	SMTXD33	Transmit data bit 3	MTXD3	SMRXD33
MTXD2	SMTXD32	Transmit data bit 2	MTXD2	SMRXD32
MTXD1	SMTXD31	Transmit data bit 1	MTXD1	SMRXD31
MTXD0	SMTXD30	Transmit data bit 0	MTXD0	SMRXD30
MTXC	SMTXC3	Transmit clock	MTXC	SMRXC3
MCOL	SCOL3	Collision detection	MCOL	SCOL3
MCRS	SCRS3	Carrier sense	MCRS	SCRS3
MRXDV	SMRXDV3	Receive data valid	MRXDV	SMTXEN3
MRXER	(not used)	Receive error	MRXER	SMTXER3
MRXD3	SMRXD33	Receive data bit 3	MRXD3	SMTXD33
MRXD2	SMRXD32	Receive data bit 2	MRXD2	SMTXD32
MRXD1	SMRXD31	Receive data bit 1	MRXD1	SMTXD31
MRXD0	SMRXD30	Receive data bit 0	MRXD0	SMTXD30
MRXC	SMRXC3	Receive clock	MRXC	SMTXC3

Table 4. MII Signals

The MII operates in either PHY mode or MAC mode. The data interface is a nibble wide and runs at ¼ the network bit rate (not encoded). Additional signals on the transmit side indicate when data is valid or when an error occurs during transmission. Similarly, the receive side has signals that convey when the data is valid and without physical layer errors. For half duplex operation, the SCOL signal indicates if a collision has occurred during transmission.

The KSZ8863MLL/FLL does not provide the MRXER signal for PHY mode operation and the MTXER signal for MAC mode operation. Normally, MRXER indicates a receive error coming from the physical layer device and MTXER indicates a transmit error from the MAC device. Since the switch filters error frames, these MII error signals are not used by the KSZ8863MLL/FLL. So, for PHY mode operation, if the device interfacing with the KSZ8863MLL/FLL has an MRXER input pin, it needs to be tied low. And, for MAC mode operation, if the device interfacing with the KSZ8863MLL/FLL has an MTXER input pin, it also needs to be tied low.

The KSZ8863MLL/FLL provides a bypass feature in the MII PHY mode. Pin SMTXER3/MII_LINK is used for MII link status. If the host is power down, pin MII_LINK will go to high. In this case, no new ingress frames from port1 or port 2 will be sent out through port 3, and the frames for port 3 already in packet memory will be flushed out.

RMII Interface Operation

The Reduced Media Independent Interface (RMII) specifies a low pin count Media Independent Interface (MII). RMII provides a common interface between physical layer and MAC layer devices, and has the following key characteristics:

- 1. ports 10Mbps and 100Mbps data rates.
- 2. Uses a single 50 MHz clock reference (provided internally or externally).
- 3. Provides independent 2-bit wide (di-bit) transmit and receive data paths.
- 4. Contains two distinct groups of signals: one for transmission and the other for reception

When EN_REFCLKO_3 is high, KSZ8863RLL will output a 50MHz in REFCLKO_3. Register 198 bit[3] is used to select internal or external reference clock. Internal reference clock means that the clock for the RMII of KSZ8863RLL will be provided by the KSZ8863RLL internally and the REFCLKI_3 pin is unconnected. For the external reference clock, the clock will provide to KSZ8863RLL via REFCLKI_3.

Note: If the reference clock is not provided by the KSZ8863RLL, this 50MHz reference clock with an external divide by 2 device has to be used in X1 pin instead of the 25MHz crystal since the clock skew of these two clock sources will impact on the RMII timing before Rev.A3 part. The Rev A3 part can connect the external 50MHz reference clock to X1 pin and SMTXC3/REFCLKI_3 pins directly with strap pins of pin 17 SMTXD33/EN_REFCLKO_3 and pin 18 SMTXD32 to be pulled down.

	Pin 17 SMTXD33	Pin 18 SMTXD32		
Reg198 bit[3]	/EN_REFCLKO_3 Internal pull-up		Clock Source	Note
	Internal pull-up	(For Rev A3)		
0	0 (pull down by 1k)	0 (pull down by 1k)	External 50MHz OSC input to SMTXC3 /REFCLKI_3 and X1 pin directly	EN_REFCLKO_3 = 0 to Disable REFCLKO_3 for better EMI
0	1	0 (pull down by 1k)	50MHz on X1 pin is as clock source. REFCLKO_3 Output Is Feedback to REFCLKI_3 externally	EN_REFCLKO_3 = 1 to Enable REFCLKO_3
0	1	1	25MHz on X1 pin is as clock source. REFCLKO_3 Output is	EN_REFCLKO_3 = 1 to Enable REFCLKO_3
			connected to REFCLKI_3 externally	
1	0	0 or 1	25MHz on X1 pin, 50MHz RMII Clock goes to SMTXC3/ REFCLKI_3 internally.	EN_REFCLKO_3 = 0 to disable REFCLKO_3 for bottor EMI
			REFCLKI_3 is unconnected	for better EMI

Table 5. RMII Clock Setting

The RMII provided by the KSZ8863RLL is connected to the device's third MAC. It complies with the RMII Specification. Table 6 describes the signals used by the RMII bus. Refer to RMII Specification for full detail on the signal description.

RMII Signal Name	Direction (with respect to the PHY)	Direction (with respect to the MAC)	RMII Signal Description	KSZ8863RLL RMII Signal (direction)
REF_CLK	Input	Input or Output	Synchronous 50 MHz clock reference for receive, transmit and control interface	REFCLKI_3 (input)
CRS_DV	Output	Input	Carrier sense/ Receive data valid	SMRXDV3 (output)
RXD1	Output	Input	Receive data bit 1	SMRXD31 (output)
RXD0	Output	Input	Receive data bit 0	SMRXD30 (output)
TX_EN	Input	Output	Transmit enable	SMTXEN3 (input)
TXD1	Input	Output	Transmit data bit 1	SMTXD31 (input)
TXD0	Input	Output	Transmit data bit 0	SMTXD30 (input)
RX_ER	Output	Input (not required)	Receive error	(not used)
				SMTXER3* (input) * Connects to RX_ER signal of RMII PHY device

Table 6. RMII Signal Description

The KSZ8863RLL filters error frames, and thus does not implement the RX_ER output signal. To detect error frames from RMII PHY devices, the SMTXER3 input signal of the KSZ8863RLL is connected to the RXER output signal of the RMII PHY device.

Collision detection is implemented in accordance with the RMII Specification.

In RMII mode, the MII signals, SMTXD3[3:2] and SMTXER3, can be floating if they are used as default strap options.

The KSZ8863RLL RMII can interface with RMII PHY and RMII MAC devices. The latter allows two KSZ8863RLL devices to be connected back-to-back. Table 7 shows the KSZ8863RLL RMII pin connections with an external RMII PHY and an external RMII MAC, such as another KSZ8863RLL device.

KSZ8863RLL			KSZ88	63RLL
PHY-MAC Connection	PHY-MAC Connections			Connections
External	KSZ8863RLL	Pin	KSZ8863RLL	External
PHY Signals	MAC Signals	Descriptions	MAC Signals	MAC Signals
REF_CLK	REFCLKI_3	Reference Clock	REFCLKI_3	REF_CLK
TX_EN	SMRXDV3	Carrier sense/ Receive data valid	SMRXDV3	CRS_DV
TXD1	SMRXD31	Receive data bit 1	SMRXD31	RXD1
TXD0	SMRXD30	Receive data bit 0	SMRXD30	RXD0
CRS_DV	SMTXEN3	Transmit enable	SMTXEN3	TX_EN
RXD1	SMTXD31	Transmit data bit 1	SMTXD31	TXD1
RXD0	SMTXD30	Transmit data bit 0	SMTXD30	TXD0
RX_ER	SMTXER3	Receive error	(not used)	(not used)

Table 7. RMII Signal Connections

MII Management (MIIM) Interface

The KSZ8863MLL/FLL/RLL supports the IEEE 802.3 MII Management Interface, also known as the Management Data Input/Output (MDIO) Interface. This interface allows upper-layer devices to monitor and control the states of the KSZ8863MLL/FLL/RLL. An external device with MDC/MDIO capability is used to read the PHY status or configure the PHY settings. Further detail on the MIIM interface is found in Clause 22.2.4.5 of the IEEE 802.3u Specification and refer to 802.3 section 22.3.4 for the timing.

The MIIM interface consists of the following:

- A physical connection that incorporates the data line (SDA_MDIO) and the clock line (SCL_MDC).
- A specific protocol that operates across the aforementioned physical connection that allows an external controller to communicate with the KSZ8863MLL/FLL/RLL device.
- Access to a set of eight 16-bit registers, consisting of six standard MIIM registers [0:5] and two custom MIIM registers [29, 31].

The MIIM Interface can operate up to a maximum clock speed of 5MHz.

Table 8 depicts the MII Management Interface frame format.

	Preamble	Start of Frame	Read/Write OP Code	PHY Address Bits [4:0]	REG Address Bits [4:0]	ТА	Data Bits [15:0]	ldle
Read	32 1's	01	10	AAAAA	RRRRR	Z0	DDDDDDDD_DDDDDDD	Z
Write	32 1's	01	01	AAAA	RRRRR	10	DDDDDDDD_DDDDDDD	Z

Table 8.	MII Management	Interface	Frame Forr	nat
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Serial Management Interface (SMI)

The SMI is the KSZ8863MLL/FLL/RLL non-standard MIIM interface that provides access to all KSZ8863MLL/FLL/RLL configuration registers. This interface allows an external device to completely monitor and control the states of the KSZ8863MLL/FLL/RLL.

The SMI interface consists of the following:

- A physical connection that incorporates the data line (SDA_MDIO) and the clock line (SCL_MDC).
- A specific protocol that operates across the aforementioned physical connection that allows an external controller to communicate with the KSZ8863MLL/FLL/RLL device.
- Access to all KSZ8863MLL/FLL/RLL configuration registers. Register access includes the Global, Port and Advanced Control Registers 0-198 (0x00 – 0xC6), and indirect access to the standard MIIM registers [0:5] and custom MIIM registers [29, 31].

Table 9 depicts the SMI frame format.

	Preamble	Start of Frame	Read/Write OP Code	PHY Address Bits [4:0]	REG Address Bits [4:0]	ТА	Data Bits [15:0]	ldle
Read	32 1's	01	00	1xRRR	RRRRR	Z0	0000_0000_DDDD_DDDD	Z
Write	32 1's	01	00	0xRRR	RRRRR	10	xxxx_xxxx_DDDD_DDDD	Z

 Table 9. Serial Management Interface (SMI) Frame Format

SMI register read access is selected when OP Code is set to "00" and bit 4 of the PHY address is set to '1'. SMI register write access is selected when OP Code is set to "00" and bit 4 of the PHY address is set to '0'. PHY address bit[3] is undefined for SMI register access, and hence can be set to either '0' or '1' in read/write operations.

To access the KSZ8873MLL/FLL/RLL registers 0-196 (0x00 – 0xC6), the following applies:

- PHYAD[2:0] and REGAD[4:0] are concatenated to form the 8-bit address; that is, {PHYAD[2:0], REGAD[4:0]} = bits [7:0] of the 8-bit address.
- TA bits [1:0] are 'Z0' means the processor MDIO pin is changed to input Hi-Z from output mode and the followed '0' is the read response from device.
- TA bits [1:0] are set to '10' when write registers.
- Registers are 8 data bits wide.

For read operation, data bits [15:8] are read back as 0's.

For write operation, data bits [15:8] are not defined, and hence can be set to either '0' or '1'.

SMI register access is the same as the MIIM register access, except for the register access requirements presented in this section.

Advanced Switch Functions

Bypass Mode

The KSZ8863MLL/FLL/RLL also offer a by-pass mode which enables system-level power saving. When the CPU (connected to Port 3) enters a power saving mode of power down or sleeping mode, the CPU can control the pin 24 SMTXER3/MII_LINK_3 which can be tied high so that the KSZ8863MLL/FLL/RLL detect this change and automatically switches to the by-pass mode in which the switch function between Port1 and Port2 is sustained. In the by-pass mode, the packets with DA to port 3 will be dropped and by pass the internal buffer memory, make the buffer memory more efficiency for the data transfer between port 1 and port 2. Specially, the power saving get more in energy detect mode with the by-pass to be used.

IEEE 802.1Q VLAN Support

The KSZ8863MLL/FLL/RLL supports 16 active VLANs out of the 4096 possible VLANs specified in the IEEE 802.1Q specification. KSZ8863MLL/FLL/RLL provides a 16-entries VLAN Table, which converts the 12-bits VLAN ID (VID) to the 4-bits Filter ID (FID) for address lookup. If a non-tagged or null-VID-tagged packet is received, the ingress port default VID is used for lookup. In VLAN mode, the lookup process starts with VLAN Table lookup to determine whether the VID is valid. If the VID is not valid, the packet is dropped and its address is not learned. If the VID is valid, the FID is retrieved for further lookup. The FID + Destination Address (FID+DA) are used to determine the destination port. The FID + Source Address (FID+SA) are used for address learning.

DA found in Static MAC Table?	Use FID flag?	FID match?	DA+FID found in Dynamic MAC Table?	Action
No	Don't care	Don't care	No	Broadcast to the membership ports defined in the VLAN Table bits [18:16]
No	Don't care	Don't care	Yes	Send to the destination port defined in the Dynamic MAC Address Table bits [53:52]
Yes	0	Don't care	Don't care	Send to the destination port(s) defined in the Static MAC Address Table bits [50:48]
Yes	1	No	No	Broadcast to the membership ports defined in the VLAN Table bits [18:16]
Yes	1	No	Yes	Send to the destination port defined in the Dynamic MAC Address Table bits [53:52]
Yes	1	Yes	Don't care	Send to the destination port(s) defined in the Static MAC Address Table bits [50:48]

Table 10. FID+DA Lookup in VLAN Mode

FID+SA found in Dynamic MAC Table?	Action			
No	Learn and add FID+SA to the Dynamic MAC Address Table			
Yes	Update time stamp			

Table 11. FID+SA Lookup in VLAN Mode

Advanced VLAN features, such as "Ingress VLAN filtering" and "Discard Non PVID packets" are also supported by the KSZ8863MLL/FLL/RLL. These features can be set on a per port basis, and are defined in register 18, 34 and 50 for ports 1, 2 and 3, respectively.

QoS Priority Support

The KSZ8863MLL/FLL/RLL provides Quality of Service (QoS) for applications such as VoIP and video conferencing. Offering four priority queues per port, the per-port transmit queue can be split into four priority queues: Queue 3 is the highest priority queue and Queue 0 is the lowest priority queue. Bit [0] of registers 16, 32 and 48 is used to enable split transmit queues for ports 1, 2 and 3, respectively. If a port's transmit queue is not split, high priority and low priority packets have equal priority in the transmit queue.

There is an additional option to either always deliver high priority packets first or use weighted fair queuing for the four priority queues. This global option is set and explained in bit [3] of register 5.

Port-Based Priority

With port-based priority, each ingress port is individually classified as a high priority receiving port. All packets received at the high priority receiving port are marked as high priority and are sent to the high-priority transmit queue if the corresponding transmit queue is split. Bits [4:3] of registers 16, 32 and 48 are used to enable port-based priority for ports 1, 2 and 3, respectively.

802.1p-Based Priority

For 802.1p-based priority, the KSZ8863MLL/FLL/RLL examines the ingress (incoming) packets to determine whether they are tagged. If tagged, the 3-bit priority field in the VLAN tag is retrieved and compared against the "priority mapping" value, as specified by the registers 12 and 13. The "priority mapping" value is programmable.

Figure 6 illustrates how the 802.1p priority field is embedded in the 802.1Q VLAN tag.

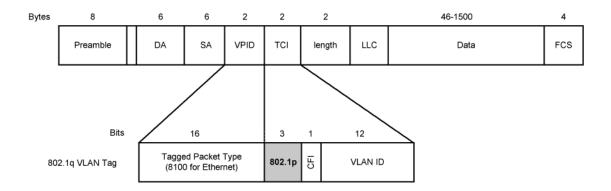


Figure 6. 802.1p Priority Field Format

802.1p-based priority is enabled by bit [5] of registers 16, 32 and 48 for ports 1, 2 and 3, respectively.

The KSZ8863MLL/FLL/RLL provides the option to insert or remove the priority tagged frame's header at each individual egress port. This header, consisting of the 2 bytes VLAN Protocol ID (VPID) and the 2-byte Tag Control Information field (TCI), is also referred to as the IEEE 802.1Q VLAN tag.

Tag Insertion is enabled by bit [2] of the port registers control 0 and the register 194 to select which source port (ingress port) PVID can be inserted on the egress port for ports 1, 2 and 3, respectively. At the egress port, untagged packets are tagged with the ingress port's default tag. The default tags are programmed in register sets {19,20}, {35,36} and {51,52} for ports 1, 2 and 3, respectively and the source port VID has to be inserted at selected egress ports by bit[5:0] of register 194. The KSZ8863MLL/FLL/RLL will not add tags to already tagged packets.

Tag Removal is enabled by bit [1] of registers 16, 32 and 48 for ports 1, 2 and 3, respectively. At the egress port, tagged packets will have their 802.1Q VLAN Tags removed. The KSZ8863MLL/FLL/RLL will not modify untagged packets.

The CRC is recalculated for both tag insertion and tag removal.

802.1p Priority Field Re-mapping is a QoS feature that allows the KSZ8863MLL/FLL/RLL to set the "User Priority Ceiling" at any ingress port. If the ingress packet's priority field has a higher priority value than the default tag's priority field of the ingress port, the packet's priority field is replaced with the default tag's priority field.

DiffServ-Based Priority

DiffServ-based priority uses the ToS registers (registers 96 to 111) in the Advanced Control Registers section. The ToS priority control registers implement a fully decoded, 64-bit Differentiated Services Code Point (DSCP) register to determine packet priority from the 6-bit ToS field in the IP header. When the most significant 6 bits of the ToS field are fully decoded, the resultant of the 64 possibilities is compared with the corresponding bits in the DSCP register to determine priority.

Spanning Tree Support

To support spanning tree, port 3 is designated as the processor port.

The other ports (port 1 and port 2) can be configured in one of the five spanning tree states via "transmit enable", "receive enable" and "learning disable" register settings in registers 18 and 34 for ports 1 and 2, respectively. The following table shows the port setting and software actions taken for each of the five spanning tree states.

Disable State	Port Setting	Software Action			
The port should not forward or receive any packets. Learning is disabled.	"transmit enable = 0, receive enable = 0, learning disable =1"	The processor <u>should not send</u> any packets to the port. The switch may still send specific packets to the processor (packets that match some entries in the "static MAC table" with "overriding bit" set) and the processor should discard those packets. Address learning is disabled on the port in this state.			
Blocking State	Port Setting	Software Action			
Only packets to the processor are forwarded. Learning is disabled.	"transmit enable = 0, receive enable = 0, learning disable =1"	The processor <u>should not send</u> any packets to the port(s) in this state. The processor should program the "Static MAC table" with the entries that it needs to receive (for example, BPDU packets). The "overriding" bit should also be set so that the switch will forward those specific packets to the processor. Address learning is disabled on the port in this state.			
Listening State	Port Setting	Software Action			
Only packets to and from the processor are forwarded. Learning is disabled.	"transmit enable = 0, receive enable = 0, learning disable =1"	The processor should program the "Static MAC table" with the entries that it needs to receive (for example, BPDU packets). The "overriding" bit should be set so that the switch will forward those specific packets to the processor. The processor may send packets to the port(s) in this state. See "Tail Tagging Mode" for details. Address learning is disabled on the port in this state.			
Learning State	Port Setting	Software Action			
Only packets to and from the processor are forwarded. Learning is enabled.	"transmit enable = 0, receive enable = 0, learning disable = 0"	The processor should program the "Static MAC table" with the entries that it needs to receive (for example, BPDU packets). The "overriding" bit should be set so that the switch will forward those specific packets to the processor. The processor may send packets to the port(s) in this state. See "Tail Tagging Mode" for details. Address learning is enabled on the port in this state.			
Forwarding State	Port Setting	Software Action			
Packets are forwarded and received normally. Learning is enabled.	"transmit enable = 1, receive enable = 1, learning disable = 0"	The processor programs the "Static MAC table" with the entries that it needs to receive (for example, BPDU packets). The "overriding" bit is set so that the switch forwards those specific packets to the processor. The processor can send packets to the port(s) in this state. See "Tail Tagging Mode" for details. Address learning is enabled on the port in this state.			

Table 12. Spanning Tree States

Rapid Spanning Tree Support

There are three operational states of the Discarding, Learning, and Forwarding assigned to each port for RSTP:

Discarding ports do not participate in the active topology and do not learn MAC addresses.

Discarding state: the state includs three states of the disable, blocking and listening of STP.

Port setting: "transmit enable = 0, receive enable = 0, learning disable = 1."

Software action: the processor should not send any packets to the port. The switch may still send specific packets to the processor (packets that match some entries in the static table with "overriding bit" set) and the processor should discard those packets. When disable the port's learning capability (learning disable='1'), set the register 2 bit 5 and bit 4 will flush rapidly the port related entries in the dynamic MAC table and static MAC table.

Note: processor is connected to port 3 via MII interface. Address learning is disabled on the port in this state.

Ports in Learning states learn MAC addresses, but do not forward user traffic.

Learning state: only packets to and from the processor are forwarded. Learning is enabled.

Port setting: "transmit enable = 0, receive enable = 0, learning disable = 0."

Software action: The processor should program the static MAC table with the entries that it needs to receive (e.g., BPDU packets). The "overriding" bit should be set so that the switch will forward those specific packets to the processor. The processor may send packets to the port(s) in this state, see "Tail Tagging Mode" section for details. Address learning is enabled on the port in this state.

Ports in Forwarding states fully participate in both data forwarding and MAC learning.

Forwarding state: packets are forwarded and received normally. Learning is enabled.

Port setting: "transmit enable = 1, receive enable = 1, learning disable = 0."

Software action: The processor should program the static MAC table with the entries that it needs to receive (e.g., BPDU packets). The "overriding" bit should be set so that the switch will forward those specific packets to the processor. The processor may send packets to the port(s) in this state, see "Tail Tagging Mode" section for details. Address learning is enabled on the port in this state.

RSTP uses only one type of BPDU called RSTP BPDUs. They are similar to STP Configuration BPDUs with the exception of a type field set to "version 2" for RSTP and "version 0" for STP, and a flag field carrying additional information.

Tail Tagging Mode

The Tail Tag is only seen and used by the port 3 interface, which should be connected to a processor. It is an effective way to retrieve the ingress port information for spanning tree protocol IGMP snooping and other applications. The Bit 1 and bit 0 in the one byte tail tagging is used to indicate the source/destination port in port 3. Bit 3 and bit 2 are used for the priority setting of the ingress frame in port 3. Other bits are not used. The Tail Tag feature is enable by setting register 3 bit 6.

Bytes	8	6	6	2	2	2	46-1500 1		4	
	Preamble	DA	SA	VPID	тсі	length	LLC	Data	Tail Tag	FCS



Ingress to Port 3 (Host -> KSZ8863)					
Bit [1,0]	Destination Port				
0,0	Normal (Address Look up)				
0,1	Port 1				
1,0	Port 2				
1,1	Port 1 and 2				
Bit [3,2]	Frame Priority				
0,0	Priority 0				
0,1	Priority 1				
1,0	Priority 2				
1,1	Priority 3				
Egress from Port 3 (KSZ8863->Host)					
Bit [0]	Source Port				
0	Port 1				
1	Port 2				

Figure 8. Tail Tag Rules

IGMP Support

For Internet Group Management Protocol (IGMP) support in layer 2, the KSZ8863MLL/FLL/RLL provides two components:

IGMP Snooping

The KSZ8863MLL/FLL/RLL traps IGMP packets and forwards them only to the processor (port 3). The IGMP packets are identified as IP packets (either Ethernet IP packets, or IEEE 802.3 SNAP IP packets) with IP version = 0x4 and protocol version number = 0x2.

IGMP Send Back to the Subscribed Port

Once the host responds the received IGMP packet, the host should knows the original IGMP ingress port and send back the IGMP packet to this port only, otherwise this IGMP packet will be broadcasted to all port to downgrade the performance.

Enable the tail tag mode, the host will know the IGMP packet received port from tail tag bits [0] and can send back the response IGMP packet to this subscribed port by setting the bits [1,0] in the tail tag. Enable "Tail tag mode" by setting Register 3 bit 6. The tail tag will be removed automatically when the IGMP packet is sent out from the subscribed port.

Port Mirroring Support

KSZ8863MLL/FLL/RLL supports "Port Mirroring" comprehensively as:

"receive only" mirror on a port

All the packets received on the port are mirrored on the sniffer port. For example, port 1 is programmed to be "receive sniff" and port 3 is programmed to be the "sniffer port". A packet received on port 1 is destined to port 2 after the internal lookup. The KSZ8863MLL/FLL/RLL forwards the packet to both port 2 and port 3. The KSZ8863MLL/FLL/RLL can optionally even forward "bad" received packets to the "sniffer port".

"transmit only" mirror on a port

All the packets transmitted on the port are mirrored on the sniffer port. For example, port 1 is programmed to be "transmit sniff" and port 3 is programmed to be the "sniffer port". A packet received on port 2 is destined to port 1 after the internal lookup. The KSZ8863MLL/FLL/RLL forwards the packet to both port 1 and port 3.

"receive and transmit" mirror on two ports

All the packets received on port A and transmitted on port B are mirrored on the sniffer port. To turn on the "AND" feature, set register 5 bit [0] to '1'. For example, port 1 is programmed to be "receive sniff", port 2 is programmed to be "transmit sniff", and port 3 is programmed to be the "sniffer port". A packet received on port 1 is destined to port 2 after the internal lookup. The KSZ8863MLL/FLL/RLL forwards the packet to both port 2 and port 3.

Multiple ports can be selected as "receive sniff" or "transmit sniff". In addition, any port can be selected as the "sniffer port". All these per port features can be selected through registers 17, 33 and 49 for ports 1, 2 and 3, respectively.

Rate Limiting Support

The KSZ8863MLL/FLL/RLL provides a fine resolution hardware rate limiting from 64Kbps to 99Mbps. The rate step is 64Kbps when the rate range is from 64Kbps to 960Kbps and 1Mbps for 1Mbps to 100Mbps(100BT) or to 10Mbps(10BT) (refer to Data Rate Limit Table). The rate limit is independently on the "receive side" and on the "transmit side" on a per port basis. For 10BASE-T, a rate setting above 10 Mbps means the rate is not limited. On the receive side, the data receive rate for each priority at each port can be limited by setting up Ingress Rate Control Registers. On the transmit side, the data transmit rate for each priority queue at each port can be limited by setting up Egress Rate Control Registers. The size of each frame has options to include minimum IFG (Inter Frame Gap) or Preamble byte, in addition to the data field (from packet DA to FCS).

For ingress rate limiting, KSZ8863MLL/FLL/RLL provides options to selectively choose frames from all types, multicast, broadcast, and flooded unicast frames. The KSZ8863MLL/FLL/RLL counts the data rate from those selected type of frames. Packets are dropped at the ingress port when the data rate exceeds the specified rate limit.

For egress rate limiting, the Leaky Bucket algorithm is applied to each output priority queue for shaping output traffic. Inter frame gap is stretched on a per frame base to generate smooth, non-burst egress traffic. The throughput of each output priority queue is limited by the egress rate specified.

If any egress queue receives more traffic than the specified egress rate throughput, packets may be accumulated in the output queue and packet memory. After the memory of the queue or the port is used up, packet dropping or flow control will be triggered. As a result of congestion, the actual egress rate may be dominated by flow control/dropping at the ingress end, and may be therefore slightly less than the specified egress rate.

To reduce congestion, it is a good practice to make sure the egress bandwidth exceeds the ingress bandwidth.

Unicast MAC Address Filtering

The unicast MAC address filtering function works in conjunction with the static MAC address table. First, the static MAC address table is used to assign a dedicated MAC address to a specific port. If a unicast MAC address is not recorded in the static table, it is also not learned in the dynamic MAC table. The KSZ8863MLL/FLL/RLL is then configured with the option to either filter or forward unicast packets for an unknown MAC address. This option is enabled and configured in register 14.

This function is useful in preventing the broadcast of unicast packets that could degrade the quality of the port in applications such as voice over Internet Protocol (VoIP).

Configuration Interface

The KSZ8863MLL/FLL/RLL can operate as both a managed switch and an unmanaged switch.

In unmanaged mode, the KSZ8863MLL/FLL/RLL is typically programmed using an EEPROM. If no EEPROM is present, the KSZ8863MLL/FLL/RLL is configured using its default register settings. Some default settings are configured via strapin pin options. The strap-in pins are indicated in the "Pin Description and I/O Assignment" table.

f²C Master Serial Bus Configuration

With an additional I²C ("2-wire") EEPROM, the KSZ8863MLL/FLL/RLL can perform more advanced switch features like "broadcast storm protection" and "rate control" without the need of an external processor.

For KSZ8863MLL/FLL/RLL I²C Master configuration, the EEPROM stores the configuration data for register 0 to register 198 (as defined in the KSZ8863MLL/FLL/RLL register map) with the exception of the "Read Only" status registers. After the de-assertion of reset, the KSZ8863MLL/FLL/RLL sequentially reads in the configuration data for all 199 registers, starting from register 0.

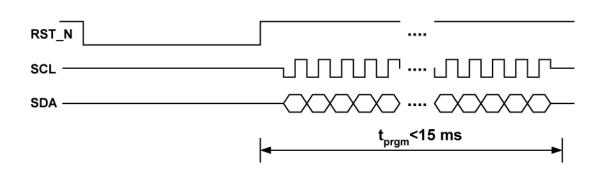


Figure 9. EEPROM Configuration Timing Diagram

The following is a sample procedure for programming the KSZ8863MLL/FLL/RLL with a pre-configured EEPROM:

- 1. Connect the KSZ8863MLL/FLL/RLL to the EEPROM by joining the SCL and SDA signals of the respective devices.
- 2. Enable I²C master mode by setting the KSZ8863MLL/FLL/RLL strap-in pins, P2LED[1:0] to "00".
- 3. Check to ensure that the KSZ8863MLL/FLL/RLL reset signal input, RSTN, is properly connected to the external reset source at the board level.
- 4. Program the desired configuration data into the EEPROM.
- 5. Place the EEPROM on the board and power up the board.
- 6. Assert an active-low reset to the RSTN pin of the KSZ8863MLL/FLL/RLL. After reset is de-asserted, the KSZ8863MLL/FLL/RLL begins reading the configuration data from the EEPROM. The KSZ8863MLL/FLL/RLL checks that the first byte read from the EEPROM is "88". If this value is correct, EEPROM configuration continues. If not, EEPROM configuration access is denied and all other data sent from the EEPROM is ignored by the KSZ8863MLL/FLL/RLL.

f²C Slave Serial Bus Configuration

In managed mode, the KSZ8863MLL/FLL/RLL can be configured as an I²C slave device. In this mode, an I²C master device (external controller/CPU) has complete programming access to the KSZ8863MLL/FLL/RLL's 198 registers. Programming access includes the Global Registers, Port Registers, Advanced Control Registers and indirect access to the "Static MAC Table", "VLAN Table", "Dynamic MAC Table," and "MIB Counters." The tables and counters are indirectly accessed via registers 121 to 131.

In I²C slave mode, the KSZ8863MLL/FLL/RLL operates like other I²C slave devices. Addressing the KSZ8863MLL/FLL/RLL's 8-bit registers is similar to addressing Atmel's AT24C02 EEPROM's memory locations. Details of I²C read/write operations and related timing information can be found in the AT24C02 Datasheet.

Two fixed 8-bit device addresses are used to address the KSZ8863MLL/FLL/RLL in I²C slave mode. One is for read; the other is for write. The addresses are as follow:

1011_1111 <read> 1011_1110 <write>

The following is a sample procedure for programming the KSZ8863MLL/FLL/RLL using the I²C slave serial bus:

- 1. Enable I²C slave mode by setting the KSZ8863MLL/FLL/RLL strap-in pins P2LED[1:0] to "01".
- Power up the board and assert reset to the KSZ8863MLL/FLL/RLL. Configure the desired register settings in the KSZ8863MLL/FLL/RLL, using the I²C write operation.
- 3. Read back and verify the register settings in the KSZ8863MLL/FLL/RLL, using the I²C read operation.

Some of the configuration settings, such as "Aging enable", "Auto Negotiation Enable", "Force Speed" and "Power down" can be programmed after the switch has been started.

SPI Slave Serial Bus Configuration

In managed mode, the KSZ8863MLL/FLL/RLL can be configured as a SPI slave device. In this mode, a SPI master device (external controller/CPU) has complete programming access to the KSZ8863MLL/FLL/RLL's 198 registers. Programming access includes the Global Registers, Port Registers, Advanced Control Registers and indirect access to the "Static MAC Table", "VLAN Table", "Dynamic MAC Table" and "MIB Counters". The tables and counters are indirectly accessed via registers 121 to 131.

The KSZ8863MLL/FLL/RLL supports two standard SPI commands: '0000_0011' for data read and '0000_0010' for data write. SPI multiple read and multiple write are also supported by the KSZ8863MLL/FLL/RLL to expedite register read back and register configuration, respectively.

SPI multiple read is initiated when the master device continues to drive the KSZ8863MLL/FLL/RLL SPISN input pin (SPI Slave Select signal) low after a byte (a register) is read. The KSZ8863MLL/FLL/RLL internal address counter increments automatically to the next byte (next register) after the read. The next byte at the next register address is shifted out onto the KSZ8863MLL/FLL/RLL SPIQ output pin. SPI multiple read continues until the SPI master device terminates it by deasserting the SPISN signal to the KSZ8863MLL/FLL/RLL.

Similarly, SPI multiple write is initiated when the master device continues to drive the KSZ8863MLL/FLL/RLL SPISN input pin low after a byte (a register) is written. The KSZ8863MLL/FLL/RLL internal address counter increments automatically to the next byte (next register) after the write. The next byte that is sent from the master device to the KSZ8863MLL/FLL/RLL SDA input pin is written to the next register address. SPI multiple write continues until the SPI master device terminates it by de-asserting the SPISN signal to the KSZ8863MLL/FLL/RLL.

For both SPI multiple read and multiple write, the KSZ8863MLL/FLL/RLL internal address counter wraps back to register address zero once the highest register address is reached. This feature allows all 198 KSZ8863MLL/FLL/RLL registers to be read, or written with a single SPI command from any initial register address.

The KSZ8863MLL/FLL/RLL is able to support SPI bus up to max 25MHz, A high performance SPI master is recommended to prevent internal counter overflow.

Table 13 is a sample procedure for programming the KSZ8863MLL/FLL/RLL using the SPI bus:

1. At the board level, connect the KSZ8863MLL/FLL/RLL pins as follows:

KSZ8863MLL/FLL/RLL Pin #	KSZ8863MLL/FLL/RLL Signal Name	External Processor Signal Description
39	SPISN	SPI Slave Select
26	SCL	SPI Clock
36	(SPIC)	SPICIOCK
27	SDA	SPI Data
37	(SPID)	(Master output; Slave input)
38	SPIQ	SPI Data (Master input; Slave output)

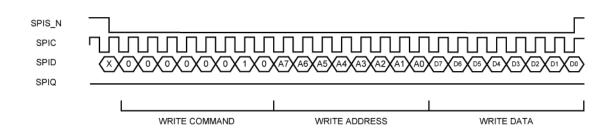
Table 13. SPI Connections

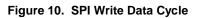
- 2. Enable SPI slave mode by setting the KSZ8863MLL/FLL/RLL strap-in pins P2LED[1:0] to "10".
- 3. Power up the board and assert reset to the KSZ8863MLL/FLL/RLL.
- 4. Configure the desired register settings in the KSZ8863MLL/FLL/RLL, using the SPI write or multiple write command.
- 5. Read back and verify the register settings in the KSZ8863MLL/FLL/RLL, using the SPI read or multiple read command.

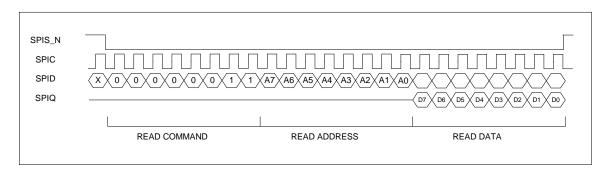
Some of the configuration settings, such as "Aging enable", "Auto Negotiation Enable", "Force Speed" and "Power down" can be programmed after the switch has been started.

The following four figures illustrate the SPI data cycles for "Write", "Read", "Multiple Write" and "Multiple Read". The read data is registered out of SPIQ on the falling edge of SPIC, and the data input on SPID is registered on the rising edge of SPIC.

January 27, 2014









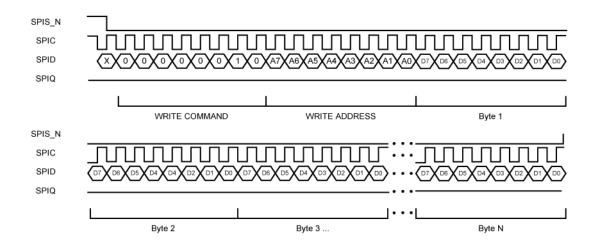


Figure 12. SPI Multiple Write

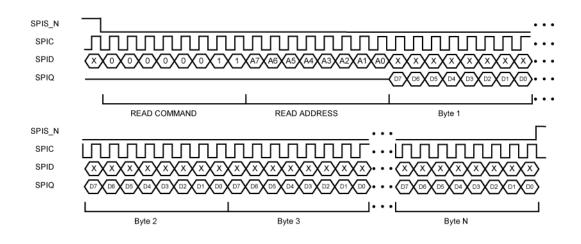


Figure 13. SPI Multiple Read

Loopback Support

The KSZ8863MLL/FLL/RLL provides loopback support for remote diagnostic of failure. In loopback mode, the speed at both PHY ports needs to be set to 100BASE-TX. Two types of loopback are supported: Far-end Loopback and Near-end (Remote) Loopback.

Far-End Loopback

Far-end loopback is conducted between the KSZ8863MLL/FLL/RLL's two PHY ports. The loopback is limited to few package a time for diagnosis purpose and can't support large traffic. The loopback path starts at the "Originating." PHY port's receive inputs (RXP/RXM), wraps around at the "loopback" PHY port's PMD/PMA, and ends at the "Originating" PHY port's transmit outputs (TXP/TXM).

Bit [0] of registers 29 and 45 is used to enable far-end loopback for ports 1 and 2, respectively. Alternatively, the MII Management register 0, bit [14] can be used to enable far-end loopback.

The far-end loopback path is illustrated in Figure 14.

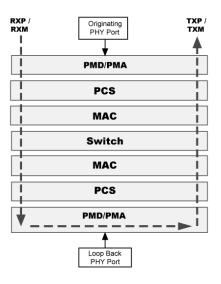


Figure 14. Far-End Loopback Path

Near-End (Remote) Loopback

Near-end (Remote) loopback is conducted at either PHY port 1 or PHY port 2.of the KSZ8863MLL/FLL/RLL. The loopback path starts at the PHY port's receive inputs (RXPx/RXMx), wraps around at the same PHY port's PMD/PMA, and ends at the PHY port's transmit outputs (TXPx/TXMx).

Bit [1] of registers 26 and 42 is used to enable near-end loopback for ports 1 and 2, respectively. Alternatively, the MII Management register 31, bit [1] can be used to enable near-end loopback.

The near-end loopback paths are illustrated in Figure 15.

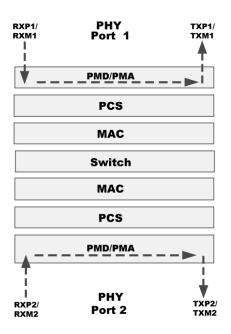


Figure 15. Near-End (Remote) Loopback Path

MII Management (MIIM) Registers

The MIIM interface is used to access the MII PHY registers defined in this section. The SPI, I^2C , and SMI interfaces can also be used to access some of these registers. The latter three interfaces use a different mapping mechanism than the MIIM interface.

The "PHYADs" by defaults are assigned "0x1" for PHY1 (port 1) and "0x2" for PHY2 (port 2). Additionally, these "PHYADs" can be programmed to the PHY addresses specified in bits[7:3] of Register 15 (0x0F): Global Control 13. The "REGAD" supported are 0x0-0x5, 0x1D and 0x1F.

Register Number	Description
PHYAD = 0x1, REGAD = 0x0	PHY1 Basic Control Register
PHYAD = 0x1, REGAD = 0x1	PHY1 Basic Status Register
PHYAD = 0x1, REGAD = 0x2	PHY1 Physical Identifier I
PHYAD = 0x1, REGAD = 0x3	PHY1 Physical Identifier II
PHYAD = 0x1, REGAD = 0x4	PHY1 Auto-Negotiation Advertisement Register
PHYAD = 0x1, REGAD = 0x5	PHY1 Auto-Negotiation Link Partner Ability Register
PHYAD = 0x1, 0x6 - 0x1C	PHY1 Not supported
PHYAD = 0x1, 0x1D	PHY1 Not supported
PHYAD = 0x1, 0x1E	PHY1 Not supported
PHYAD = 0x1, 0x1F	PHY1 Special Control/Status
PHYAD = 0x2, REGAD = 0x0	PHY2 Basic Control Register
PHYAD = 0x2, REGAD = 0x1	PHY2 Basic Status Register
PHYAD = 0x2, REGAD = 0x2	PHY2 Physical Identifier I
PHYAD = 0x2, REGAD = 0x3	PHY2 Physical Identifier II
PHYAD = 0x2, REGAD = 0x4	PHY2 Auto-Negotiation Advertisement Register
PHYAD = 0x2, REGAD = 0x5	PHY2 Auto-Negotiation Link Partner Ability Register
PHYAD = 0x2, 0x6 - 0x1C	PHY2 Not supported
PHYAD = 0x2, 0x1D	PHY2 LinkMD Control/Status
PHYAD = 0x2, 0x1E	PHY2 Not supported
PHYAD = 0x2, 0x1F	PHY2 Special Control/Status

PHY1 Register 0 (PHYAD = 0x1, REGAD = 0x0): MII Basic Control

PHY2 Register 0 (PHYAD = 0x2, REGAD = 0x0): MII Basic Control

Bit	Name	R/W	Description	Default	Reference
15	Soft reset	RO	NOT SUPPORTED	0	
14	Loopback	R/W	 = 1, Perform loopback, as indicated: Port 1 Loopback (reg. 29, bit 0 = '1') Start: RXP2/RXM2 (port 2) Loopback: PMD/PMA of port 1's PHY End: TXP2/TXM2 (port 2) Port 2 Loopback (reg. 45, bit 0 = '1') Start: RXP1/RXM1 (port 1) Loopback: PMD/PMA of port 2's PHY End: TXP1/TXM1 (port 1) =0, Normal operation 	0	Reg. 29, bit 0 Reg. 45, bit 0
13	Force 100	R/W	=1, 100 Mbps =0, 10 Mbps	0	Reg. 28, bit 6 Reg. 44, bit 6
12	AN enable	R/W	=1, Auto-negotiation enabled=0, Auto-negotiation disabled	1	Reg. 28, bit 7 Reg. 44, bit 7
11	Power down	R/W	=1, Power down =0, Normal operation	0	Reg. 29, bit 3 Reg. 45, bit 3
10	Isolate	RO	NOT SUPPORTED	0	
9	Restart AN	R/W	=1, Restart auto-negotiation =0, Normal operation	0	Reg. 29, bit 5 Reg. 45, bit 5
8	Force full duplex	R/W	=1, Full duplex =0, Half duplex	0	Reg. 28, bit 5 Reg. 44, bit 5
7	Collision test	RO	NOT SUPPORTED	0	
6	Reserved	RO		0	
5	Hp_mdix	R/W	1 = HP Auto MDI/MDI-X mode 0 = Micrel Auto MDI/MDI-X mode	1	Reg. 31, bit 7 Reg. 47, bit 7
4	Force MDI	R/W	=1, Force MDI (transmit on RXP / RXM pins) =0, Normal operation (transmit on TXP / TXM pins)	0	Reg. 29, bit 1 Reg. 45, bit 1
3	Disable MDIX	R/W	=1, Disable auto MDI-X =0, Enable auto MDI-X	0	Reg. 29, bit 2 Reg. 45, bit 2
2	Disable far-end fault	R/W	=1, Disable far-end fault detection =0, Normal operation	0	Reg. 29, bit 4
1	Disable transmit	R/W	=1, Disable transmit =0, Normal operation	0	Reg. 29, bit 6 Reg. 45, bit 6
0	Disable LED	R/W	=1, Disable LED =0, Normal operation	0	Reg. 29, bit 7 Reg. 45, bit 7

PHY1 Register 1 (PHYAD = 0x1, REGAD = 0x1): MII Basic Status

Bit	Name	R/W	Description	Default	Reference
15	T4 capable	RO	=0, Not 100 BASE-T4 capable	0	
14	100 Full capable	RO	=1, 100BASE-TX full duplex capable =0, Not capable of 100BASE-TX full duplex	1	Always 1
13	100 Half capable	RO	=1, 100BASE-TX half duplex capable =0, Not 100BASE-TX half duplex capable	1	Always 1
12	10 Full capable	RO	=1, 10BASE-T full duplex capable =0, Not 10BASE-T full duplex capable	1	Always 1
11	10 Half capable	RO	=1, 10BASE-T half duplex capable =0, Not 10BASE-T half duplex capable	1	Always 1
10-7	Reserved	RO		0000	
6	Preamble suppressed	RO	NOT SUPPORTED	0	
5	AN complete	RO	=1, Auto-negotiation complete=0, Auto-negotiation not completed	0	Reg. 30, bit 6 Reg. 46, bit 6
4	Far-end fault	RO	=1, Far-end fault detected =0, No far-end fault detected	0	Reg. 31, bit 0
3	AN capable	RO	=1, Auto-negotiation capable=0, Not auto-negotiation capable	1	Reg. 28, bit 7 Reg. 44, bit 7
2	Link status	RO	=1, Link is up =0, Link is down	0	Reg. 30, bit 5 Reg. 46, bit 5
1	Jabber test	RO	NOT SUPPORTED	0	
0	Extended capable	RO	=0, Not extended register capable	0	

PHY1 Register 2 (PHYAD = 0x1, REGAD = 0x2): PHYID High

PHY2 Register 2 (PHYAD = 0x2, REGAD = 0x2): PHYID High

Bit	Name	R/W	Description	Default
15-0	PHYID high	RO	High order PHYID bits	0x0022

PHY1 Register 3 (PHYAD = 0x1, REGAD = 0x3): PHYID Low

PHY2 Register 3 (PHYAD = 0x2, REGAD = 0x3): PHYID Low

Bit	Name	R/W	Description	Default
15-0	PHYID low	RO	Low order PHYID bits	0x1430

Bit	Name	R/W	Description	Default	Reference
15	Next page	RO	NOT SUPPORTED	0	
14	Reserved	RO		0	
13	Remote fault	RO	NOT SUPPORTED	0	
12-11	Reserved	RO		00	
10	Pause	R/W	=1, Advertise pause ability =0, Do not advertise pause ability	1	Reg. 28, bit 4 Reg. 44, bit 4
9	Reserved	R/W		0	
8	Adv 100 Full	R/W	=1, Advertise 100 full duplex ability =0, Do not advertise 100 full duplex ability	1	Reg. 28, bit 3 Reg. 44, bit 3
7	Adv 100 Half	R/W	=1, Advertise 100 half duplex ability =0, Do not advertise 100 half duplex ability	1	Reg. 28, bit 2 Reg. 44, bit 2
6	Adv 10 Full	R/W	=1, Advertise 10 full duplex ability =0, Do not advertise 10 full duplex ability	1	Reg. 28, bit 1 Reg. 44, bit 1
5	Adv 10 Half	R/W	=1, Advertise 10 half duplex ability =0, Do not advertise 10 half duplex ability	1	Reg. 28, bit 0 Reg. 44, bit 0
4-0	Selector field	RO	802.3	00001	

PHY1 Register 4 (PHYAD = 0x1, REGAD = 0x4): Auto-Negotiation Advertisement Ability PHY2 Register 4 (PHYAD = 0x2, REGAD = 0x4): Auto-Negotiation Advertisement Ability

PHY1 Register 5 (PHYAD = 0x1, REGAD = 0x5): Auto-Negotiation Link Partner Ability

PHY2 Register 5 (PHYAD = 0x2, REGAD = 0x5): Auto-Negotiation Link Partner Ability

Bit	Name	R/W	Description	Default	Reference
15	Next page	RO	NOT SUPPORTED	0	
14	LP ACK	RO	NOT SUPPORTED	0	
13	Remote fault	RO	NOT SUPPORTED	0	
12-11	Reserved	RO		00	
10	Pause	RO	Link partner pause capability	0	Reg. 30, bit 4 Reg. 46, bit 4
9	Reserved	RO		0	
8	Adv 100 Full	RO	Link partner 100 full capability	0	Reg. 30, bit 3 Reg. 46, bit 3
7	Adv 100 Half	RO	Link partner 100 half capability	0	Reg. 30, bit 2 Reg. 46, bit 2
6	Adv 10 Full	RO	Link partner 10 full capability	0	Reg. 30, bit 1 Reg. 46, bit 1
5	Adv 10 Half	RO	Link partner 10 half capability	0	Reg. 30, bit 0 Reg. 46, bit 0
4-0	Reserved	RO		00000	

PHY1 Register 29 (PHYAD = 0x1, REGAD = 0x1D): Not support

Bit	Name	R/W	Description	Default	Reference
15	Vct_enable	R/W (SC)	 =1, Enable cable diagnostic. After VCT test has completed, this bit will be self-cleared. =0, Indicate cable diagnostic test (if 	0	Reg. 42, bit 4
			enabled) has completed and the status information is valid for read.		
			=00, Normal condition		
14-13	Vct result	esult RO	=01, Open condition detected in cable	00	Reg 42, bit[6:5]
14-13	vci_iesuit	ΝŪ	=10, Short condition detected in cable	00	
			=11, Cable diagnostic test has failed		
12	Vct 10M Short	RO	=1, Less than 10 meter short	0	Reg. 42, bit 7
11-9	Reserved	RO	Reserved	000	
			Distance to the fault.		{(Reg. 42, bit 0),
8-0	Vct_fault_count	RO	It's approximately 0.4m*vct_fault_count[8:0]	{0, (0x00)}	(Reg. 43, bit[7:0])}

PHY1 Register 31 (PHYAD = 0x1, REGAD = 0x1F): PHY Special Control/Status

PHY2 Register 31 (PHYAD = 0x2,	REGAD = 0x1F): PHY Special Co	ontrol/Status
······································		

Bit	Name	R/W	Description	Default	Reference
15-6	Reserved	RO	Reserved	{(0x00),00}	
5	5 Polrvs		1 = polarity is reversed 0 = polarity is not reversed	0	Reg. 31, bit 5 Reg. 47, bit 5 Note: This bit is
					only valid for 10BT
4	MDI-X status	RO	1 = MDI 0 = MDI-X	0	Reg. 30, bit 7 Reg. 46, bit 7
3	Force_Ink	R/W	1 = Force link pass 0 = Normal Operation	0	Reg. 26, bit 3 Reg. 42, bit 3
2	Pwrsave	R/W	0 = Enable power saving 1 = Disable power saving	1	Reg. 26, bit 2 Reg. 42, bit 2
			1 = Perform Remote loopback, as follows:		
			Port 1 (reg. 26, bit 1 = '1')		
			Start: RXP1/RXM1 (port 1)		
			Loopback: PMD/PMA of port 1's PHY		
1	Remote	R/W	End: TXP1/TXM1 (port 1)	0	Reg. 26, bit 1
1	Loopback	R/VV	Port 2 (reg. 42, bit 1 = '1')	0	Reg. 42, bit 1
			Start: RXP2/RXM2 (port 2)		
			Loopback: PMD/PMA of port 2's PHY		
			End: TXP2/TXM2 (port 2)		
			0 = Normal Operation		
0	Reserved	R/W	Reserved Do not change the default value.	0	

January 27, 2014

Memory Map (8-Bit Registers)

Global Registers

Register (Decimal)	Register (Hex)	Description
0-1	0x00-0x01	Chip ID Registers
2-15	0x02-0x0F	Global Control Registers

Port Registers

Register (Decimal)	Register (Hex)	Description
16-29	0x10-0x1D	Port 1 Control Registers, including MII PHY Registers
30-31	0x1E-0x1F	Port 1 Status Registers, including MII PHY Registers
32-45	0x20-0x2D	Port 2 Control Registers, including MII PHY Registers
46-47	0x2E-0x2F	Port 2 Status Registers, including MII PHY Registers
48-57	0x30-0x39	Port 3 Control Registers
58-62	0x3A-0x3E	Reserved
63	0x3F	Port 3 Status Register
64-95	0x40-0x5F	Reserved

Advanced Control Registers

Register (Decimal)	Register (Hex)	Description
96-111	0x60-0x6F	TOS Priority Control Registers
112-117	0x70-0x75	Switch Engine's MAC Address Registers
118-120	0x76-0x78	User Defined Registers
121-122	0x79-0x7A	Indirect Access Control Registers
123-131	0x7B-0x83	Indirect Data Registers
142-153	0x8E-0x99	Station Address
154-165	0x9A-0xA5	Egress data rate limit
166	0xA6	Device mode indicator
167-170	0xA7-0xAA	High Priority Packet Buffer Reserved
171-174	0xAB-0xAE	PM Usage Flow Control Select Mode
175-186	0xAF-0xBA	TXQ Split
187-188	0xBB-0xBC	Link Change Interrupt register
189	0xBD	Force Pause Off Iteration Limit Enable
192	0xC0	Fiber Signal Threshold
194	0xC2	Insert SRC PVID
195	0xC3	Power Management and LED Mode
196	0xC4	Sleep Mode
198	0xC6	Forward Invalid VID Frame and Host Mode

Register Description

Global Registers (Registers 0 – 15)

Register 0 (0x00): Chip ID0

•	· / ·			
Bit	Name	R/W	Description	Default
7-0	Family ID	RO	Chip family	0x88

Register 1 (0x01): Chip ID1 / Start Switch

Bit	Name	R/W	Description	Default
7-4	Chip ID	RO	0x3 is assigned to M series. (73M)	0x3
3-1	Revision ID	RO	Revision ID	-
0	Start Switch	RW	=1, start the switch (default) 0=, stop the switch	1

Register 2 (0x02): Global Control 0

Bit	Name	R/W	Description	Default
7	New Back-off Enable	R/W	New back-off algorithm designed for UNH =1, Enable =0, Disable	0
6	Reserved	RO	Reserved	0
5	Flush Dynamic MAC Table	R/W	=1, enable flush dynamic MAC table for spanning tree application =disable	0
4	Flush Static MAC Table	R/W	=1, enable flush static MAC table for spanning tree application =disable,	0
3	Pass Flow Control Packet	R/W	= 1, switch will pass 802.1x "flow control" packets=0, switch will drop 802.1x "flow control" packets	0
2	Reserved	R/W	Reserved Do not change the default value.	0
1	Reserved	R/W	Reserved Do not change the default value.	0
0	Reserved	RO	Reserved	0

Register 3 (0x03): Global Control 1

Bit	Name	R/W	Description	Default
7	Pass All Frames	R/W	 = 1, switch all packets including bad ones. Used solely for debugging purposes. Works in conjunction with sniffer mode only. 	0
6	Port 3 Tail Tag Mode Enable	R/W	=1, Enable port 3 tail tag mode. =0, Disable.	0
5	IEEE 802.3x Transmit Direction Flow Control Enable	R/W	 = 1, will enable transmit direction flow control feature. = 0, will not enable transmit direction flow control feature. Switch will not generate any flow control (PAUSE) frame. 	1
4	IEEE 802.3x Receive Direction Flow Control Enable	R/W	 = 1, will enable receive direction flow control feature. = 0, will not enable receive direction flow control feature. Switch will not react to any flow control (PAUSE) frame it receives. 	1
3	Frame Length Field Check	R/W	 =1, will check frame length field in the IEEE packets. If the actual length does not match, the packet will be dropped (for Length/Type field < 1500). =0, not check 	0
2	Aging Enable	R/W	1 = enable age function in the chip0 = disable age function in the chip	1
1	Fast Age Enable	R/W	1 = turn on fast age (800us)	0
0	Aggressive Back-off Enable	R/W	1 = enable more aggressive back off algorithm in half duplex mode to enhance performance. This is not an IEEE standard.	0

Register 4 (0x04): Global Control 2

Bit	Name	R/W	Description	Default
7	Unicast Port-VLAN Mismatch Discard	R/W	This feature is used with port-VLAN (described in reg. 17, reg. 33,) = 1, all packets can not cross VLAN boundary = 0, unicast packets (excluding unkown/multicast/ broadcast) can cross VLAN boundary Note: Port mirroring is not supported if this bit is set to "0".	1
6	Multicast Storm Protection Disable	R/W	 = 1, "Broadcast Storm Protection" does not include multicast packets. Only DA = FF-FF-FF-FF-FF packets will be regulated. = 0, "Broadcast Storm Protection" includes DA = FF-FF-FF-FF-FF-FF-FF-FF-FF-FF-FF-FF-FF-	1
5	Back Pressure Mode	R/W	= 1, carrier sense based backpressure is selected= 0, collision based backpressure is selected	1
4	Flow Control and Back Pressure Fair Mode	R/W	 = 1, fair mode is selected. In this mode, if a flow control port and a non-flow control port talk to the same destination port, packets from the non-flow control port may be dropped. This is to prevent the flow control port from being flow controlled for an extended period of time. = 0, in this mode, if a flow control port and a non-flow control port talk to the same destination port, the flow control port will be flow controlled. This may not be "fair" to the flow control port. 	1
3	No Excessive Collision Drop	R/W	 = 1, the switch will not drop packets when 16 or more collisions occur. = 0, the switch will drop packets when 16 or more collisions occur. 	0

Register 4 (0x04): Global Control 2 (Continued)

Bit	Name	R/W	Description	Default
2	Huge Packet Support	R/W	= 1, will accept packet sizes up to 1916 bytes (inclusive). This bit setting will override setting from bit 1 of this register.	0
	•••••		= 0, the max packet size will be determined by bit 1 of this register.	
1	Legal Maximum Packet Size Check Enable	R/W	 = 0, will accept packet sizes up to 1536 bytes (inclusive). = 1, 1522 bytes for tagged packets, 1518 bytes for untagged packets. Any packets larger than the specified value will be dropped. 	0
0	Reserved	R/W	Reserved Do not change the default value.	0

Register 5 (0x05): Global Control 3

Bit	Name	R/W	Description	Default
7	802.1Q VLAN Enable	R/W	 = 1, 802.1Q VLAN mode is turned on. VLAN table needs to set up before the operation. = 0, 802.1Q VLAN is disabled. 	0
6	IGMP Snoop Enable on Switch MII Interface	R/W	 =1, IGMP snoop is enabled. All IGMP packets will be forwarded to the Switch MII port. =0, IGMP snoop is disabled. 	0
5	Reserved	RO	Reserved Do not change the default values.	0
4	Reserved	RO	Reserved Do not change the default values.	0
3	Weighted Fair Queue Enable	R/W	 = 0, Priority method set by the registers 175-186 bit [7]=0 for port 1, port 2 and port 3. = 1, Weighted Fair Queueing enabled. When all four queues have packets waiting to transmit, the bandwidth allocation is q3:q2:q1:q0 = 8:4:2:1. If any queues are empty, the highest non-empty queue gets one more weighting. For example, if q2 is empty, q3:q2:q1:q0 becomes (8+1):0:2:1. 	0
2	Reserved	RO	Reserved Do not change the default values.	0
1	Reserved	RO	Reserved Do not change the default values.	0
0	Sniff Mode Select	R/W	 = 1, will do RX AND TX sniff (both source port and destination port need to match) = 0, will do RX OR TX sniff (either source port or destination port needs to match). This is the mode used to implement RX only sniff. 	0

Register 6 (0x06): Global Control 4

Bit	Name	R/W	Description	Default
7	Reserved	RO	Reserved Do not change the default values.	0
6	Switch MII Half Duplex Mode	R/W	= 1, enable MII interface half-duplex mode.= 0, enable MII interface full-duplex mode.	0
5	Switch MII Flow Control Enable	R/W	= 1, enable full duplex flow control on Switch MII interface.= 0, disable full duplex flow control on Switch MII interface.	1
4	Switch MII 10BT	R/W	= 1, the switch interface is in 10Mbps mode= 0, the switch interface is in 100Mbps mode	0
3	Null VID Replacement	R/W	= 1, will replace NULL VID with port VID (12 bits)= 0, no replacement for NULL VID	0
2-0	Broadcast Storm Protection Rate ⁽¹⁾ Bit [10:8]	R/W	This register along with the next register determines how many "64 byte blocks" of packet data are allowed on an input port in a preset period. The period is 67ms for 100BT or 500ms for 10BT. The default is 1%.	000

Register 7 (0x07): Global Control 5

Bit	Name	R/W	Description	Default
7-0	Broadcast Storm Protection Rate ⁽¹⁾ Bit [7:0]	R/W	This register along with the previous register determines how many "64 byte blocks" of packet data are allowed on an input port in a preset period. The period is 67ms for 100BT or 500ms for 10BT. The default is 1%.	0x63

Note: (1) 100BT Rate: 148,800 frames/sec * 67 ms/interval * 1% = 99 frames/interval (approx.) = 0x63

Register 8 (0x08): Global Control 6

Bit	Name	R/W	Description	Default
7-0	Factory Testing	RO	Reserved Do not change the default values.	0x00

Register 9 (0x09): Global Control 7

Bit	Name	R/W	Description	Default
7-0	Factory Testing	RO	Reserved Do not change the default values.	0x24

Register 10 (0x0A): Global Control 8

Bit	Name	R/W	Description	Default
7-0	Factory Testing	RO	Reserved Do not change the default values.	0x35

Register 11 (0x0B): Global Control 9

Bit	Name	R/W	Description	Default
7-6		R/W	=00, 31.25MHz supports SPI speed below 6MHz =01, 62.5MHz supports SPI speed between 6MHz to 12.5MHz =10, 125MHz supports SPI speed above 12.5MHz	10
	Selection		Note: Lower clock speed will save more power consumption, It is better set to to 31.25MHz if SPI doesn't request a high speed.	00
5-4	Reserved	RO	N/A Don't change	00
3-2	Reserved	RO	N/A Don't change	10
1	Reserved	RO	N/A Don't change	0
0	Reserved	RO	N/A Don't change	0

Register 12 (0x0C): Global Control 10

Bit	Name	R/W	Description	Default
7-6	Tag_0x3	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x3.	01
5-4	Tag_0x2	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x2.	01
3-2	Tag_0x1	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x1.	00
1-0	Tag_0x0	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x0.	00

Register 13 (0x0D): Global Control 11

Bit	Name	R/W	Description	Default
7-6	Tag_0x7	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x7.	11
5-4	Tag_0x6	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x6.	11
3-2	Tag_0x5	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x5.	10
1-0	Tag_0x4	R/W	IEEE 802.1p mapping. The value in this field is used as the frame's priority when its IEEE 802.1p tag has a value of 0x4.	10

Register 14 (0x0E): Global Control 12

Bit	Name	R/W	Description	Default
7	Unknown Packet Default Port Enable	R/W	Send packets with unknown destination MAC addresses to specified port(s) in bits [2:0] of this register. 0 = disable 1 = enable	0
6	Drive Strength of I/O Pad	R/W	1: 16mA 0: 8mA	1
5	Reserved	RO	Reserved Do not change the default values.	0
4	Reserved	RO	Reserved Do not change the default values.	0
3	Reserved	RO	Reserved Do not change the default values.	0
2-0	Unknown Packet Default Port	R/W	Specify which port(s) to send packets with unknown destination MAC addresses. This feature is enabled by bit [7] of this register. Bit 2 stands for port 3. Bit 1 stands for port 2. Bit 0 stands for port 1. An '1' includes a port. An '0' excludes a port.	111

Register 15 (0x0F): Global Control 13

Bit	Name	R/W	Description	Default
7-3	PHY Address	R/W	00000 : N/A 00001 : Port 1 PHY address is 0x1 00010 : Port 1 PHY address is 0x2 11101 : Port 1 PHY address is 0x29 11110 : N/A 11111 : N/A	00001
			Note: Port 2 PHY address = (Port 1 PHY address) + 1	
2-0	Reserved	RO	Reserved Do not change the default values.	000

Port Registers (Registers 16 – 95)

The following registers are used to enable features that are assigned on a per port basis. The register bit assignments are the same for all ports, but the address for each port is different, as indicated.

Register 16 (0x10): Port 1 Control 0

Register 32 (0x20): Port 2 Control 0

Register 48 (0x30): Port 3 Control 0

Bit	Name	R/W	Description	Default
7	Broadcast Storm Protection Enable	R/W	 = 1, enable broadcast storm protection for ingress packets on port = 0, disable broadcast storm protection 	0
6	DiffServ Priority Classification Enable	R/W	 = 1, enable DiffServ priority classification for ingress packets (IPv4) on port = 0, disable DiffServ function 	0
5	802.1p Priority Classification Enable	R/W	= 1, enable 802.1p priority classification for ingress packets on port= 0, disable 802.1p	0
4-3	Port-based Priority Classification	R/W	 = 00, ingress packets on port will be classified as priority 0 queue if "Diffserv" or "802.1p" classification is not enabled or fails to classify. = 01, ingress packets on port will be classified as priority 1 queue if "Diffserv" or "802.1p" classification is not enabled or fails to classify. = 10, ingress packets on port will be classified as priority 2 queue if "Diffserv" or "802.1p" classification is not enabled or fails to classify. = 10, ingress packets on port will be classified as priority 2 queue if "Diffserv" or "802.1p" classification is not enabled or fails to classify. = 11, ingress packets on port will be classified as priority 3 queue if "Diffserv" or "802.1p" classification is not enabled or fails to classify. Note: "DiffServ", "802.1p" and port priority can be enabled at the same time. The OR'ed result of 802.1p and DSCP overwrites the port priority. 	00
2	Tag Insertion	R/W	 = 1, when packets are output on the port, the switch will add 802.1p/q tags to packets without 802.1p/q tags when received. The switch will not add tags to packets already tagged. The tag inserted is the ingress port's "port VID". = 0, disable tag insertion Note: For the tag insertion available, the register 194 bits [5:0] have to be set first. 	0
1	Tag Removal	R/W	 = 1, when packets are output on the port, the switch will remove 802.1p/q tags from packets with 802.1p/q tags when received. The switch will not modify packets received without tags. = 0, disable tag removal 	0
0	TXQ Split Enable	R/W	 = 1, split TXQ to 4 queue configuration. It cannot be enable at the same time with split 2 queue at register 18, 34,50 bit 7. = 0, no split, treated as 1 queue configuration 	0

Register 17 (0x11): Port 1 Control 1

Register 33 (0x21): Port 2 Control 1

Register 49 (0x31): Port 3 Control 1

Bit	Name	R/W	Description	Default	
7	Sniffer Port	R/W	= 1, Port is designated as sniffer port and will transmit packets that are monitored.	0	
			= 0, Port is a normal port		
6	Receive Sniff	R/W	= 1, All packets received on the port will be marked as "monitored packets" and forwarded to the designated "sniffer port"	0	
	Shill		= 0, no receive monitoring		
5	5 Transmit Sniff		R/W	= 1, All packets transmitted on the port will be marked as "monitored packets" and forwarded to the designated "sniffer port"	0
			= 0, no transmit monitoring		
4	4 Double Tag	R/W	= 1, All packets will be tagged with port default tag of ingress port regardless of the original packets are tagged or not	0	
			= 0, do not double tagged on all packets		
3	User Priority Ceiling	R/W	= 1, if the packet's "user priority field" is greater than the "user priority field" in the port default tag register, replace the packet's "user priority field" with the "user priority field" in the port default tag register.	0	
			= 0, do not compare and replace the packet's 'user priority field"		
2-0	Port VLAN	R/W	Define the port's egress port VLAN membership. The port can only communicate within the membership. Bit 2 stands for port 3, bit 1 stands for port 2, bit 0 stands for port 1.	111	
-	membership		An '1' includes a port in the membership.		
			An '0' excludes a port from membership.		

Register 18 (0x12): Port 1 Control 2

Register 34 (0x22): Port 2 Control 2

Register 50 (0x32): Port 3 Control 2

Bit	Name	R/W	Description	Default
7	Enable 2 Queue Split of Tx Queue	R/W	=1, Enable It cannot be enable at the same time with split 4 queue at register 16,32 and 48 bit 0.	0
6	Ingress VLAN Filtering	R/W	 =0, Disable = 1, the switch will discard packets whose VID port membership in VLAN table bits [18:16] does not include the ingress port. = 0, no ingress VLAN filtering. 	0
5	Discard non PVID Packets	R/W	 = 1, the switch will discard packets whose VID does not match ingress port default VID. = 0, no packets will be discarded 	0
4	Force Flow Control	R/W	 = 1, will always enable full duplex flow control on the port, regardless of AN result. = 0, full duplex flow control is enabled based on AN result. 	Pin value during reset: For port 1, SPIQ pin (defult is PD) For port 2, SMRXD30 pin For port 3, this bit has no meaning. Flow Control is set by Reg. 6, bit 5.

January 27, 2014

Register 18 (0x12): Port 1 Control 2

Register 34 (0x22): Port 2 Control 2

Register 50 (0x32): Port 3 Control 2 (Continued)

Bit	Name	R/W	Description	Default
3	Back Pressure Enable	R/W	= 1, enable port's half duplex back pressure= 0, disable port's half duplex back pressure	0
2	Transmit Enable	R/W	= 1, enable packet transmission on the port= 0, disable packet transmission on the port	1
1	Receive Enable	R/W	= 1, enable packet reception on the port= 0, disable packet reception on the port	1
0	Learning Disable	R/W	= 1, disable switch address learning capability= 0, enable switch address learning	0

Note: Bits [2:0] are used for spanning tree support.

Register 19 (0x13): Port 1 Control 3

Register 35 (0x23): Port 2 Control 3

Register 51 (0x33): Port 3 Control 3

Bit	Name	R/W	Description	Default
			Port's default tag, containing	
7-0	Default Tag	R/W	7-5 : User priority bits	0x00
7-0	[15:8]	R/W	4 : CFI bit	0x00
			3-0 : VID[11:8]	

Register 20 (0x14): Port 1 Control 4

Register 36 (0x24): Port 2 Control 4

Register 52 (0x34): Port 3 Control 4

Bit	Name	R/W	Description	Default
7-0	Default Tag	R/W	Port's default tag, containing	0x01
7-0	[7:0]	r/W	7-0 : VID[7:0]	UXUT

Note:

Registers 19 and 20 (and those corresponding to other ports) serve two purposes:

Associated with the ingress untagged packets, and used for egress tagging.

Default VID for the ingress untagged or null-VID-tagged packets, and used for address lookup.

Register 21 (0x15): Port 1 Control 5

Register 37 (0x25): Port 2 Control 5

Register 53 (0x35): Port 3 Control 5

Bit	Name	R/W	Description	Default
			1: Port 3 MII MAC mode	
			0: Port 3 MII PHY mode	
	Port 3 MII mode		Note:	
7	Selection	R/W	This bit should be set for port 1, Register 21 bit [7] = '1' for normal operation.	0
			This bit is reserved for port 2.	
	Self-address			
	filtering enable		=1, enable port 1 self-address filtering MACA1	
6	MACA1	R/W	=0, disable	0
	(not for 0x35)			
	Self-address			
	filtering enable		=1, enable port 2 Self-address filtering MACA2	
5	MACA2	R/W	=0, disable	0
	(not for 0x35)			
4	Drop Ingress	Tagged R/W	=1, Enable	0
4	Frame		=0, Disable	0
			Ingress Limit Mode	
			These bits determine what kinds of frames are limited and counted against ingress rate limiting.	
3-2	Limit Mode	R/W	= 00, limit and count all frames	00
5-2			= 01, limit and count Broadcast, Multicast, and flooded unicast frames	00
			= 10, limit and count Broadcast and Multicast frames only	
			= 11, limit and count Broadcast frames only	
			Count IFG bytes	
			= 1, each frame's minimum inter frame gap	
1	Count IFG	R/W	(IFG) bytes (12 per frame) are included in Ingress and Egress rate limiting calculations.	0
			= 0, IFG bytes are not counted.	
			Count Preamble bytes	
0	Count Pre	R/W	= 1, each frame's preamble bytes (8 per	0
0	Countrie	1.7.4.4	frame) are included in Ingress and Egress rate limiting calculations.	0
			= 0, preamble bytes are not counted.	

Register 22[6:0] (0x16): Port 1 Q0 ingress data rate limit

Register 38[6:0] (0x26): Port 2 Q0 ingress data rate limit

Register 54[6:0] (0x36): Port 3 Q0 ingress data rate limit

Bit	Name	R/W	Description	Default
7	RMII REFCLK INVERT.	R/W	 Port 3 inverted refclk selected Port 3 original refclk selected Note: Bit 7 is reserved for port 1 and port 2 	0 Note: Not Applied to Reg.22 and 38(Port 1, Port 2)
6-0	Q0 Ingress Data Rate limit	R/W	Ingress data rate limit for priority 0 frames Ingress traffic from this priority queue is shaped according to the ingress Data Rate Selected Table.	0

Register 23[6:0] (0x17): Port 1 Q1 ingress data rate limit

Register 39[6:0] (0x27): Port 2 Q1 ingress data rate limit

Register 55[6:0] (0x37): Port 3 Q1 ingress data rate limit

Bit	Name	R/W	Description	Default
7	Reserved	R/W	Reserved Do not change the default values.	0
6-0	Q1 Ingress data Rate limit	R/W	Ingress data rate limit for priority 1 frames Ingress traffic from this priority queue is shaped according to the ingress Data Rate Selected Table.	0

Register 24[6:0] (0x18): Port 1 Q2 ingress data rate limit

Register 40[6:0] (0x28): Port 2 Q2 ingress data rate limit

Register 56[6:0] (0x38): Port 3 Q2 ingress data rate limit

Bit	Name	R/W	Description	Default
7	Reserved	R/W	Reserved Do not change the default values.	0
6-0	Q2 Ingress Data Rate limit	R/W	Ingress data rate limit for priority 2 frames Ingress traffic from this priority queue is shaped according to ingress Data Rate Selection Table.	0

Register 25[6:0] (0x19): Port 1 Q3 ingress data rate limit

Register 41[6:0] (0x29): Port 2 Q3 ingress data rate limit

Register 57[6:0] (0x39): Port 3 Q3 ingress data rate limit

Bit	Name	R/W	Description	Default
7	Reserved	RO	Reserved Do not change the default values.	0
6-0	Q3 Ingress Data Rate limit	R/W	Ingress data rate limit for priority 3 frames Ingress traffic from this priority queue is shaped according to ingress Data Rate Selection Table.	0

Note: Most of the contents in registers 26-31 and registers 42-47 for ports 1 and 2, respectively, can also be accessed with the MIIM PHY registers.

	100BT	10BT		
	Register bit[6:0], Q=03	Register bit[6:0], Q=03		
Data Rate Limit	1 to 0x63 for the Rate	1 to 0x09 for the rate		
for ingress or egress	1Mbps to 99Mbps.	1Mbps to 9Mbps		
	0 or 0x64 for the rate	0 or 0x0A for the rate		
	100Mbps	10Mbps		
64 Kbps		0x65		
128 Kbps		0x66		
192 Kbps	0x67 0x68 0x69 0x6A 0x6B			
256 Kbps				
320 Kbps				
384 Kbps				
448 Kbps				
512 Kbps		0x6C		
576 Kbps		0x6D		
640 Kbps		0x6E		
704 Kbps		0x6F		
768 Kbps		0x70		
832 Kbps		0x71 0x72		
896 Kbps				
960 Kbps		0x73		

Table 14. Data Rate Limit Table

Register 26 (0x1A): Port 1 PHY Special Control/Status

Register 42 (0x2A): Port 2 PHY Special Control/Status

Register 58 (0x3A): Reserved, not applied to port 3

Bit	Name	R/W	Description	Default	
7	Vct 10M Short	RO	=1, Less than 10 meter short	0	
			=00, Normal condition	00	
0.5			=01, Open condition detected in cable		
6-5	Vct_result	RO	=10, Short condition detected in cable	00	
			=11, Cable diagnostic test has failed		
4	Vot on	R/W	=1, Enable cable diagnostic test. After VCT test has completed, this bit will be self-cleared.	0	
4	Vct_en	(SC)	=0, Indicate cable diagnostic test (if enabled) has completed and the status information is valid for read.	0	
3		R/W	=1, Force link pass		
3	Force_Ink	K/VV	=0, Normal Operation	0	
2	Reserved	RO	Reserved	0	
_			Do not change the default value.	0	
			=1, Perform Remote loopback, as follows:		
			Port 1 (reg. 26, bit 1 = '1')		
			Start: RXP1/RXM1 (port 1)		
			Loopback: PMD/PMA of port 1's PHY	0	
1	Remote Loopback	R/W	End: TXP1/TXM1 (port 1)		
I	Remote Loopback	r///	Port 2 (reg. 42, bit 1 = '1')		
			Start: RXP2/RXM2 (port 2)		
			Loopback: PMD/PMA of port 2's PHY		
			End: TXP2/TXM2 (port 2)		
			=0, Normal Operation		
			Bit[8] of VCT fault count		
0	Vct_fault_count[8]	RO	Distance to the fault.	0	
			It's approximately 0.4m*vct_fault_count[8:0]		

Register 27 (0x1B): Port 1 Not support

Register 43 (0x2B): Port 2 LinkMD Result

Register 59 (0x3B): Reserved, not applied to port 3

Bit	Name	R/W	Description	Default
			Bits[7:0] of VCT fault count	
7-0	Vct_fault_count[7: 0]	RO	Distance to the fault.	0x00
	0]		It's approximately 0.4m*Vct_fault_count[8:0]	

Register 28 (0x1C): Port 1 Control 12

Register 44 (0x2C): Port 2 Control 12

Register 60 (0x3C): Reserved, not applied to port 3

Bit	Name	R/W	Description	Default
7	Auto Negotiation Enable	R/W	 = 1, auto negotiation is on = 0, disable auto negotiation; speed and duplex are determined by bits 6 and 5 of this register. 	1 For port 1, P1LED0 pin value during reset.(default is PD) For port 2, SMRXD33 pin value during reset
6	Force Speed	R/W	= 1, forced 100BT if AN is disabled (bit 7) = 0, forced 10BT if AN is disabled (bit 7)	1 For port 1, P1LED1 pin value during reset. For port 2, SMRXD32 pin value during reset.
5	Force Duplex	R/W	 = 1, forced full duplex if (1) AN is disabled or (2) AN is enabled but failed. = 0, forced half duplex if (1) AN is disabled or (2) AN is enabled but failed. Note: This bit or strap pin should be set to '0' for the correct duplex mode indication of LED and register status when the link-up is AN to force mode. 	1 For port 1, SMRXDV3 pin value during reset. For port 2, SMRXD31 pin value during reset.
4	Advertise Flow Control capability	R/W	 = 1, advertise flow control (pause) capability = 0, suppress flow control (pause) capability from transmission to link partner 	1
3	Advertise 100BT Full Duplex Capability	R/W	 = 1, advertise 100BT full duplex capability = 0, suppress 100BT full duplex capability from transmission to link partner 	1
2	Advertise 100BT Half Duplex Capability	R/W	 = 1, advertise 100BT half duplex capability = 0, suppress 100BT half duplex capability from transmission to link partner 	1
1	Advertise 10BT Full Duplex Capability	R/W	 = 1, advertise 10BT full duplex capability = 0, suppress 10BT full duplex capability from transmission to link partner 	1
0	Advertise 10BT Half Duplex Capability	R/W	 = 1, advertise 10BT half duplex capability = 0, suppress 10BT half duplex capability from transmission to link partner 	1

Register 29 (0x1D): Port 1 Control 13

Register 45 (0x2D): Port 2 Control 13

Register 61 (0x3D): Reserved, not applied to port 3

Bit	Name	R/W	Description	Default
7	LED Off	R/W	= 1, turn off all port's LEDs (LEDx_1, LEDx_0, where "x" is the port number). These pins will be driven high if this bit is set to one.	0
			= 0, normal operation	
			= 1, disable the port's transmitter	
6	Txdis	R/W	= 0, normal operation	0
5	Restart AN	R/W	= 1, restart auto-negotiation	0
			= 0, normal operation	
4	Disable Far-	R/W	= 1, disable far-end fault detection and pattern transmission.	0
	end Fault		= 0, enable far-end fault detection and pattern transmission	
3	Power Down	R/W	= 1, power down	0
			= 0, normal operation	
2	Disable Auto	R/W	= 1, disable auto MDI/MDI-X function	0
	MDI/MDI-X		= 0, enable auto MDI/MDI-X function	
			If auto MDI/MDI-X is disabled,	0
1	Force MDI	R/W	= 1, force PHY into MDI mode (transmit on RXP/RXM pins)	0
			= 0, force PHY into MDI-X mode (transmit on TXP/TXM pins)	
			= 1, perform loopback, as indicated:	
			Port 1 Loopback (reg. 29, bit 0 = '1')	
			Start: RXP2/RXM2 (port 2)	
			Loopback: PMD/PMA of port 1's PHY	
0	Loopback	R/W	End: TXP2/TXM2 (port 2)	0
0	Loopback	1.7,4,4	Port 2 Loopback (reg. 45, bit 0 = '1')	v
			Start: RXP1/RXM1 (port 1)	
			Loopback: PMD/PMA of port 2's PHY	
			End: TXP1/TXM1 (port 1)	
			= 0, normal operation	

Register 30 (0x1E): Port 1 Status 0

Register 46 (0x2E): Port 2 Status 0

Register 62 (0x3E): Reserved, not applied to port 3

Bit	Name	R/W	Description	Default
7	MDI-X Status	RO	= 1, MDI = 0, MDI-X	0
6	AN Done	RO	= 1, auto-negotiation completed= 0, auto-negotiation not completed	0
5	Link Good	RO	= 1, link good = 0, link not good	0
4	Partner Flow Control Capability	RO	= 1, link partner flow control (pause) capable= 0, link partner not flow control (pause) capable	0
3	Partner 100BT Full Duplex Capability	RO	= 1, link partner 100BT full duplex capable= 0, link partner not 100BT full duplex capable	0
2	Partner 100BT Half Duplex Capability	RO	= 1, link partner 100BT half duplex capable= 0, link partner not 100BT half duplex capable	0
1	Partner 10BT Full Duplex Capability	RO	= 1, link partner 10BT full duplex capable= 0, link partner not 10BT full duplex capable	0
0	Partner 10BT Half Duplex Capability	RO	= 1, link partner 10BT half duplex capable= 0, link partner not 10BT half duplex capable	0

Register 31 (0x1F): Port 1 Status 1

Register 47 (0x2F): Port 2 Status 1

Register 63 (0x3F): Port 3 Status 1

Bit	Name	R/W	Description	Default
7	Hp_mdix	R/W	1 = HP Auto MDI/MDI-X mode 0 = Micrel Auto MDI/MDI-X mode	1 Note: Only ports 1 and 2 are PHY ports. This bit is not applicable to port 3 (MII).
6	Reserved	RO	Reserved Do not change the default value.	0
5	Polrvs	RO	1 = polarity is reversed0 = polarity is not reversed	0 Note: This bit is not applicable to port 3 (MII). This bit is only valid for 10BT
4	Transmit Flow Control Enable	RO	1 = transmit flow control feature is active0 = transmit flow control feature is inactive	0
3	Receive Flow Control Enable	RO	1 = receive flow control feature is active0 = receive flow control feature is inactive	0
2	Operation Speed	RO	1 = link speed is 100Mbps 0 = link speed is 10Mbps	0

January 27, 2014

Register 31 (0x1F): Port 1 Status 1

Register 47 (0x2F): Port 2 Status 1

Register 63 (0x3F): Port 3 Status 1 (Continued)

Bit	Name	R/W	Description	Default
1	Operation	RO	1 = link duplex is full	0
1	Duplex	ĸŪ	0 = link duplex is half	0
0	For and Foult		= 1, Far-end fault status detected	0
0	Far-end Fault	RO	= 0, no Far-end fault status detected	This bit is applicable to port 1 only.

Register 67 (0x43): Reset

Bit	Name	R/W	Description	Default
			=1, Software reset	
	Software		=0, Clear	
4	Reset	R/W	Note: Software reset will reset all registers to the initial values of the power-on reset or warm reset (keep the strap values).	0
			=1, PCS reset is used when is doing software reset for a compelete reset	
0	PCS Reset	R/W	=0, Clear	0
			Note: PCS reset will reset the state machine and clock domain in PHY's PCS layer.	

Advanced Control Registers (Registers 96-198)

The IPv4/IPv6 TOS Priority Control Registers implement a fully decoded, 128-bit DSCP (Differentiated Services Code Point) register set that is used to determine priority from the ToS (Type of Service) field in the IP header. The most significant 6 bits of the TOS field are fully decoded into 64 possibilities, and the singular code that results is compared against the corresponding bits in the DSCP register to determine the priority.

Register 96 (0x60):	TOS Priority	Control Register 0
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Bit	Name	R/W	Description	Default
7-6	DSCP[7:6]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x03.	00
5-4	DSCP[5:4]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x02.	00
3-2	DSCP[3:2]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x01.	00
1-0	DSCP[1:0]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x00.	00

Register 97 (0x61): TOS Priority Control Register 1

Bit	Name	R/W	Description	Default
7-6	DSCP[15:14]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x07.	00
5-4	DSCP[13:12]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x06.	00
3-2	DSCP[11:10]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x05.	00
1-0	DSCP[9:8]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x04.	00

Register 98 (0x62): TOS Priority Control Register 2

Bit	Name	R/W	Description	Default
7-6	DSCP[23:22]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x0B.	00
5-4	DSCP[21:20]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x0A.	00
3-2	DSCP[19:18]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x09.	00
1-0	DSCP[17:16]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x08.	00

Register 99 (0x63): TOS Priority Control Register 3

Bit	Name	R/W	Description	Default
7-6	DSCP[31:30]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x0F.	00
5-4	DSCP[29:28]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x0E.	00
3-2	DSCP[27:26]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x0D.	00
1-0	DSCP[25:24]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x0C.	00

Register 100 (0x64): TOS Priority Control Register 4

Bit	Name	R/W	Description	Default
7-6	DSCP[39:38]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x13.	00
5-4	DSCP[37:36]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x12.	00
3-2	DSCP[35:34]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x11.	00
1-0	DSCP[33:32]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x10.	00

Register 101 (0x65): TOS Priority Control Register 5

Bit	Name	R/W	Description	Default
7-6	DSCP[47:46]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x17.	00
5-4	DSCP[45:44]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x16.	00
3-2	DSCP[43:42]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x15.	00
1-0	DSCP[41:40]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x14.	00

Register 102 (0x66): TOS Priority Control Register 6

Bit	Name	R/W	Description	Default
7-6	DSCP[55:54]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x1B.	00
5-4	DSCP[53:52]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x1A.	00
3-2	DSCP[51:50]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x19.	00
1-0	DSCP[49:48]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x18.	00

Register 103 (0x67): TOS Priority Control Register 7

Bit	Name	R/W	Description	Default
7-6	DSCP[63:62]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x1F.	00
5-4	DSCP[61:60]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x1E.	00
3-2	DSCP[59:58]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x1D.	00
1-0	DSCP[57:56]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x1C.	00

Register 104 (0x68): TOS Priority Control Register 8

Bit	Name	R/W	Description	Default
7-6	DSCP[71:70]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x23.	00
5-4	DSCP[69:68]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x22.	00
3-2	DSCP[67:66]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x21.	00
1-0	DSCP[65:64]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x20.	00

Register 105 (0x69): TOS Priority Control Register 9

Bit	Name	R/W	Description	Default
7-6	DSCP[79:78]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x27.	00
5-4	DSCP[77:76]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x26.	00
3-2	DSCP[75:74]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x25.	00
1-0	DSCP[73:72]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x24.	00

Register 106 (0x6A): TOS Priority Control Register 10

Bit	Name	R/W	Description	Default
7-6	DSCP[87:86]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x2B.	00
5-4	DSCP[85:84]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x2A.	00
3-2	DSCP[83:82]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x29.	00
1-0	DSCP[81:80]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x28.	00

Register 107 (0x6B): TOS Priority Control Register 11

Bit	Name	R/W	Description	Default
7-6	DSCP[95:94]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x2F.	00
5-4	DSCP[93:92]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x2E.	00
3-2	DSCP[91:90]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x2D.	00
1-0	DSCP[89:88]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x2C.	00

Register 108 (0x6C): TOS Priority Control Register 12

Bit	Name	R/W	Description	Default
7-6	DSCP[103:102]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x33.	00
5-4	DSCP[101:100]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x32.	00
3-2	DSCP[99:98]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x31.	00
1-0	DSCP[97:96]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x30.	00

Register 109 (0x6D): TOS Priority Control Register 13

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Bit	Name	R/W	Description	Default
7-6	DSCP[111:110]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x37.	00
5-4	DSCP[109:108]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x36.	00
3-2	DSCP[107:106]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x35.	00
1-0	DSCP[105:104]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x34.	00

Register 110 (0x6E): TOS Priority Control Register 14

Bit	Name	R/W	Description	Default
7-6	DSCP[119:118]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x3B.	00
5-4	DSCP[117:116]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x3A.	00
3-2	DSCP[115:114]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x39.	00
1-0	DSCP[113:112]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x38.	00

Register 111 (0.	x6F): TOS Priority	Control Register 15
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Bit	Name	R/W	Description	Default
7-6	DSCP[127:126]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x3F.	00
5-4	DSCP[125:124]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x3E.	00
3-2	DSCP[123:122]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x3D.	00
1-0	DSCP[121:120]	R/W	The value in this field is used as the frame's priority when bits [7:2] of the frame's IP TOS/DiffServ/Traffic Class value is 0x3C.	00

Registers 112 to 117

Registers 112 to 117 contain the switch engine's MAC address. This 48-bit address is used as the Source Address for the MAC's full duplex flow control (PAUSE) frame.

Register 112 (0x70): MAC Address Register 0

Bit	Name	R/W	Description	Default
7-0	MACA[47:40]	R/W		0x00

Register 113 (0x71): MAC Address Register 1

Bit	Name	R/W	Description	Default
7-0	MACA[39:32]	R/W		0x10

Register 114 (0x72): MAC Address Register 2

Bit	Name	R/W	Description	Default
7-0	MACA[31:24]	R/W		0xA1

Register 115 (0x73): MAC Address Register 3

Bit	Name	R/W	Description	Default
7-0	MACA[23:16]	R/W		0xFF

Register 116 (0x74): MAC Address Register 4

Bit	Name	R/W	Description	Default
7-0	MACA[15:8]	R/W		0xFF

Register 117 (0x75): MAC Address Register 5

	Bit	Name	R/W	Description	Default
ſ	7-0	MACA[7:0]	R/W		0xFF

Registers 118 to 120

Registers 118 to 120 are User Defined Registers (UDRs). These are general purpose read/write registers that can be used to pass user defined control and status information between the KSZ8863 and the external processor.

Register 118 (0x76): User Defined Register 1

Bit	Name	R/W	Description	Default	
7-0	UDR1	R/W		0x00	
Participant 440 (Av77): User Defined Derivier 2					

Register 119 (0x77): User Defined Register 2

ſ	Bit	Name	R/W	Description	Default
	7-0	UDR2	R/W		0x00

Register 120 (0x78): User Defined Register 3

Bit	Name	R/W	Description	Default
7-0	UDR3	R/W		0x00

Registers 121 to 131

Registers 121 to 131 provide read and write access to the static MAC address table, VLAN table, dynamic MAC address table, and MIB counters.

Register 121 (0x79): Indirect Access Control 0

Bit	Name	R/W	Description	Default	
7-5	Reserved	R/W	Reserved	000	
7-5	Reserved		Do not change the default values.	000	
4	Read High /	R/W	= 1, read cycle	0	
4	Write Low		= 0, write cycle	0	
	3-2 Table Select R/W		00 = static MAC address table selected		
3-2		chia Calaat DAV	01 = VLAN table selected	00	
5-2				10 = dynamic MAC address table selected	00
			11 = MIB counter selected		
1-0	Indirect Address High	R/W	Bits [9:8] of indirect address	00	

Register 122 (0x7A): Indirect Access Control 1

Bit	Name	R/W	Description	Default
7-0	Indirect Address Low	R/W	Bits [7:0] of indirect address	0000_0000

Note: A write to register 122 triggers the read/write command. Read or write access is determined by register 121 bit 4.

Register 123 (0x7B): Indirect Data Register 8

Bit	Name	R/W	Description	Default
7	CPU Read Status	RO	 This bit is applicable only for dynamic MAC address table and MIB counter reads. = 1, read is still in progress = 0, read has completed 	0
6-3	Reserved	RO	Reserved	0000
2-0	Indirect Data [66:64]	RO	Bits [66:64] of indirect data	000

January 27, 2014

Register 124 (0x7C): Indirect Data Register 7

Bit	Name	R/W	Description	Default
7-0	Indirect Data [63:56]	R/W	Bits [63:56] of indirect data	0000_0000

Register 125 (0x7D): Indirect Data Register 6

Bit	Name	R/W	Description	Default
7-0	Indirect Data [55:48]	R/W	Bits [55:48] of indirect data	0000_0000

Register 126 (0x7E): Indirect Data Register 5

Bit	Name	R/W	Description	Default
7-0	Indirect Data [47:40]	R/W	Bits [47:40] of indirect data	0000_0000

Register 127 (0x7F): Indirect Data Register 4

Bit	Name	R/W	Description	Default
7-0	Indirect Data [39:32]	R/W	Bits [39:32] of indirect data	0000_0000

Register 128 (0x80): Indirect Data Register 3

Bit	Name	R/W	Description	Default
7-0	Indirect Data [31:24]	R/W	Bits [31:24] of indirect data	0000_0000

Register 129 (0x81): Indirect Data Register 2

Bit	Name	R/W	Description	Default
7-0	Indirect Data [23:16]	R/W	Bits [23:16] of indirect data	0000_0000

Register 130 (0x82): Indirect Data Register 1

Bit	Name	R/W	Description	Default
7-0	Indirect Data [15:8]	R/W	Bits [15:8] of indirect data	0000_0000

Register 131 (0x83): Indirect Data Register 0

Bit	Name	R/W	Description	Default
7-0	Indirect Data [7:0]	R/W	Bits [7:0] of indirect data	0000_0000

Register 147~142(0x93~0x8E): Station Address 1 MACA1

Register 153~148 (0x99~0x94): Station Address 2 MACA2

Bit	Name	R/W	Description	Default
47-0	Station address	R/W	48-bit Station address MACA1 and MACA2. Note: The station address is used for self MAC address filtering, see the port register control 5 bits [6,5] for detail.	48'h0 Note: the MSB bits[47-40] of the MAC is the register 147 and 153. The LSB bits[7-0] of MAC is the register 142 and 148.

Register 154[6:0] (0x9A): Port 1 Q0 Egress data rate limit

Register 158[6:0] (0x9E): Port 2 Q0 Egress data rate limit

Register 162[6:0] (0xA2): Port 3 Q0 Egress data rate limit

Bit	Name	R/W	Description	Default
7	Egress Rate Limit Flow Control Enable	R/W	1: enable egress rate limit flow control. 0: disable	0
6-0	Q0 Egress Data Rate limit	R/W	Egress data rate limit for priority 0 frames Egress traffic from this priority queue is shaped according to the Data Rate Limit Selected Table.	0

Register 155[6:0] (0x9B): Port 1 Q1 Egress data rate limit

Register 159[6:0] (0x9F): Port 2 Q1 Egress data rate limit

Register 163[6:0] (0xA3): Port 3 Q1 Egress data rate limit

Bit	Name	R/W	Description	Default
7	Reserved	R/W	Reserved Do not change the default values.	0
6-0	Q1 Egress data Rate limit	R/W	Egress data rate limit for priority 1 frames Egress traffic from this priority queue is shaped according to the Data Rate Limit Selected Table.	0

Register 156[6:0] (0x9C): Port 1 Q2 Egress data rate limit

Register 160[6:0] (0xA0): Port 2 Q2 Egress data rate limit

Register 164[6:0] (0xA4): Port 3 Q2 Egress data rate limit

Bit	Name	R/W	Description	Default
7	Reserved	R/W	Reserved Do not change the default values.	0
6-0	Q2 Egress Data Rate limit	R/W	Egress data rate limit for priority 2 frames Egress traffic from this priority queue is shaped according to the Data Rate Limit Selected Table.	0

Register 157[6:0] (0x9D): Port 1 Q3 Egress data rate limit

Register 161[6:0] (0xA1): Port 2 Q3 Egress data rate limit

Register 165[6:0] (0xA5): Port 3 Q3 Egress data rate limit

Bit	Name	R/W	Description	Default
7	Reserved	R/W	Reserved Do not change the default values.	0
6-0	Q3 Egress Data Rate limit	R/W	Egress data rate limit for priority 3 frames Egress traffic from this priority queue is shaped according to the Data Rate Limit Selected Table.	0

Register 166 (0xA6): KSZ8863 mode indicator

Name	RO	Description		Default
KSZ8863 Mode Indicator	RO	bit7: 1: Reserved bit6: 1: 48P pkg of 2 PH bit5: 1: Reserved bit4: 1: Port 3 RMII bit3: 1: Reserved bit2: 1: Port 3 MAC MII bit1: 1: Port 1 Copper	0: Reserved 0: Port 3 MII 0: Reserved 0: Port 3 PHY MII 0: Port 1 Fiber	0x43 MLL 0x53 RLL 0x41 FLL
	KSZ8863	KSZ8863 BO	KSZ8863 Mode Indicator RO RO Bit7: 1: Reserved bit6: 1: 48P pkg of 2 PH bit5: 1: Reserved bit4: 1: Port 3 RMII bit3: 1: Reserved bit2: 1: Port 3 MAC MII	KSZ8863 Mode IndicatorRObit7: 1: Reserved bit6: 1: 48P pkg of 2 PHY mode bit5: 1: Reserved0: Reserved bit7: 1: Port 3 RMIIKSZ8863 Mode IndicatorRObit4: 1: Port 3 RMII0: Port 3 MII bit3: 1: Reserved0: Reserved bit2: 1: Port 3 RMIIbit4: 1: Port 3 RMII bit1: 1: Port 1 Copper0: Port 3 PHY MII bit1: 1: Port 1 Copper0: Port 1 Fiber

Register 167 (0xA7): High Priority Packet Buffer Reserved for Q3

Bit	Name	RW	Description	Default
7-0	Reserved	RO	Reserved	0x45
			Do not change the default values.	

Register 168 (0xA8): High Priority Packet Buffer Reserved for Q2

Bit	Name	RW	Description	Default
7-0	Reserved	RO	Reserved Do not change the default values.	0x35

Register 169 (0xA9): High Priority Packet Buffer Reserved for Q1

Bit	Name	RW	Description	Default
7-0	Reserved	RO	Reserved Do not change the default values.	0x25

Register 170 (0xAA): High Priority Packet Buffer Reserved for Q0

Bit	Name	RW	Description	Default
7-0 Reser	Reserved	RO	Reserved	0x15
7-0	Reserved	κυ	Do not change the default values.	0215

Register 171 (0xAB): PM Usage Flow Control Select Mode 1

Bit	Name	R/W	Description	Default
7 Reserved	RO	Reserved	0	
1	Reserved	RU	Do not change the default values.	0
6	Reserved	RO	Reserved	1
0	Reserved	RU	Do not change the default values.	I
5-0	Reserved	RO	Reserved	0x18
5-0	Reserved	RU	Do not change the default values.	0210

Register 172 (0xAC): PM Usage Flow Control Select Mode 2

Bit	Name	R/W	Description	Default
7-6	Reserved	RO	Reserved	0
10	Received	NO	Do not change the default values.	5
5-0	Record	RO	Reserved	0×10
5-0	Reserved	κU	Do not change the default values.	0x10

Register 173 (0xAD): PM Usage Flow Control Select Mode 3

Bit	Name	R/W	Description	Default
7-6	Reserved	RO	Reserved	00
7-0 Reserved	i i i i i i i i i i i i i i i i i i i	Do not change the default values.	00	
5-0	Decerved	RO	Reserved	0x08
5-0	Reserved	RU	Do not change the default values.	0x08

Register 174 (0xAE): PM Usage Flow Control Select Mode 4

Bit	Name	R/W	Description	Default	
7-4	Reserved	RO	Reserved	0	
7-4 Reserved	RO I	Do not change the default values.	0		
2.0	Record	RO	Reserved	0,05	
3-0 Reserved	Reserved	RU	Do not change the default values.	0x05	

Register 175 (0xAF): TXQ Split for Q3 in Port 1

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 176/177/178 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 176/177/178 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	8

Register 176 (0xB0): TXQ Split for Q2 in Port 1

Bit	Name	R/W	Description	Default
7	Driggity Salact	DAA	0 = enable straight priority with Reg 175/177/178 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first	4
	Priority Select	R/W	1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 175/177/178 bits[7]=1.	I
6:0	Deserved	DO	Reserved	4
6:0	Reserved	RO	Do not change the default values.	4

Register 177 (0xB1): TXQ Split for Q1 in Port 1

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 175/176/178 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first	1
	Filonity Select	Γ./ V V	1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 175/176/178 bits[7]=1.	
6:0	Reserved	RO	Reserved	2
0.0	Reserved	RU	Do not change the default values.	2

Register 178 (0xB2): TXQ Split for Q0 in Port 1

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 175/176/177 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 175/176/177 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	1

January 27, 2014

Register 179 (0xB3): TXQ Split for Q3 in Port 2

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 180/181/182 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 180/181/182 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	8

Register 180 (0xB4): TXQ Split for Q2 in Port 2

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 179/181/182 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 179/181/182 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	4

Register 181 (0xB5): TXQ Split for Q1 in Port 2

Bit	Name	R/W	Description	Default
7	Driority Soloct	R/W	0 = enable straight priority with Reg 179/180/182 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first	1
	7 Priority Select	Γ./ V V	1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 179/180/182 bits[7]=1.	
6:0	Reserved	RO	Reserved	2
0.0	Reserved	ΝŪ	Do not change the default values.	2

Register 182 (0xB6): TXQ Split for Q0 in Port 2

Bit	Name	R/W	Description	Default
7		R/W	0 = enable straight priority with Reg 179/180/181 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first	1
	Priority Select	K / V V	1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 179/180/181 bits[7]=1.	
6.0	Record	PO	Reserved	1
0.0	6:0 Reserved	RO	Do not change the default values.	I

Register 183 (0xB7): TXQ Split for Q3 Port 3

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 184/185/186 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 184/185/186 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	8

Register 184 (0xB8): TXQ Split for Q2 Port 3

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 183/185/186 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 183/185/186 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	4

Register 185 (0xB9): TXQ Split for Q1 in Port 3

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 183/184/186 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues with Reg 183/184/186 bits[7]=1.	1
6:0	Reserved	RO	Reserved Do not change the default values.	2

Register 186 (0xBA): TXQ Split for Q0 in Port 3

Bit	Name	R/W	Description	Default
7	Priority Select	R/W	0 = enable straight priority with Reg 183/184/185 bits[7]=0 and Reg 5 bit[3]=0 for higher priority first 1= priority ratio is 8:4:2:1 for 4 queues and 2:1 for 2 queues	1
			with Reg 183/184/185 bits[7]=1.	
6:0) Reserved		Reserved	1
0.0	Reserved	κυ	Do not change the default values.	I

Register 187 (0xBB): Interrupt enable register

Bit	Name	R/W	Description	Default
7-0	Interrupt Enable Register	R/W	Interrupt enable register corresponding to bits in Register 188 Note: Set register 187 first and then set register 188 (W1C= Write '1' Clear) to wait the interrupt at pin 35 INTRN for the link to be changed.	0x00

Register 188 (0xBC): Link Change Interrupt

Bit	Name	R/W	Description	Default
7	P1 or P2 Link Change (LC) Interrupt	R/W	Set to 1 when P1 or P2 link changes in analog interface (W1C).	0
6-3	Reserved	R/W	Reserved Do not change the default values.	0
2	P3 Link Change (LC) Interrupt	R/W	Set to 1 when P3 link changes in MII interface (W1C).	0
1	P2 Link Change (LC) Interrupt	R/W	Set to 1 when P2 link changes in analog interface (W1C).	0
0	P1 MII Link Change (LC) Interrupt	R/W	Set to 1 when P1 link changes in analog interface or MII interface (W1C).	0

Register 189 (0xBD): Force Pause Off Iteration Limit Enable

Bit	Name	R/W	Description	Default
7-0	Force Pause Off Iteration Limit Enable	R/W	=1, Enable, It is 160ms before requesting to invalidate flow control.=0, Disable	0

Register 192 (0xC0): Fiber Signal Threshold

Bit	Name	R/W	Description	Default
7	Port 2 Fiber Signal Threshold	R/W	=1, Threshold is 2.0V =0, Threshold is 1.2V	0
6	Port 1 Fiber Signal Threshold	R/W	=1, Threshold is 2.0V =0, Threshold is 1.2V	0
5-0	Reserved	RO	Reserved Do not change the default value.	0

Register 193 (0xC1): Internal 1.8V LDO Control

Bit	Name	R/W	Description	Default
7	Reserved	RO	Reserved Do not change the default value.	0
6	Internal 1.8V LDO Disable	R/W	=1, Disable internal 1.8V LDO =0, Enable internal 1.8V LDO	0
5-0	Reserved	RO	Reserved Do not change the default value.	0

Register 194 (0xC2): Insert SRC PVID

Bit	Name	R/W	Description	Default
7-6	Reserved	RO	Reserved Do not change the default value.	00
5	Insert SRC port 1 PVID at Port 2	R/W	1= insert SRC port 1 PVID for untagged frame at egress port 2	0
4	Insert SRC port 1 PVID at Port 3	R/W	1= insert SRC port 1 PVID for untagged frame at egress port 3	0
3	Insert SRC port 2 PVID at Port 1	R/W	1= insert SRC port 2 PVID for untagged frame at egress port 1	0
2	Insert SRC port 2 PVID at Port 3	R/W	1= insert SRC port 2 PVID for untagged frame at egress port 3	0
1	Insert SRC port 3 PVID at Port 1	R/W	1= insert SRC port 3 PVID for untagged frame at egress port 1	0
0	Insert SRC port 3 PVID at Port 2	R/W	1= insert SRC port 3 PVID for untagged frame at egress port 2	0

January 27, 2014

Register 195 (0xC3): Power Management and LED Mode

Bit	Name	R/W	Description	Default	
			CPU interface clock tree power down enable.		
	CPU interface		1: Enable		
7	Power Down	R/W	0: Disable	0	
			Note: Power save a little bit when MII interface is used and the traffic is stopped in the power management with normal mode		
			Switch clock tree power down enable.		
	Switch Power		1: Enable		
6	Down	R/W	0:Disable	0	
			Note: Power save a little bit when MII interface is used and the traffic is stopped in the power management with normal mode		
			00: LED0 -> Link/ACT, LED1-> Speed		
5-4	LED Mode Selection	R/W	01: LED0 -> Link, LED1 -> ACT	00	
5-4			10: LED0 -> Link/ACT, LED1 -> Duplex	00	
			11: LED0 -> Link, LED1 -> Duplex		
3	LED output mode	R/W	 =1, the internal stretched energy signal from the analog module will be negated and output to LED1 and the internal device ready signal will be negated and output to LED0. =0, the LED1/LED0 pins will indicate the regular LED outputs. (Note. This is for debugging purpose.) 	0	
			=1, PLL power down enable		
			=0, disable		
2	PLL Off Enable	R/W	Note: This bit is used in Energy Detect mode with pin 27 MII_LINK_3 pull-up in the by-pass mode for saving power	0	
1-0	Power Management Mode	R/W	Power management mode 00: Normal Mode 01: Energy Detection Mode 10: Software Power Down Mode 11: Power Saving Mode	00	

Register 196(0xC4): Sleep Mode

Bit	Name	R/W	Description	Default
7-0	Sleep Mode	R/W	This value is used to control the minimum period the no energy event has to be detected consecutively before the device enters the low power state when the ED mode is on. The unit is 20 ms. The default go_sleep time is 1.6 seconds.	0x50

Bit	Name	R/W	Description	Default	
7	Reserved	RO	Reserved	2	
	Reserved	ĸŬ	Do not change the default value.	0	
6-4	Forward Invid VID Frame	R/W	Forwarding ports for frame with invalid VID	3b'0	
3	P3 RMII Clock	R/W	1: Internal	0	
5	Selection	ction	0: External	0	
2	P1 RMII Clock		1: Internal	0	
2	2 Selection		0: External		
			00: I2C master mode		
1-0	Host Interface	R/W	01: I2C slave mode	Strapped value of P2LED1, P2LED0.	
1-0	Mode	1.7,4.4	10: SPI slave mode		
			11: SMI mode		

Static MAC Address Table

The KSZ8863 supports both a static and a dynamic MAC address table. In response to a Destination Address (DA) look up, the KSZ8863 searches both tables to make a packet forwarding decision. In response to a Source Address (SA) look up, only the dynamic table is searched for aging, migration and learning purposes.

The static DA look up result takes precedence over the dynamic DA look up result. If there is a DA match in both tables, the result from the static table is used. The entries in the static table will not be aged out by the KSZ8863.

The static table is accessed by a external processor via the SMI, SPI or I2C interfaces. The external processor performs all addition, modification and deletion of static MAC table entries.

Bit	Name	R/W	Description	Default
57-54	FID	R/W	Filter VLAN ID – identifies one of the 16 active VLANs	0000
53	Use FID	R/W	= 1, use (FID+MAC) for static table look ups	0
53	Use FID	R/VV	= 0, use MAC only for static table look ups	0
52	Override	R/W	= 1, override port setting "transmit enable=0" or "receive enable=0" setting	0
			= 0, no override	
51	Valid	R/W	= 1, this entry is valid, the lookup result will be used	0
51		13/00	= 0, this entry is not valid	0
			These 3 bits control the forwarding port(s):	
			001, forward to port 1	
		ding R/W	010, forward to port 2	000
	Forwarding		100, forward to port 3	
50-48	Ports		011, forward to port 1 and port 2	
			110, forward to port 2 and port 3	
			101, forward to port 1 and port 3	
			111, broadcasting (excluding the ingress port)	
47-0	MAC Address	R/W	48-bit MAC Address	0x0000_0000_000 0

Table 15. Format of Static MAC Table (8 Entries)

Examples:

 Static Address Table Read (Read the 2nd Entry) Write to reg. 121 (0x79) with 0x10 Write to reg. 122 (0x7A) with 0x01

// Read static table selected

// Trigger the read operation

Then,

Read reg. 124 (0x7C), static table bits [57:56] Read reg. 125 (0x7D), static table bits [55:48] Read reg. 126 (0x7E), static table bits [47:40] Read reg. 127 (0x7F), static table bits [39:32] Read reg. 128 (0x80), static table bits [31:24] Read reg. 129 (0x81), static table bits [23:16] Read reg. 130 (0x82), static table bits [15:8] Read reg. 131 (0x83), static table bits [7:0] 2. Static Address Table Write (Write the 8th Entry)

 Write to reg. 124 (0x7C), static table bits [57:56]

 Write to reg. 125 (0x7D), static table bits [55:48]

 Write to reg. 126 (0x7E), static table bits [47:40]

 Write to reg. 127 (0x7F), static table bits [39:32]

 Write to reg. 128 (0x80), static table bits [31:24]

 Write to reg. 129 (0x81), static table bits [23:16]

 Write to reg. 130 (0x82), static table bits [15:8]

 Write to reg. 131 (0x83), static table bits [7:0]

 Write to reg. 122 (0x7A) with 0x00
 // V

// Write static table selected
// Trigger the write operation

VLAN Table

The KSZ8863 uses the VLAN table to perform look ups. If 802.1Q VLAN mode is enabled (register 5, bit 7 = 1), this table will be used to retrieve the VLAN information that is associated with the ingress packet. This information includes FID (filter ID), VID (VLAN ID), and VLAN membership as described in Table 16.

Bit	Name	R/W	Description	Default
19	Valid	R/W	= 1, entry is valid	1
15	Valid	1.7, 4.4	= 0, entry is invalid	•
18-16	Membership	R/W	Specify which ports are members of the VLAN. If a DA lookup fails (no match in both static and dynamic tables), the packet associated with this VLAN will be forwarded to ports specified in this field. For example, 101 means port 3 and 1 are in this VLAN.	111
15-12	FID	R/W	Filter ID. KSZ8863 supports 16 active VLANs represented by these four bit fields. FID is the mapped ID. If 802.1Q VLAN is enabled, the look up will be based on FID+DA and FID+SA.	0x0
11-0	VID	R/W	IEEE 802.1Q 12 bits VLAN ID	0x001

Table 16. Format of Static VLAN Table (16 Entries)

If 802.1Q VLAN mode is enabled, KSZ8863 will assign a VID to every ingress packet. If the packet is untagged or tagged with a null VID, the packet is assigned with the default port VID of the ingress port. If the packet is tagged with non null VID, the VID in the tag will be used. The look up process will start from the VLAN table look up. If the VID is not valid, the packet will be dropped and no address learning will take place. If the VID is valid, the FID is retrieved. The FID+DA and FID+SA lookups are performed. The FID+DA look up determines the forwarding ports. If FID+DA fails, the packet will be broadcast to all the members (excluding the ingress port) of the VLAN. If FID+SA fails, the FID+SA will be learned.

Examples:

2.

1. VLAN Table Read (read the 3rd entry)

Dynamic MAC Address Table

The KSZ8863 maintains the dynamic MAC address table. Read access is allowed only.

Bit	Name	R/W	Description	Default					
71 Data Not	2 4 4 7 7 7 7	RO	= 1, entry is not ready, continue retrying until this bit is set to 0						
	Ready		= 0, entry is ready						
70-67	Reserved	RO	Reserved						
66		RO	= 1, there is no valid entry in the table	1					
00	MAC Empty	RU	= 0, there are valid entries in the table	I					
			Indicates how many valid entries in the table						
	5-56 No of Valid Entries	RO	0x3ff means 1K entries						
65-56			0x001 means 2 entries	00_0000_0000					
			0x000 and bit 66 = 0 means 1 entry						
									0x000 and bit 66 = 1 means 0 entry
55-54	Time Stamp	RO	2 bits counter for internal aging						
			The source port where FID+MAC is learned						
	Course Dort	00 : port 1	00						
53-52	Source Port R	RO	01 : port 2	00					
			10 : port 3						
51-48	FID	RO	Filter ID	0x0					
47-0	MAC Address	RO	48-bit MAC Address	0x0000_0000_0000					



Example:

Dynamic MAC Address Table Read (read the 1st entry and retrieve the MAC table size)

Write to reg. 121 (0x79) with 0x18	// Read dynamic table selected
Write to reg. 122 (0x7A) with 0x00	<pre>// Trigger the read operation</pre>

Then,

Read reg. 123 (0x7B), bit [7]

// if bit 7 = 1, restart (reread) from this register

selected

dynamic table bits [66:64] Read reg. 124 (0x7C), dynamic table bits [63:56]

Read reg. 125 (0x7D), dynamic table bits [55:48]

Read reg. 126 (0x7E), dynamic table bits [47:40]

Read reg. 127 (0x7F), dynamic table bits [39:32]

Read reg. 128 (0x80), dynamic table bits [31:24]

Read reg. 129 (0x81), dynamic table bits [23:16]

Read reg. 130 (0x82), dynamic table bits [15:8]

Read reg. 131 (0x83), dynamic table bits [7:0]

MIB (Management Information Base) Counters

The KSZ8863 provides 34 MIB counters per port. These counters are used to monitor the port activity for network management. The MIB counters have two format groups: "Per Port" and "All Port Dropped Packet."

Bit	Name	R/W	Description	Default
31	Overflow	RO	= 1, counter overflow	0
			= 0, no counter overflow	
30	Count valid	RO	= 1, counter value is valid	0
			= 0, counter value is not valid	
29-0	Counter values	RO	Counter value	0

Table 18. Format of "Per Port" MIB Counters

"Per Port" MIB counters are read using indirect memory access. The base address offsets and address ranges for all three ports are:

Port 1, base is 0x00 and range is (0x00-0x1f)

Port 2, base is 0x20 and range is (0x20-0x3f)

Port 3, base is 0x40 and range is (0x40-0x5f)

Port 1 MIB counters are read using the indirect memory offsets in Table 19.

Offset	Counter Name	Description
0x0	RxLoPriorityByte	Rx lo-priority (default) octet count including bad packets
0x1	RxHiPriorityByte	Rx hi-priority octet count including bad packets
0x2	RxUndersizePkt	Rx undersize packets w/ good CRC
0x3	RxFragments	Rx fragment packets w/ bad CRC, symbol errors or alignment errors
0x4	RxOversize	Rx oversize packets w/ good CRC (max: 1536 or 1522 bytes)
0x5	RxJabbers	Rx packets longer than 1522 bytes w/ either CRC errors, alignment errors, or symbol errors (depends on max packet size setting)
0x6	RxSymbolError	Rx packets w/ invalid data symbol and legal packet size.
0x7	RxCRCError	Rx packets within (64,1522) bytes w/ an integral number of bytes and a bad CRC (upper limit depends on max packet size setting)
0x8	RxAlignmentError	Rx packets within (64,1522) bytes w/ a non-integral number of bytes and a bad CRC (upper limit depends on max packet size setting)
0x9	RxControl8808Pkts	Number of MAC control frames received by a port with 88-08h in EtherType field
0xA	RxPausePkts	Number of PAUSE frames received by a port. PAUSE frame is qualified with EtherType (88-08h), DA, control opcode (00-01), data length (64B min), and a valid CRC
0xB	RxBroadcast	Rx good broadcast packets (not including error broadcast packets or valid multicast packets)
0xC	RxMulticast	Rx good multicast packets (not including MAC control frames, error multicast packets or valid broadcast packets)
0xD	RxUnicast	Rx good unicast packets
0xE	Rx64Octets	Total Rx packets (bad packets included) that were 64 octets in length
0xF	Rx65to127Octets	Total Rx packets (bad packets included) that are between 65 and 127 octets in length
0x10	Rx128to255Octets	Total Rx packets (bad packets included) that are between 128 and 255 octets in length
0x11	Rx256to511Octets	Total Rx packets (bad packets included) that are between 256 and 511 octets in length
0x12	Rx512to1023Octets	Total Rx packets (bad packets included) that are between 512 and 1023 octets in length
0x13	Rx1024to1522Octets	Total Rx packets (bad packets included) that are between 1024 and 1522 octets in length (upper limit depends on max packet size setting)
0x14	TxLoPriorityByte	Tx lo-priority good octet count, including PAUSE packets
0x15	TxHiPriorityByte	Tx hi-priority good octet count, including PAUSE packets
0x16	TxLateCollision	The number of times a collision is detected later than 512 bit-times into the Tx of a packet
0x17	TxPausePkts	Number of PAUSE frames transmitted by a port
0x18	TxBroadcastPkts	Tx good broadcast packets (not including error broadcast or valid multicast packets)
0x19	TxMulticastPkts	Tx good multicast packets (not including error multicast packets or valid broadcast packets)
0x1A	TxUnicastPkts	Tx good unicast packets
0x1B	TxDeferred	Tx packets by a port for which the 1st Tx attempt is delayed due to the busy medium
0x1C	TxTotalCollision	Tx total collision, half duplex only
0x1D	TxExcessiveCollision	A count of frames for which Tx fails due to excessive collisions
0x1E	TxSingleCollision	Successfully Tx frames on a port for which Tx is inhibited by exactly one collision
0x1F	TxMultipleCollision	Successfully Tx frames on a port for which Tx is inhibited by more than one collision

Table 19. Port 1's "Per Port" MIB Counters Indirect Memory Offsets

Bit	Name	R/W	Description	Default
30-16	Reserved	N/A	Reserved	N/A
15-0	Counter Value	RO	Counter Value	0

Table 20. Format of "All Port Dropped Packet" MIB Counters

"All Port Dropped Packet" MIB counters are read using indirect memory access. The address offsets for these counters are shown in Table 21:

Offset	Counter Name	Description	
0x100	Port1 TX Drop Packets	TX packets dropped due to lack of resources	
0x101	Port2 TX Drop Packets TX packets dropped due to lack of resources		
0x102	Port3 TX Drop Packets	TX packets dropped due to lack of resources	
0x103	Port1 RX Drop Packets	RX packets dropped due to lack of resources	
0x104	Port2 RX Drop Packets	RX packets dropped due to lack of resources	
0x105	Port3 RX Drop Packets	RX packets dropped due to lack of resources	

Table 21. "All Port Dropped Packet" MIB Counters Indirect Memory Offsets

Examples:

1. MIB Counter Read (Read port 1 "Rx64Octets	s" Counter)
Write to reg. 121 (0x79) with 0x1c	// Read MIB counters selected
Write to reg. 122 (0x7A) with 0x0e	// Trigger the read operation
Then	
Read reg. 128 (0x80), overflow bit [31]	// If bit $31 = 1$, there was a counter overflow
valid bit [30]	// If bit 30 = 0, restart (reread) from this register
counter bits [29:2	4]
Read reg. 129 (0x81), counter bits [23:1	6]
Read reg. 130 (0x82), counter bits [15:8]
Read reg. 131 (0x83), counter bits [7:0]	
2. MIB Counter Read (Read port 2 "Rx64Octets	s" Counter)
Write to reg. 121 (0x79) with 0x1c	// Read MIB counter selected
Write to reg. 122 (0x7A) with 0x2e	<pre>// Trigger the read operation</pre>
Then,	
Read reg. 128 (0x80), overflow bit [31]	// If bit $31 = 1$, there was a counter overflow
valid bit [30]	// If bit $30 = 0$, restart (reread) from this register
counter bits [29:2	4]
Read reg. 129 (0x81), counter bits [23:1	6]
Read reg. 130 (0x82), counter bits [15:8]
Read reg. 131 (0x83), counter bits [7:0]	

3. MIB Counter Read (Read "Port1 TX Drop Packets" Counter)

Write to reg. 121 (0x79) with 0x1d	// Read MIB counter selected
Write to reg. 122 (0x7A) with 0x00	// Trigger the read operation
T L	

Then

Read reg. 130 (0x82), counter bits [15:8] Read reg. 131 (0x83), counter bits [7:0]

Additional MIB Counter Information

"Per Port" MIB counters are designed as "read clear." These counters will be cleared after they are read.

"All Port Dropped Packet" MIB counters are not cleared after they are accessed and do not indicate overflow or validity; therefore, the application must keep track of overflow and valid conditions.

To read out all the counters, the best performance over the SPI bus is (160+3)*8*200 = 260ms, where there are 160 registers, 3 overheads, 8 clocks per access, at 5MHz. In the heaviest condition, the counters will overflow in 2 minutes. It is recommended that the software read all the counters at least every 30 seconds.

A high performance SPI master is also recommended to prevent counters overflow.

Absolute Maximum Ratings⁽¹⁾

–0.5V to 2.4V
–0.5V to 4.0V
–0.5V to 4.0V
–0.5V to 4.0V
260°C
–55°C to 150°C
4KV

Operating Ratings⁽²⁾

Supply Voltage	
(VDDA_1.8, VDDC)	1.67V to 1.94V
(VDDA_3.3)	2.5V to 3.465V
(VDDIO)	1.71V to 3.465V
Ambient Temperature (T _A)	
Commercial	0°C to 70°C
Industrial	
Junction Temperature (T _J) Junction Thermal Resistance ⁽³⁾	125°C
Junction Thermal Resistance ⁽³⁾	
LQFP (θ _{JA})	69.64°C/W
LQFP (θ_{JC})	15°C/W

Electrical Characteristics⁽⁴⁾

Current consumption is for the single 3.3V supply device only, and includes the 1.8V supply voltages (VDDA, VDDC) that are provided via power output pin 42(VDDCO).

Each PHY port's transformer consumes an additional 45mA @ 3.3V for 100BASE-TX and 70mA @ 3.3V for 10BASE-T at fully traffic.

Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
100BAS	E-TX Operation (All Ports @ 100%	6 Utilization)	•			
	100BASE-TX	V_{DDA} 3.3, V_{DDIO} = 3.3V				
I _{ddxio}	(analog core + digital core + transceiver + digital I/O)	Core power is provided from the internal 1.8V LDO with input voltage VDDIO		114		mA
10BASE	-T Operation (All Ports @ 100% U	tilization)	•			
	10BASE-T	V_{DDA} 3.3, V_{DDIO} = 3.3V				
l _{ddxio}	(analog core + digital core + transceiver + digital I/O)	Core power is provided from the internal 1.8V LDO with input voltage VDDIO		85		mA
Power I	Management Mode					
I _{dd3}	Power Saving Mode	$V_{DDA}_3.3, V_{DDIO} = 3.3V$ Unplug Port 1 and Port 2 Set Register 195 bit[1,0] = [1,1]		96		mA
I _{dd4}	Soft Power Down Mode	V _{DDA} _3.3, V _{DDIO} = 3.3V Set Register 195 bit[1,0] = [1,0]		8		mA
I _{dd5}	Energy Detect Mode	$V_{DDA}_{3.3}$, $V_{DDIO} = 3.3V$ Unplug Port 1 and Port 2 Set Register 195 bit[7,0] = 0x05 with port 3 PHY mode and by-pass mode.		16		mA
CMOS I	nputs (VDD_IO = 3.3V/2.5V/1.8	V)				
VIH	Input High Voltage		2.0/1. 8/1.3			V
V _{IL}	Input Low Voltage				0.8/0. 7/0.5	V
I _{IN}	Input Current	$V_{IN} = GND \sim VDD_IO$	-10		10	μA

Notes:

1. Exceeding the absolute maximum rating may damage the device.

2. The device is not guaranteed to function outside its operating rating.

3. No (HS) heat spreader in this package.

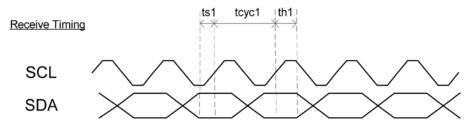
4. $T_A = 25^{\circ}C$. Specification for packaged product only.

Electrical Characteristics(4) (Continued)

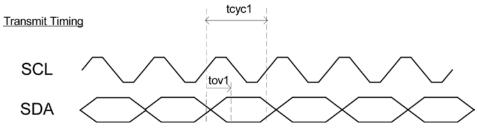
Symbol	Parameter	Condition	Min.	Тур.	Max.	Units
CMOS O	utputs (VDD_IO = 3.3V/2.5V/1.8	V)	•			
V _{OH}	Output High Voltage	I _{OH} = -8mA	2.4/2. 0/1.5			V
Vol	Output Low Voltage	I _{OL} = 8mA			0.4/0. 4/0.3	V
I _{OZ}	Output Tri-State Leakage				10	μA
100BASE	-TX Transmit (measured differentia	ally after 1:1 transformer)				
Vo	Peak Differential Output Voltage	100Ω termination across differential output	0.95		1.05	V
VIMB	Output Voltage Imbalance	100Ω termination across differential output			2	%
T _r /T _f	Rise/Fall Time		3		5	ns
	Rise/Fall Time Imbalance		0		0.5	ns
	Duty Cycle Distortion				±0.5	ns
	Overshoot				5	%
	Output Jitter	Peak-to-peak		0.7	1.4	ns
10BASE-	Г Receive	•				
V _{SQ}	Squelch Threshold	5MHz square wave		400		mV
10BASE-	Transmit (measured differentially	y after 1:1 transformer)		•		
VP	Peak Differential Output Voltage	100Ω termination across differential output		2.4		V
	Output Jitter	Peak-to-peak		1.4	11	ns

Timing Specifications

EEPROM Timing



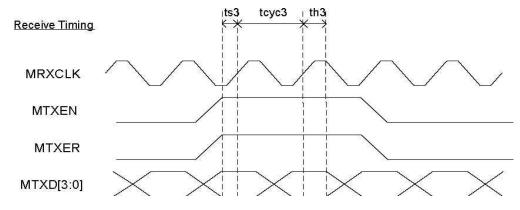




Symbols	Parameters	Min.	Тур.	Max.	Unit
t _{cyc1}	Clock cycle		16384		ns
t _{s1}	Setup time	20			ns
t _{h1}	Hold time	20			ns
t _{ov1}	Output valid	4096	4112	4128	ns

Table 22. EEPROM Timing Parameters

MII Timing





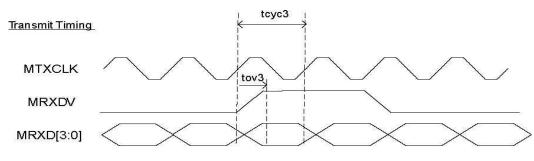


Figure 19. MAC Mode MII Timing – Data Transmitted to MII

		10Base-T/100Base-TX					
Symbol	Parameter	Min.	Тур.	Max.	Units		
tCYC3	Clock Cycle		400/40		ns		
t\$3	Set-Up Time	4			ns		
tнз	Hold Time	2			ns		
tov3	Output Valid	7	11	16	ns		

Table 23.	MAC Mode	MII Timing	Parameters
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MII Timing (Continued)

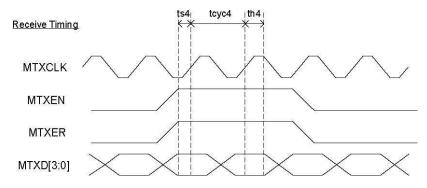


Figure 20. PHY Mode MII Timing – Data Received from MII

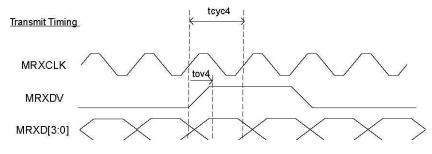


Figure 21. PHY Mode MII Timing – Data Transmitted to MII

		10BaseT/100BaseT			
Symbol	Parameter	Min.	Тур.	Max.	Units
tCYC4	Clock Cycle		400/40		ns
tS4	Set-Up Time	10			ns
tH4	Hold Time	0			ns
tov4	Output Valid	18		19	ns

Table 24. PHY Mode MII Timing Parameters

RMII Timing

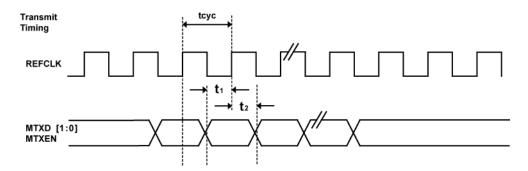


Figure 22. RMII Timing – Data Received from RMII

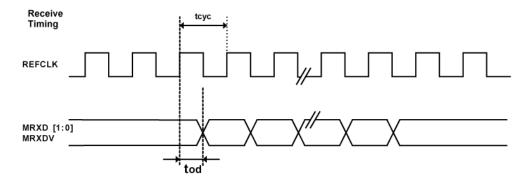
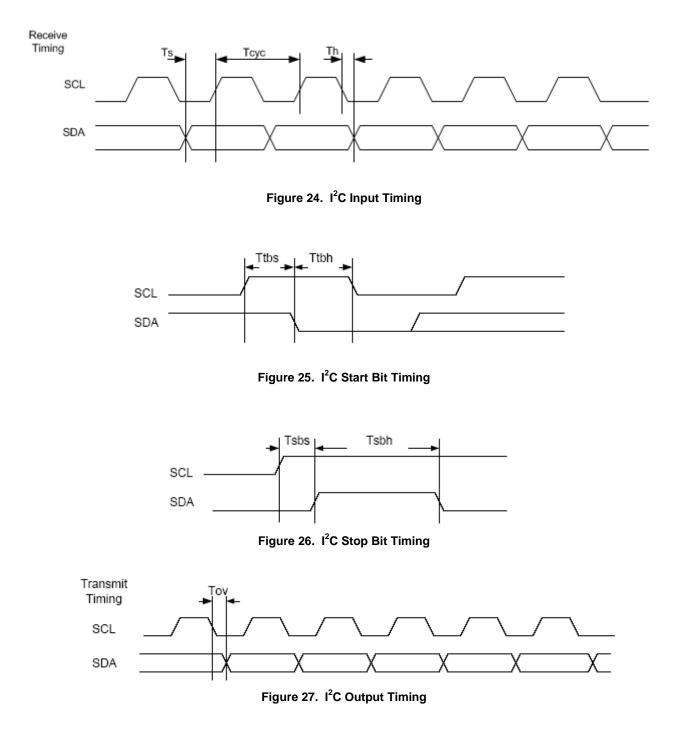


Figure 23. RMII Timing – Data Transmitted to RMII

Symbols	Parameters	Min.	Тур.	Max.	Unit
tcyc	Clock Cycle		20		ns
t1	Setup Time	4			ns
t2	Hold Time	2			ns
tod	Output Delay	6		16	ns

Table 25. RMII Timing Parameters

I²C Slave Mode Timing



I²C Slave Mode Timing (Continued)

Symbols	Parameters	Min.	Тур.	Max.	Unit
tcyc	Clock Cycle	400			ns
ts	Setup Time	33		Half-Cycle	ns
t _H	Hold Time	0			ns
t _{TBS}	Start Bit Setup Time	33			ns
t _{твн}	Start Bit Hold Time	33			ns
t _{SBS}	Stop Bit Setup Time	2			ns
t _{SBH}	Stop Bit Hold Time	33			ns
t _{OV}	Output Valid	64		96	ns

Table 26. I²C Timing Parameters

Note: Data is only allowed to change during SCL low time except start and stop bits.

SPI Timing

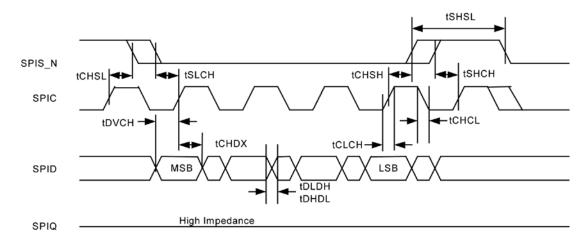


Figure 28. SPI Input Timing

Symbols	Parameters	Min.	Max.	Units
fc	Clock Frequency		25	MHz
t _{CHSL}	SPISN Inactive Hold Time	18		ns
t _{SLCH}	SPISN Active Setup Time	18		ns
tснян	SPISN Active Hold Time	18		ns
t _{shCH}	SPISN Inactive Setup Time	18		ns
t _{SHSL}	SPISN Deselect Time	20		ns
t _{DVCH}	Data Input Setup Time	4		ns
t _{CHDX}	Data Input Hold Time	6		ns
t _{CLCH}	Clock Rise Time		1	us
t _{CHCL}	Clock Fall Time		1	us
toldh	Data Input Rise Time		1	us
t _{DHDL}	Data Input Fall Time		1	us

Table 27. SPI Input Timing Parameters

SPI Timing (Continued)

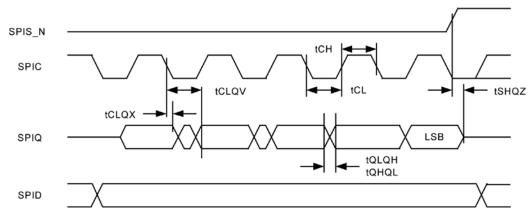


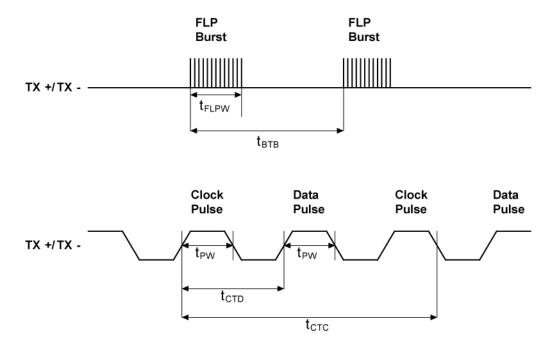
Figure 29. SPI Output Timing

Symbols	Parameters	Min.	Max.	Units
fc	Clock Frequency		25	MHz
t _{CLQX}	SPIQ Hold Time	0	0	ns
t _{CLQV}	Clock Low to SPIQ Valid		60	ns
t _{CH}	Clock High Time	18		ns
t _{CL}	Clock Low Time	18		
t _{QLQH}	SPIQ Rise Time		50	ns
t _{QHQL}	SPIQ Fall Time		50	ns
t _{SHQZ}	SPIQ Disable Time		100	ns

Table 28.	SPI Outp	ut Timing	Parameters
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Auto-Negotiation Timing



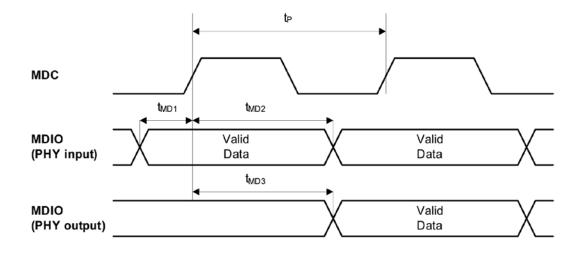




Symbols	Parameters	Min.	Тур.	Max.	Units
tBTB	FLP Burst to FLP Burst	8	16	24	ms
tFLPW	FLP Burst Width		2		ms
tPW	Clock/Data Pulse Width		100		ns
tCTD	Clock Pulse to Data Pulse	55.5	64	69.5	μs
tCTC	Clock Pulse to Clock Pulse	111	128	139	μs
	Number of Clock/Data Pulse per Burst	17		33	

Table 29. Auto-Negotiation Timing Parameters

MDC/MDIO Timing





Timing Parameter	Description	Min.	Тур.	Max.	Unit
t _P	MDC Period		400		ns
t _{1MD1}	MDIO (PHY Input) Setup to Rising Edge of MDC	10			ns
t _{MD2}	MDIO (PHY Input) Hold from Rising Edge of MDC	4			ns
t _{MD3}	MDIO (PHY Output) Delay from Rising Edge of MDC		222		ns

Table 30. MDC/MDIO Timing Parameters

Reset Timing

The KSZ8863MLL/FLL/RLL reset timing requirement is summarized in the Figure 32 and Table 31.

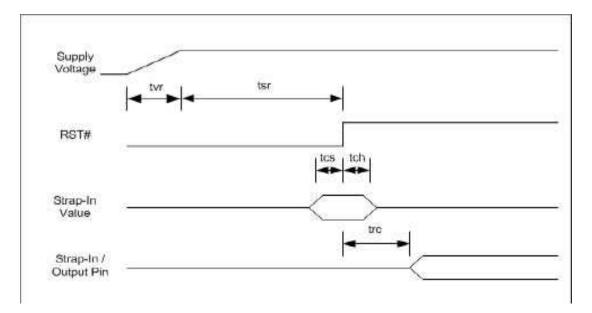


Figure 32. Reset Timing

Symbols	Parameters	Min	Max	Units
t _{sr}	Stable Supply Voltages to Reset High	10		ms
t _{cs}	Configuration Setup Time	50		ns
t _{ch}	Configuration Hold Time	50		ns
t _{rc}	Reset to Strap-In Pin Output	50		ns
t _{vr}	3.3V Rise Time	100		μs

Table 31. Reset Timing Parameters

After the de-assertion of reset, it is recommended to wait a minimum of 100μ s before starting programming on the managed interface (I²C slave, SPI slave, SMI, MIIM).

Reset Circuit

The reset circuit in Figure 33 is recommended for powering up the KSZ8863MLL/FLL/RLL if reset is triggered only by the power supply.

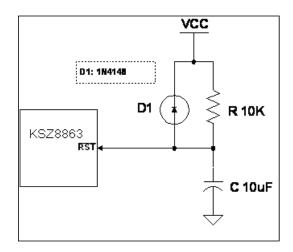


Figure 33. Recommended Reset Circuit

The reset circuit in Figure 34 is recommended for applications where reset is driven by another device (e.g., CPU, FPGA, etc),. At power-on-reset, R, C and D1 provide the necessary ramp rise time to reset the KSZ8863MLL/FLL/RLL device. The RST_OUT_n from CPU/FPGA provides the warm reset after power up.

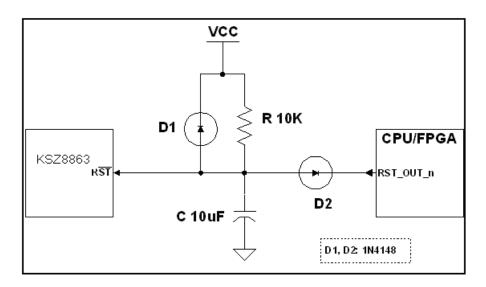


Figure 34. Recommended Reset Circuit for interfacing with CPU/FPGA Reset Output

Selection of Isolation Transformers

An 1:1 isolation transformer is required at the line interface. An isolation transformer with integrated common-mode choke is recommended for exceeding FCC requirements.

Table 32 gives recommended transformer characteristics.

Parameter	Value	Test Condition
Turns ratio	1 CT : 1 CT	
Open-circuit inductance (minimum)	350µH	100mV, 100kHz, 8mA
Leakage inductance (maximum)	0.4µH	1MHz (minimum)
Inter-winding capacitance (maximum)	12pF	
D.C. resistance (maximum)	0.9Ω	
Insertion loss (maximum)	1.0dB	0MHz – 65MHz
HIPOT (min.)	1500Vrms	

Table 32. Transformer Selection Criteria

Magnetic Manufacturer	Part Number	Auto MDI-X	Number of Port
Bel Fuse	S558-5999-U7	Yes	1
Bel Fuse (MagJack)	SI-46001	Yes	1
Bel Fuse (MagJack)	SI-50170	Yes	1
Delta	LF8505	Yes	1
LanKom	LF-H41S	Yes	1
Pulse	H1102	Yes	1
Pulse (Low Cost)	H1260	Yes	1
Datatronic	NT79075	Yes	1
Transpower	HB726	Yes	1
YCL	LF-H41S	Yes	1
TDK (Mag Jack)	TLA-6T718	Yes	1

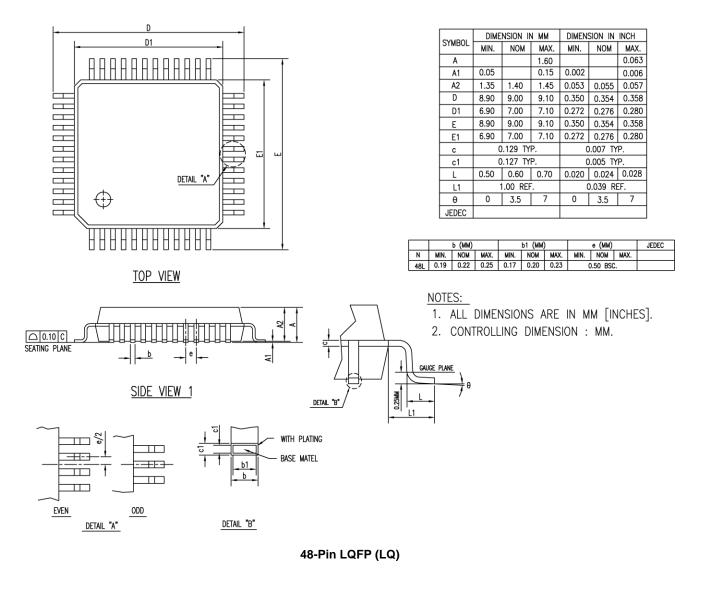
Table 33. Qualified Single Port Magnetics

Selection of Reference Crystal

Characteristics	Value	Units	
Frequency	25.00000	MHz	
Frequency Tolerance (maximum)	±50	ppm	
Load Capacitance (maximum)	20	pF	
Series Resistance	40	Ω	

Table 34. Typical Reference Crystal Characteristics

Package Information



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